

Algorithms for graph modification problems: towards generality and efficiency

Laure Morelle

September 23rd, 2025

Committee

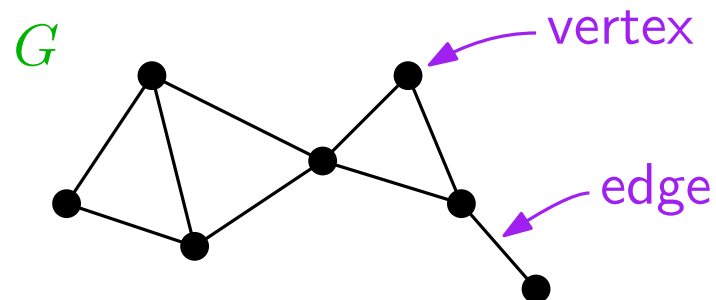
Robert Ganian	Reviewer
Eunjung Kim	Reviewer
Archontia Giannopoulou	Examiner
Petr Golovach	Examiner
Frédéric Havet	Examiner
Ignasi Sau	Supervisor
Dimitrios M. Thilikos	Supervisor

Graphs and Algorithms

Our research:

Design fast **algorithms** to solve computational problems.

Model of abstraction: **graphs**



$V(G)$ = set of vertices of G

$E(G)$ = set of edges of G

Graph modification problems

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Require:

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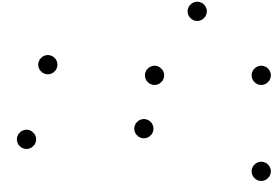
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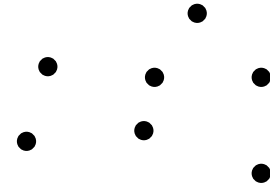
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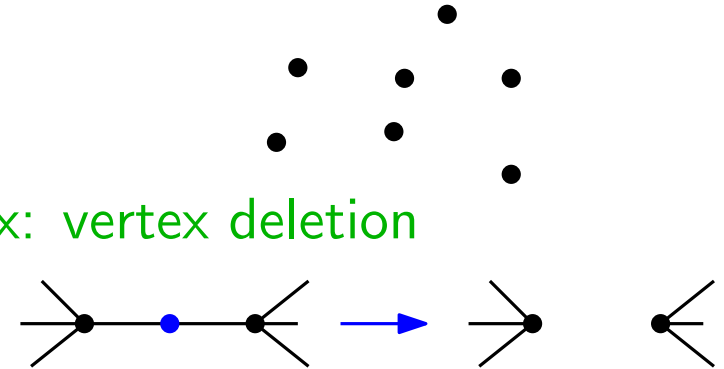
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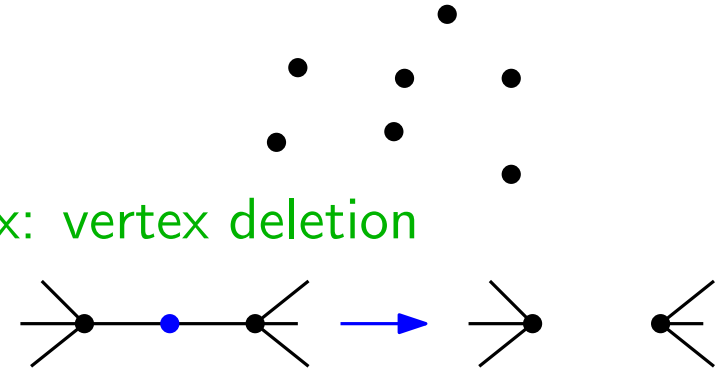
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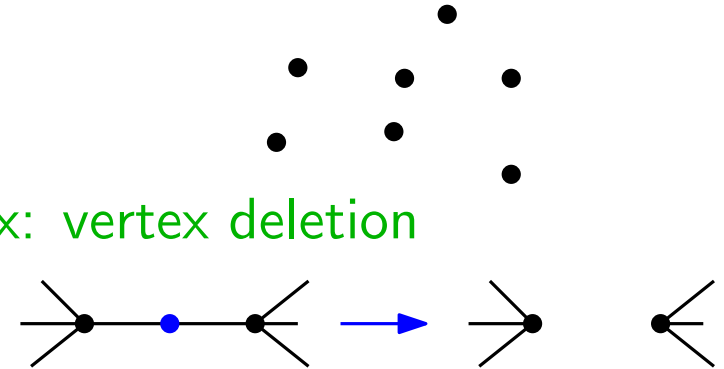


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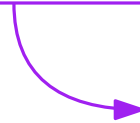
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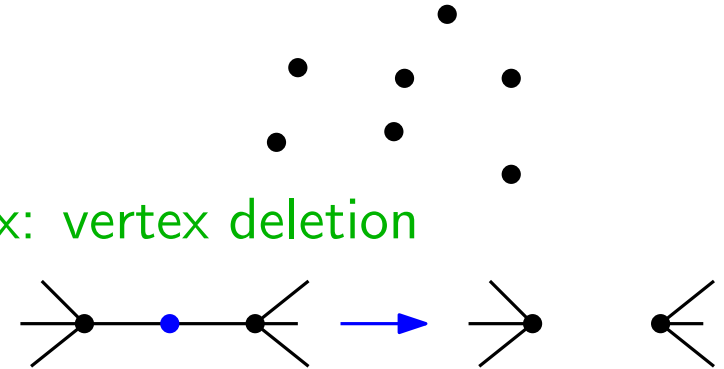
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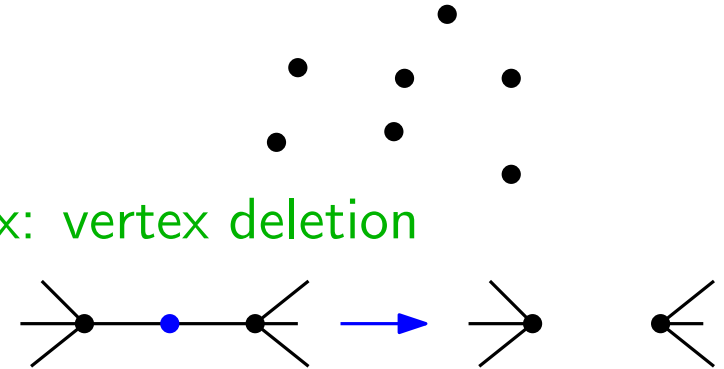
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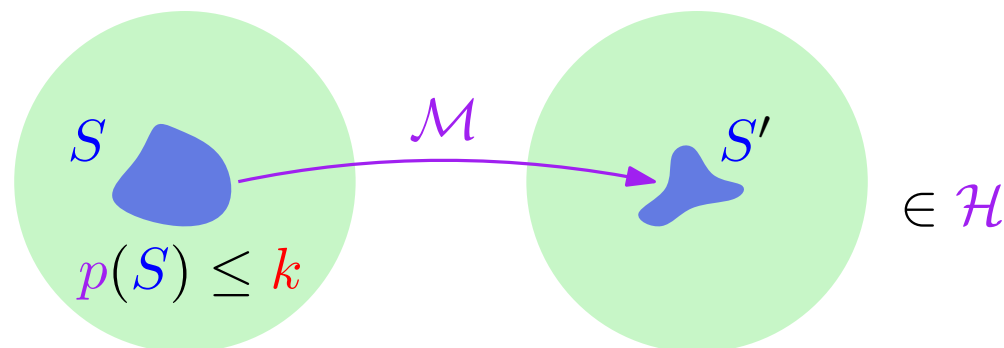
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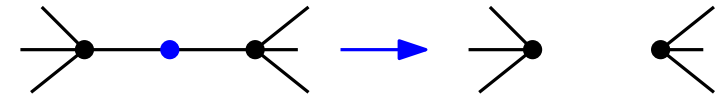
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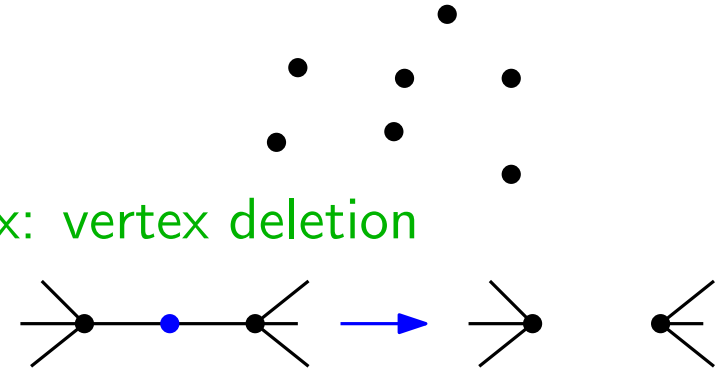
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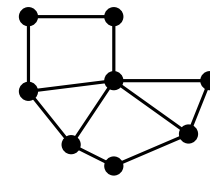
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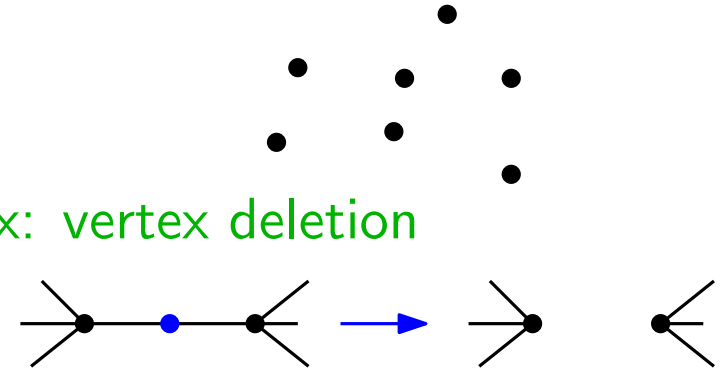
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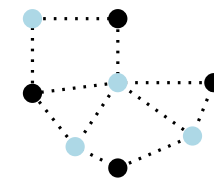
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[Chen, Kanj, Jia, '06]

There is an algorithm solving VERTEX COVER in time $\mathcal{O}(1.2738^k + k \cdot n)$.

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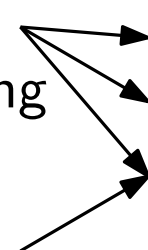
Organization

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- 
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 2. Set of modifications
 3. Measure on the modulator
 4. Vertex identification

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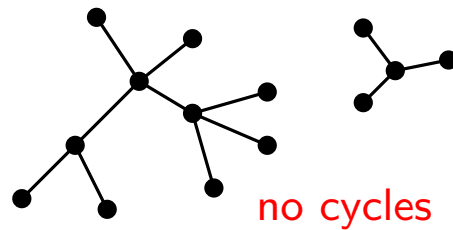
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[Li, Nederlof, '22]

solvable in time $\mathcal{O}(2.7^k \cdot n)$

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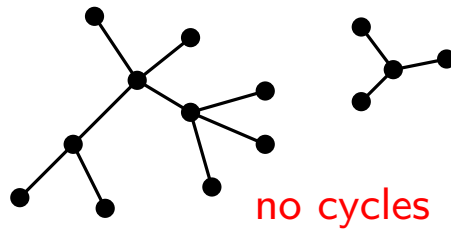
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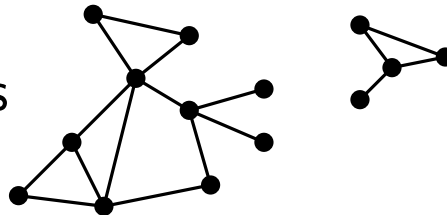
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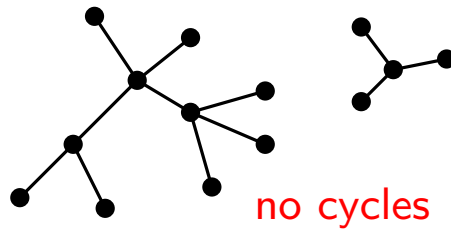
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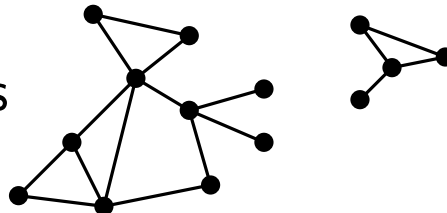
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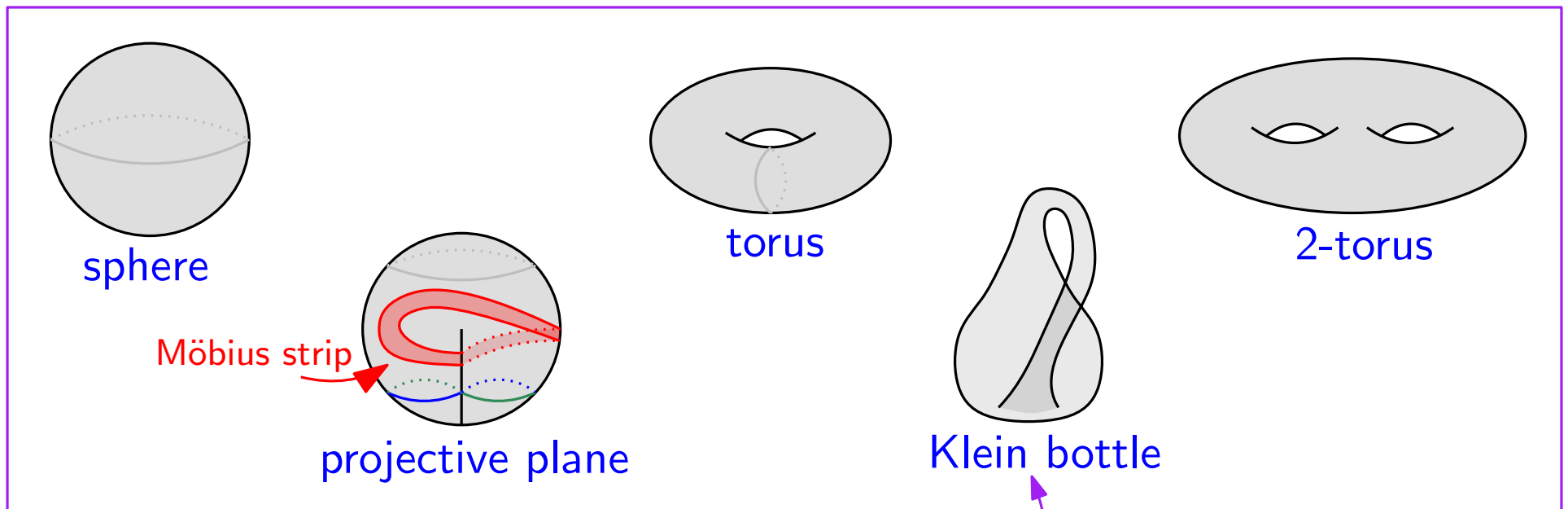
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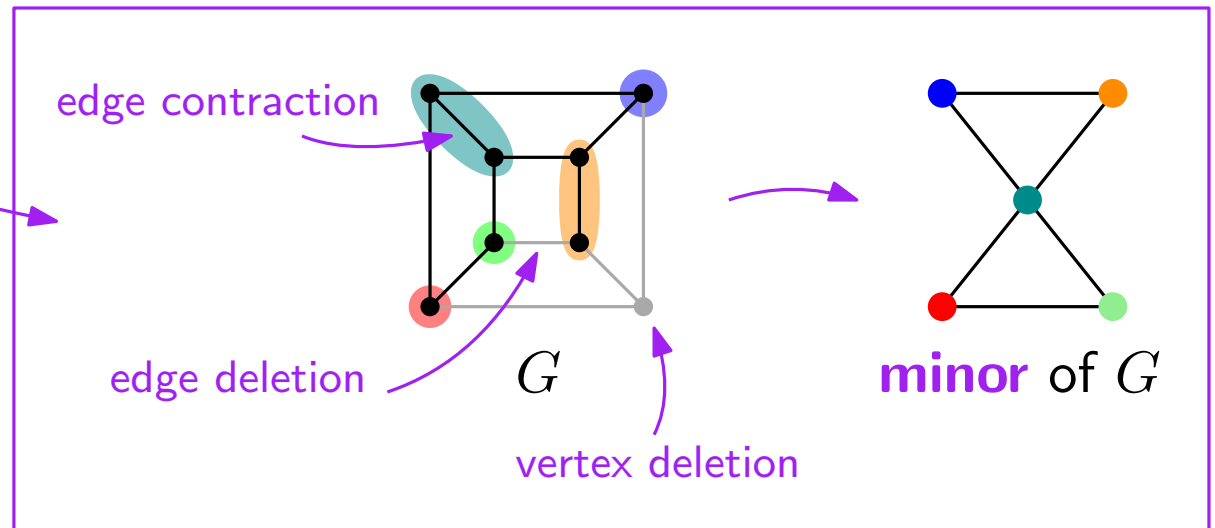
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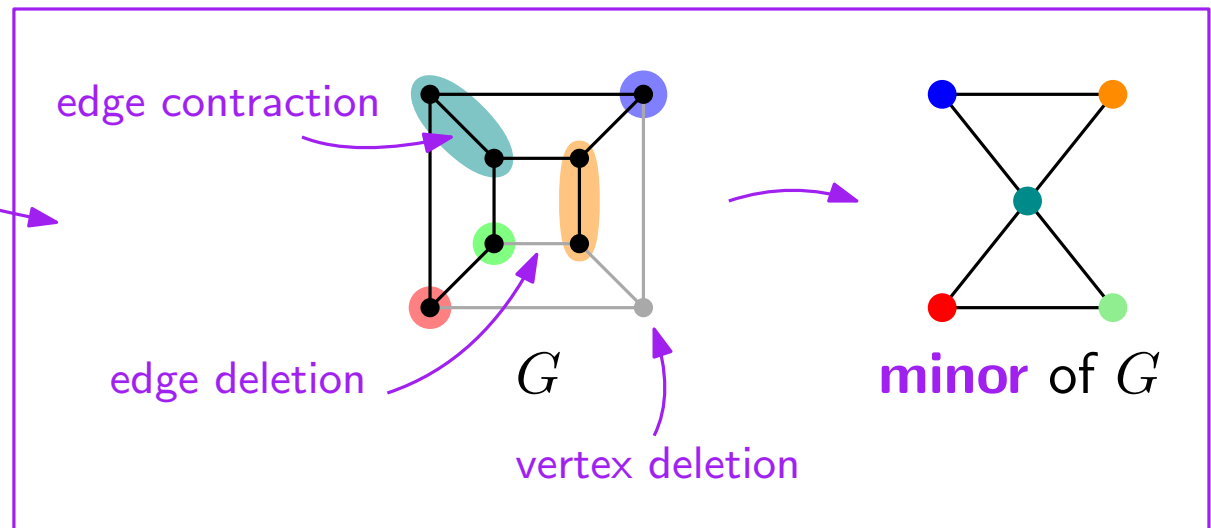
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Sketch of the proof

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originates from [Robertson, Seymour, '95]

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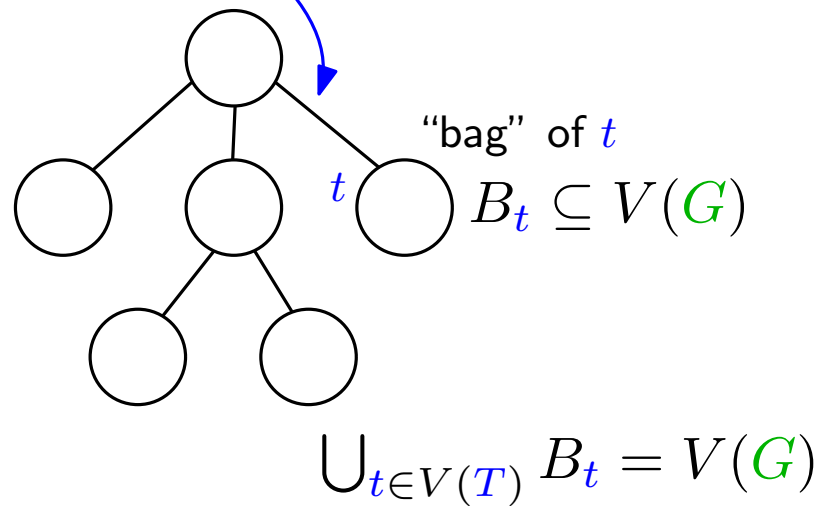


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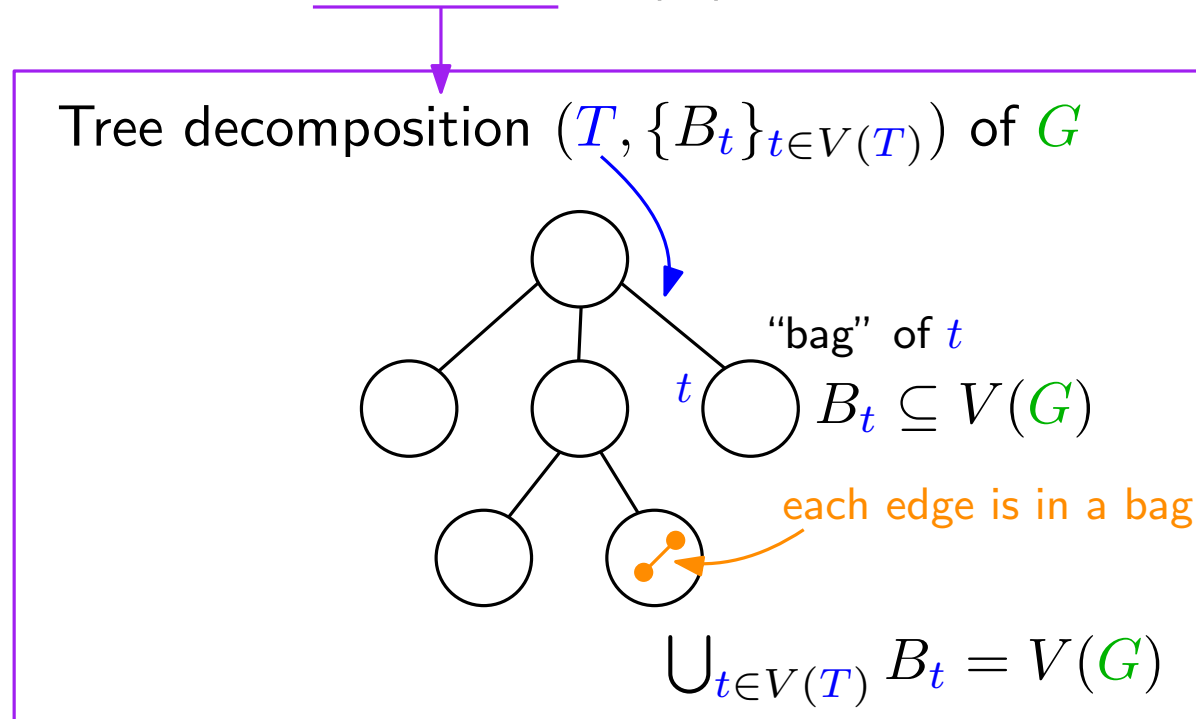
Tree decomposition $(T, \{B_t\}_{t \in V(T)})$ of G



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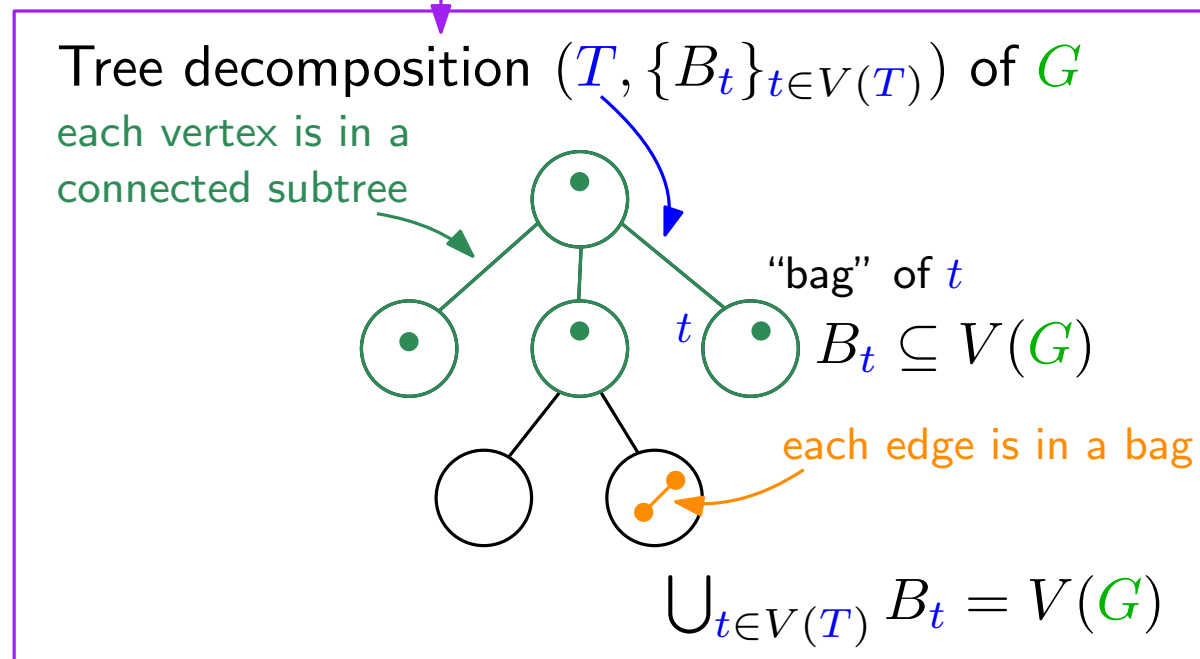
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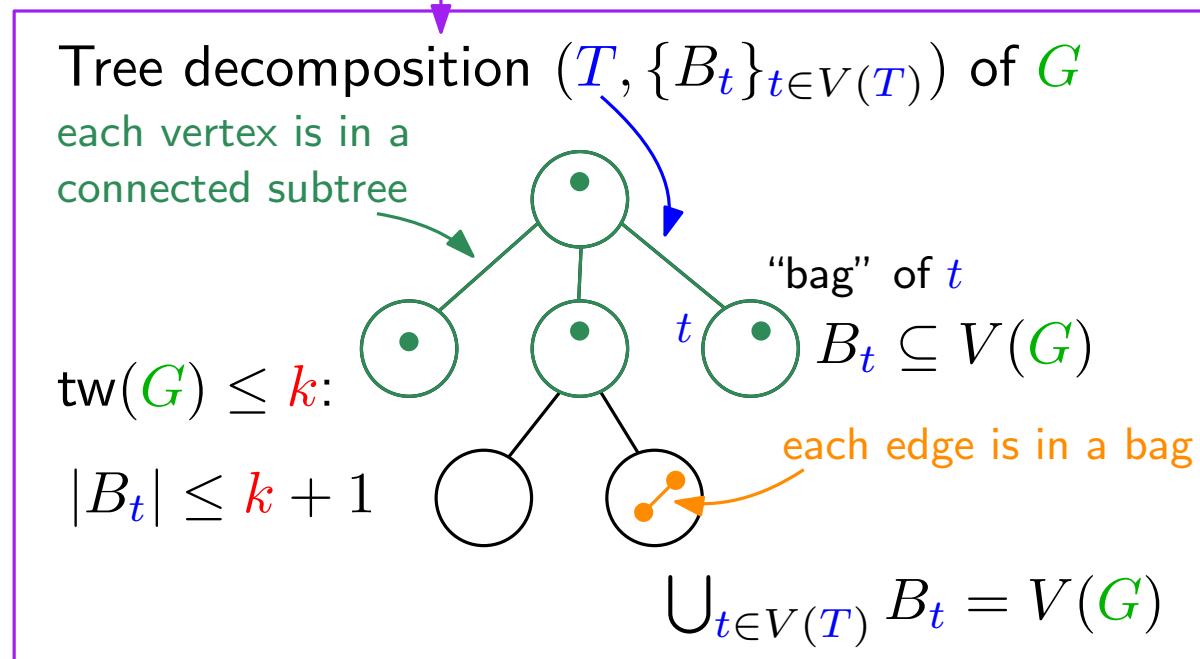
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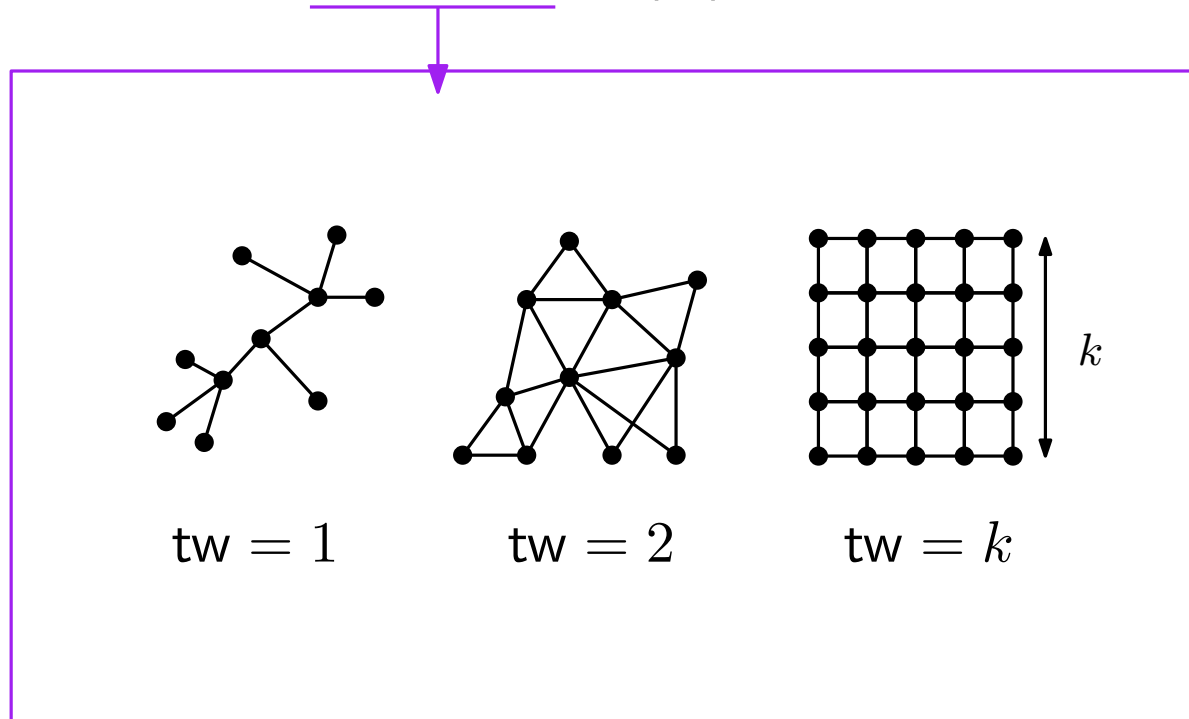
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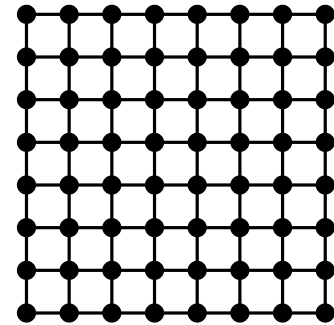
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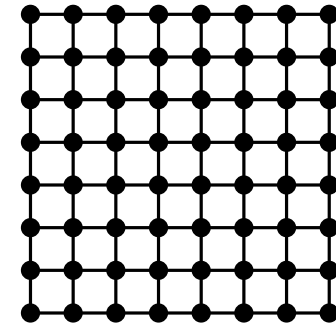
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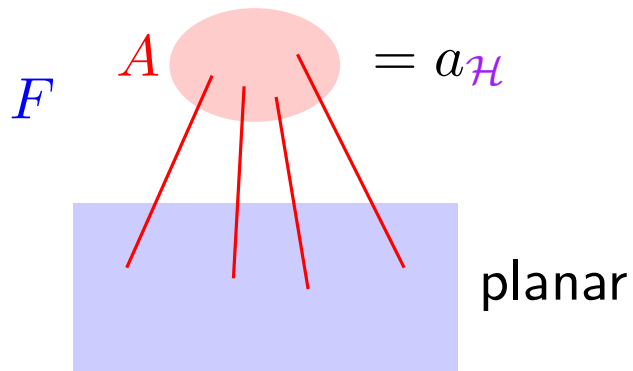
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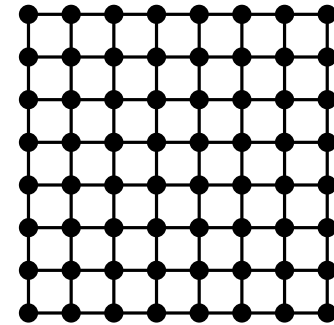
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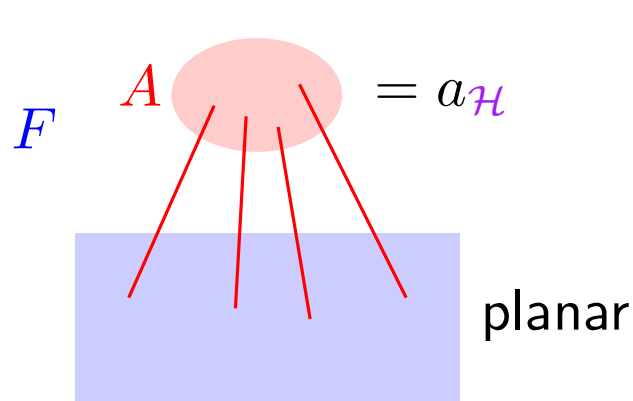
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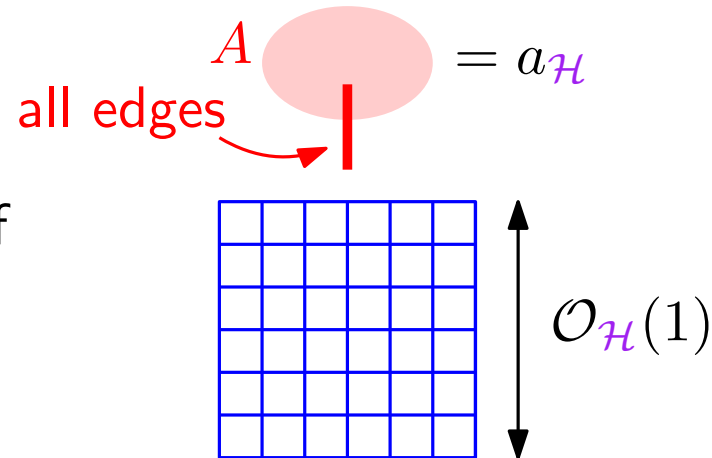
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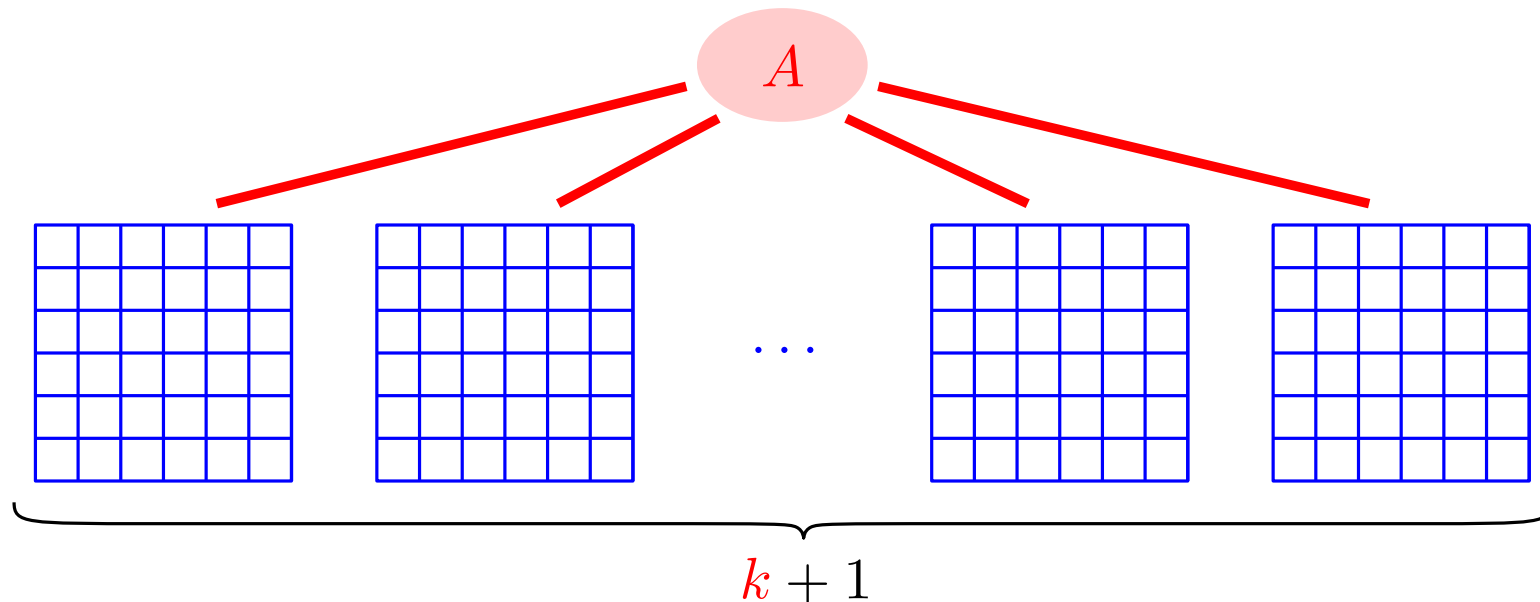
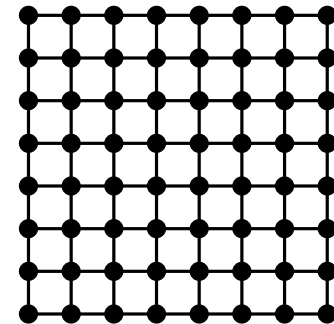
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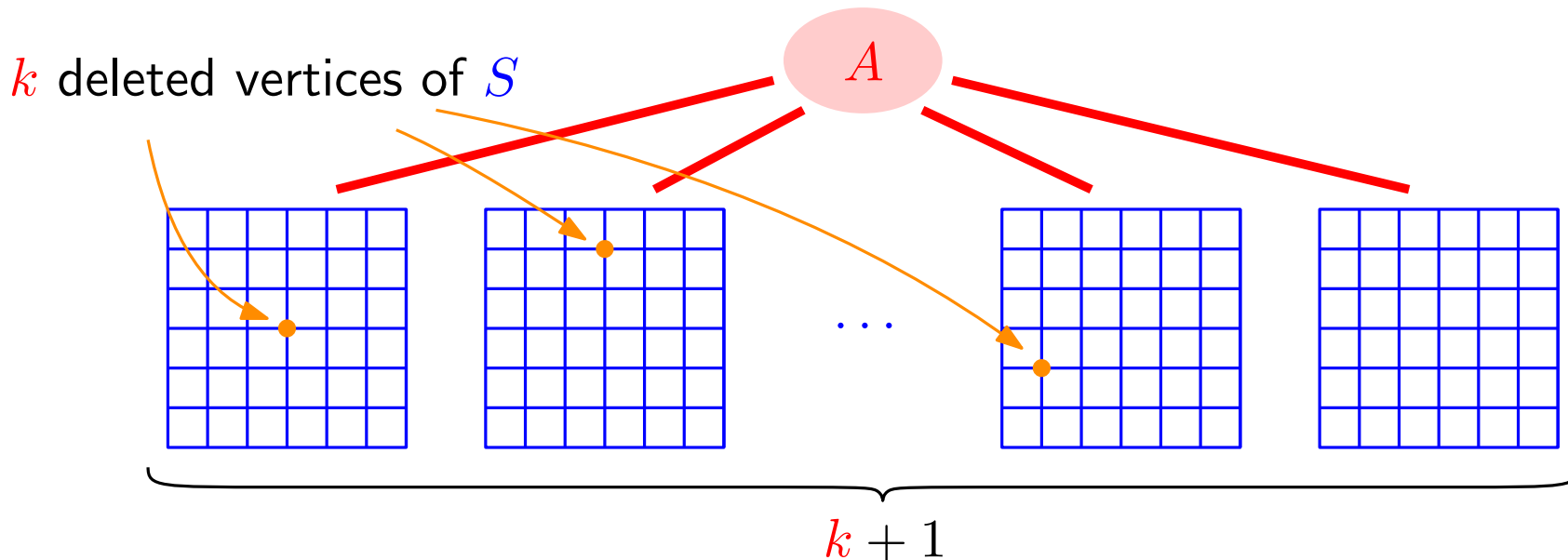
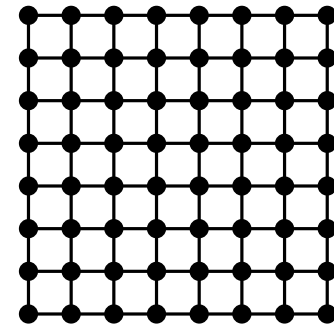
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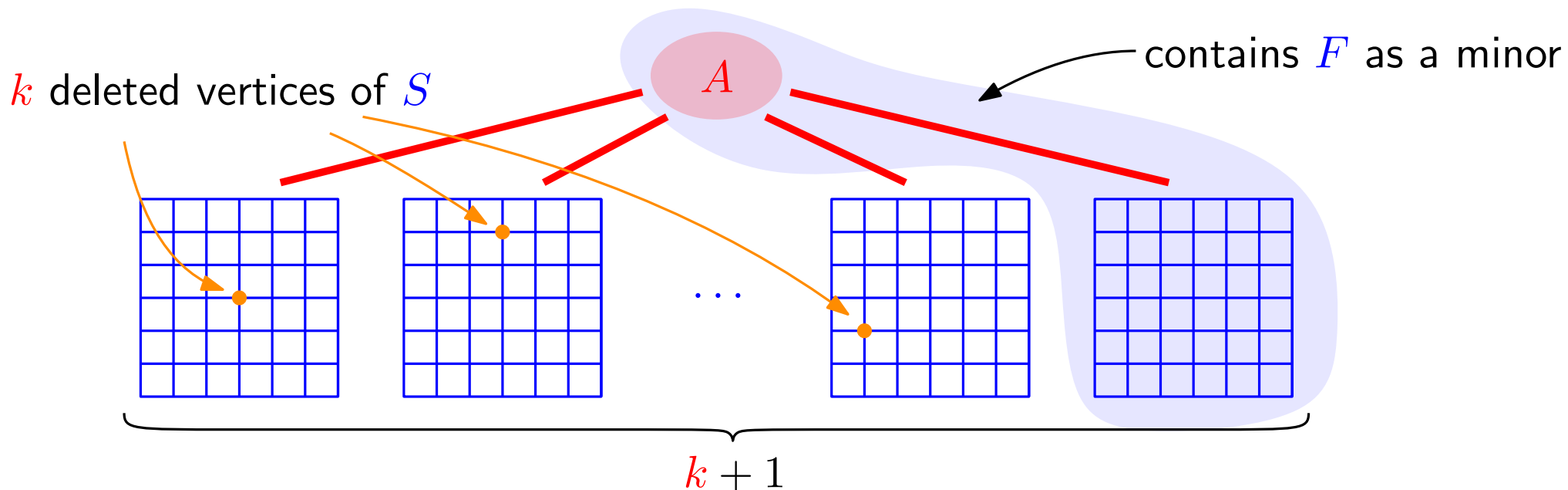
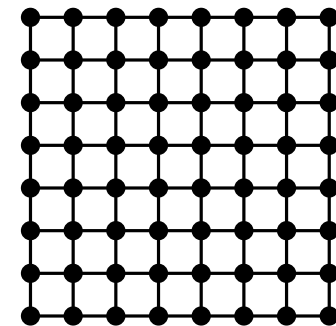
Target graph class \mathcal{H}

Sketch of the proof

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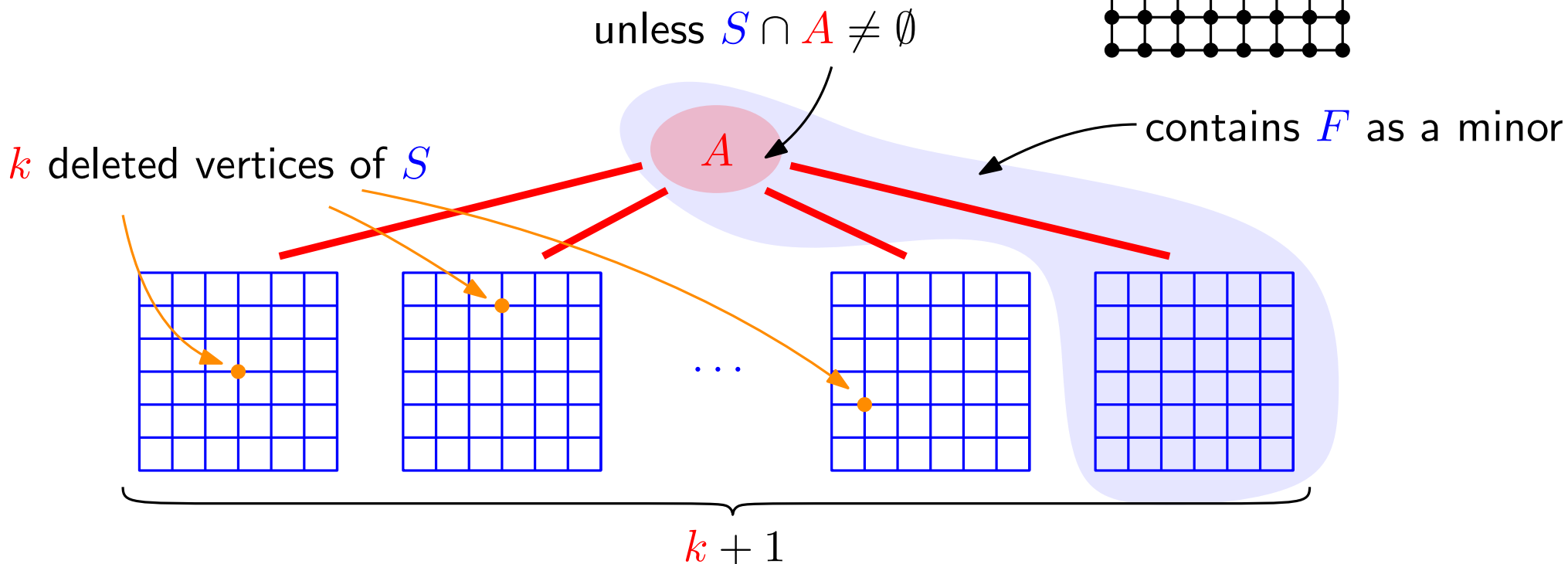
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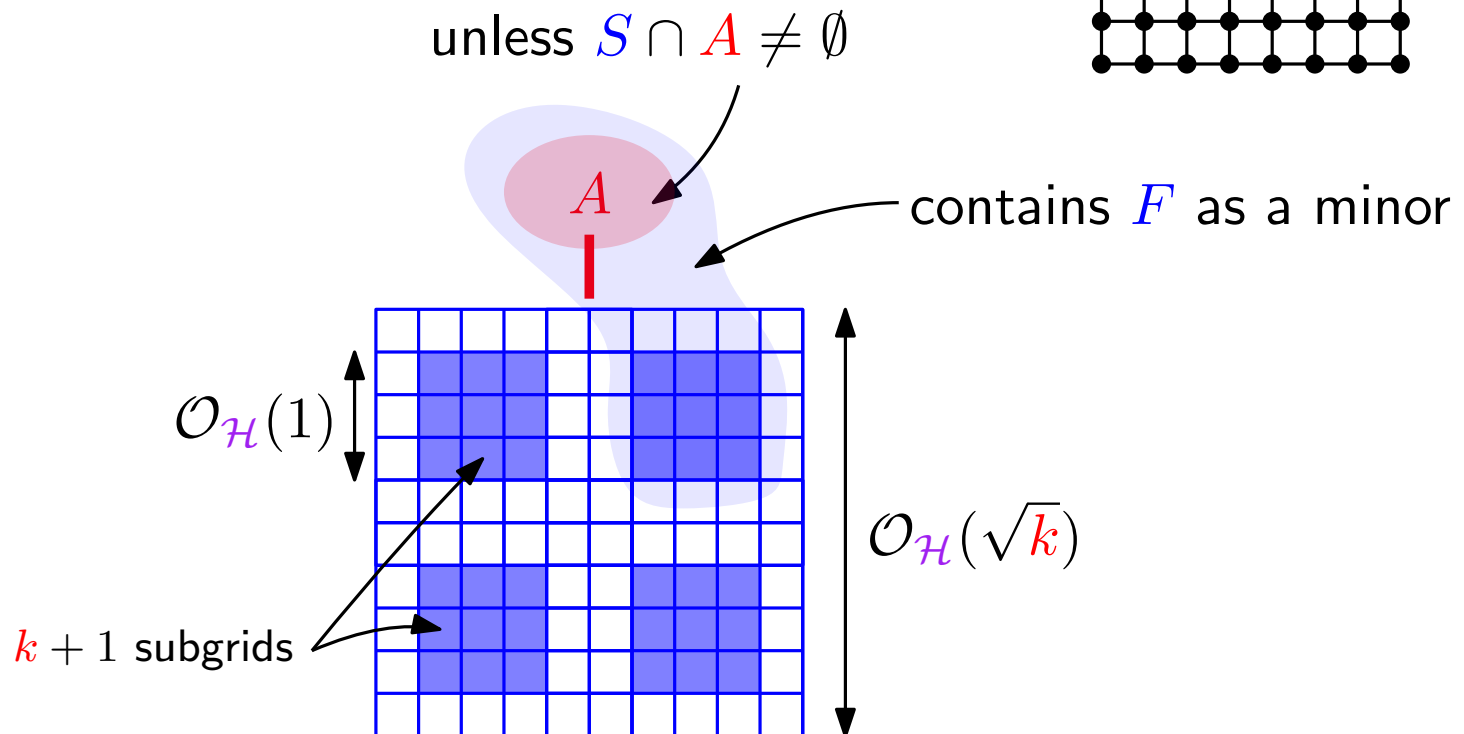
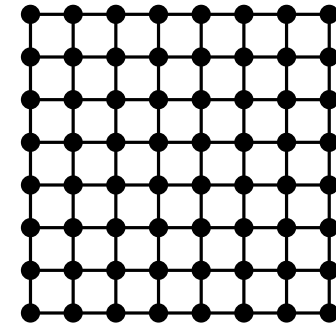
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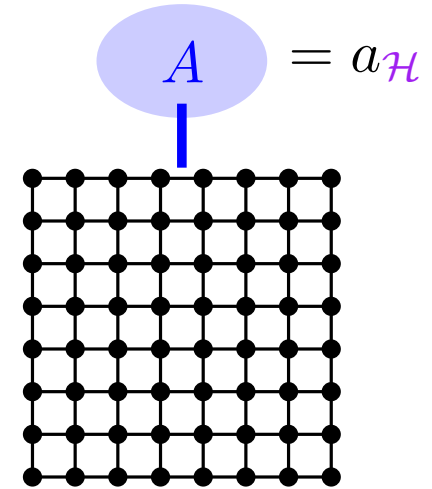
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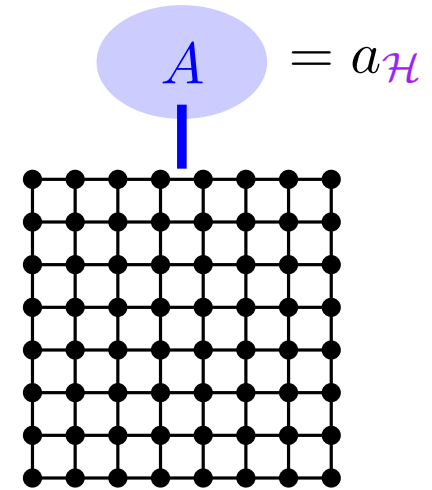
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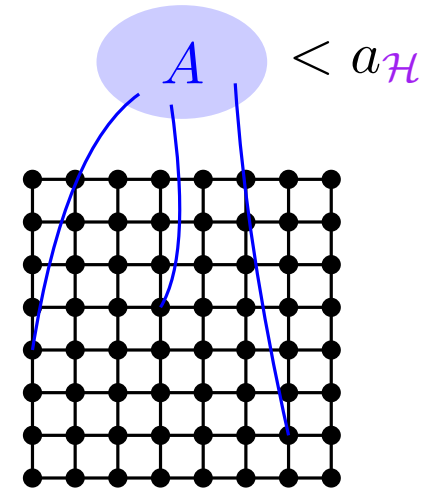
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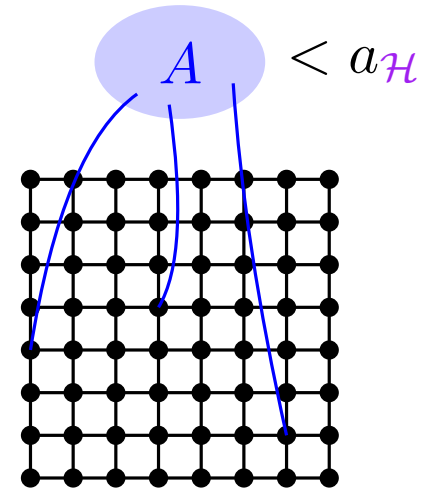
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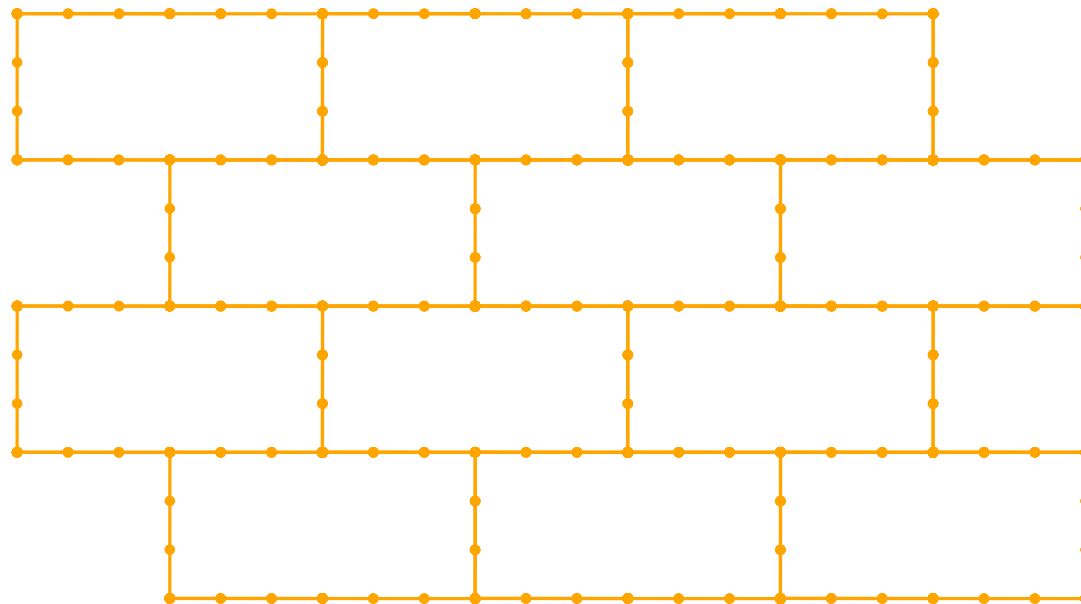
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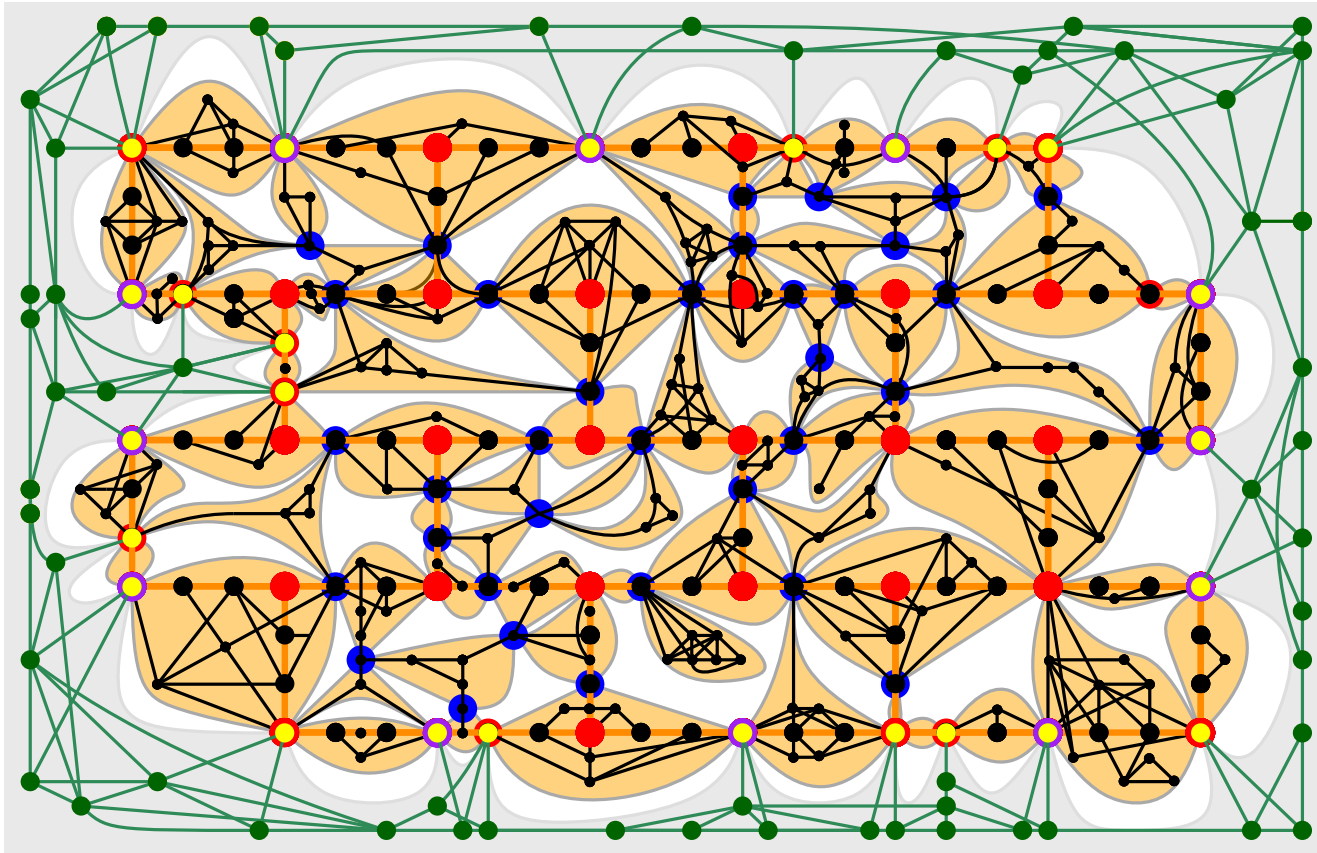
Target graph class \mathcal{H}

A wall:



Target graph class \mathcal{H}

A **flat** wall:



[figure by Dimitrios M. Thilikos]

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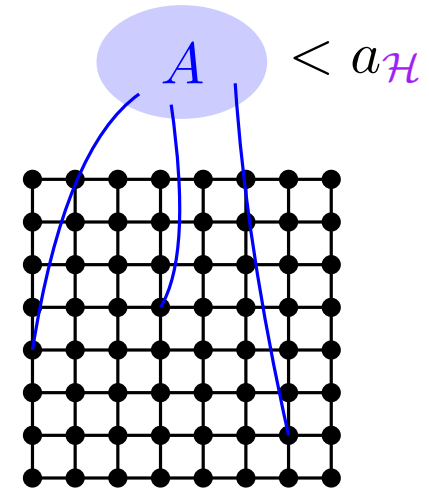
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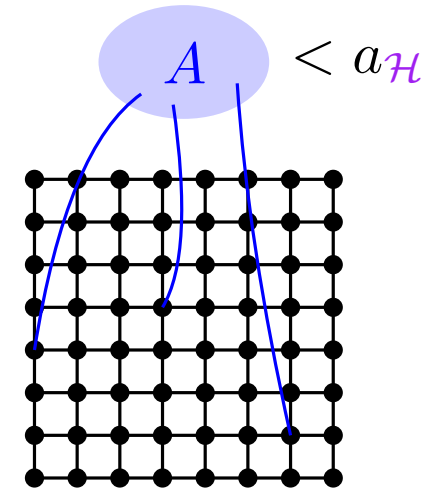
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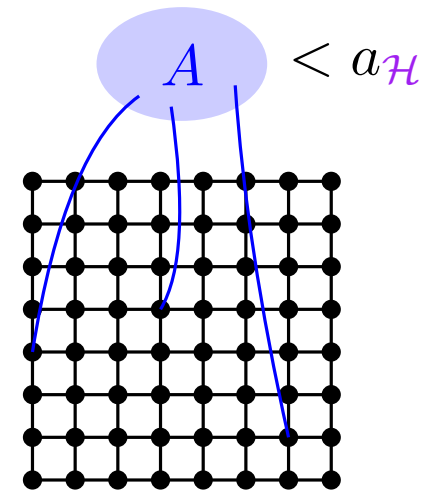
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2. Set of modifications \mathcal{M}

Measure = size of the modulator

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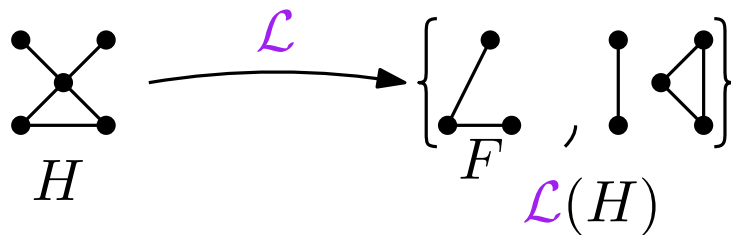
Model of abstraction to represent many modifications at once?

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Model of abstraction to represent many modifications at once?

R-action: function \mathcal{L} mapping each graph H to a collection $\mathcal{L}(H)$ of graphs of equal or smaller size.

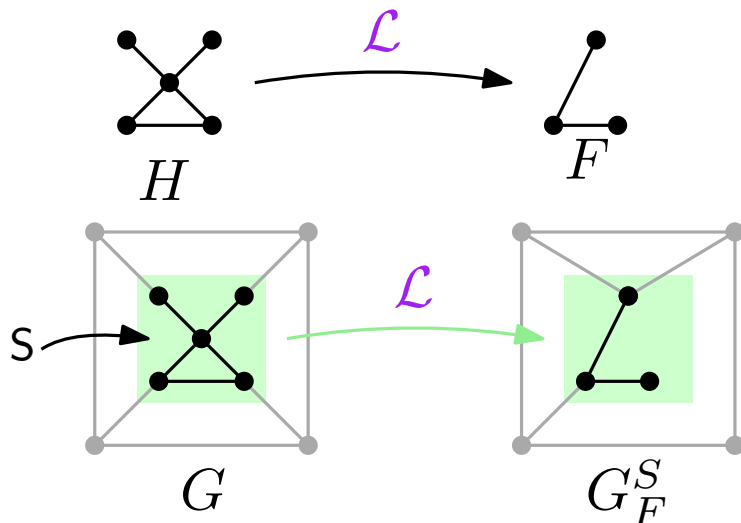
[Fomin, Golovach, Thilikos, '19]



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\mathcal{L} -Replacement to \mathcal{H}

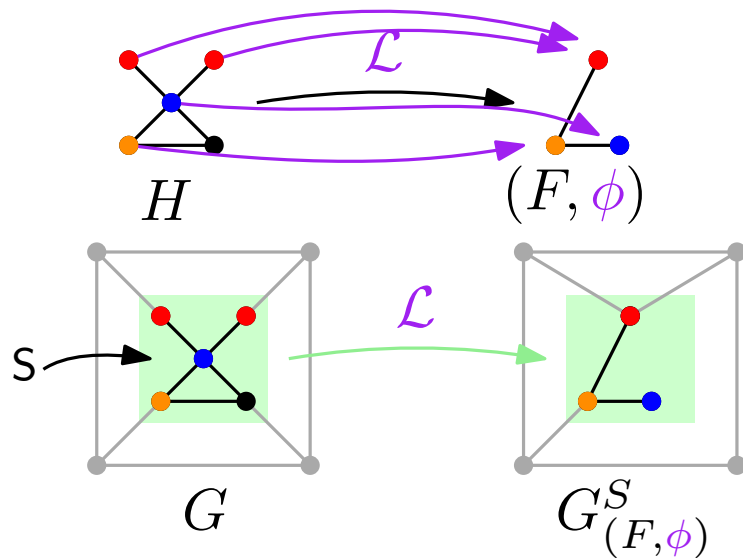
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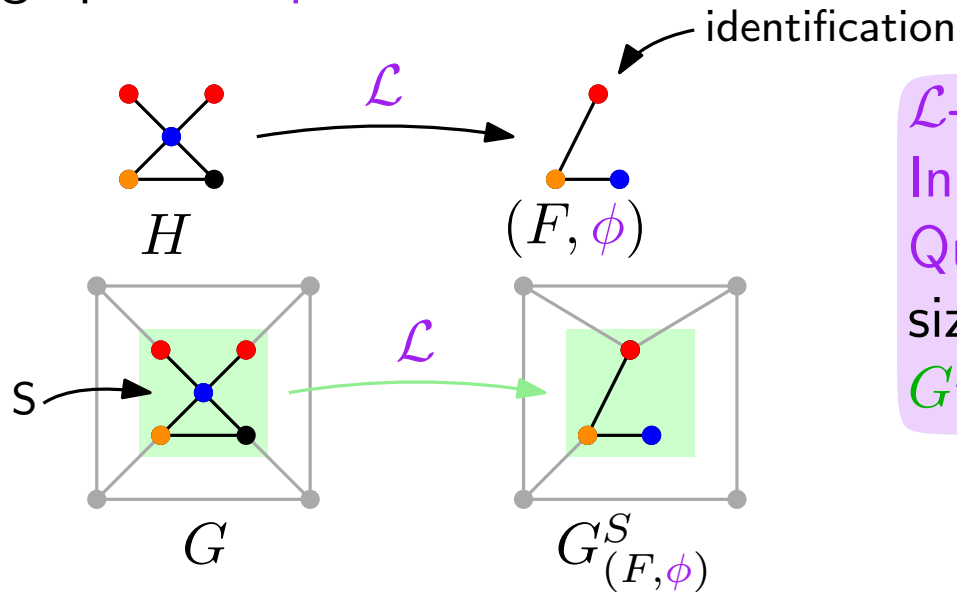
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[Fomin, Golovach, Thilikos, '19]



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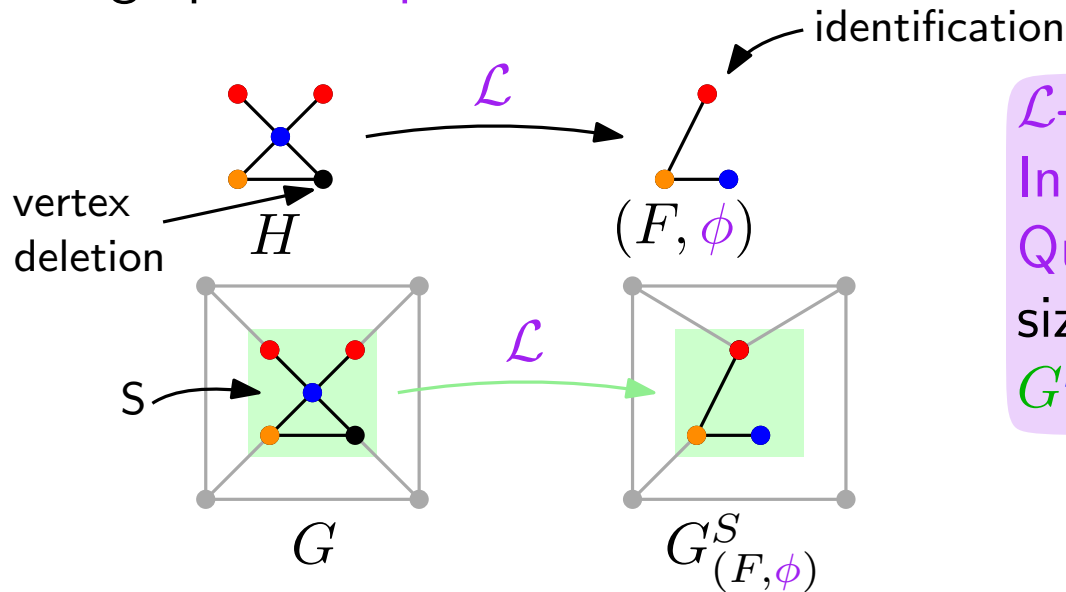
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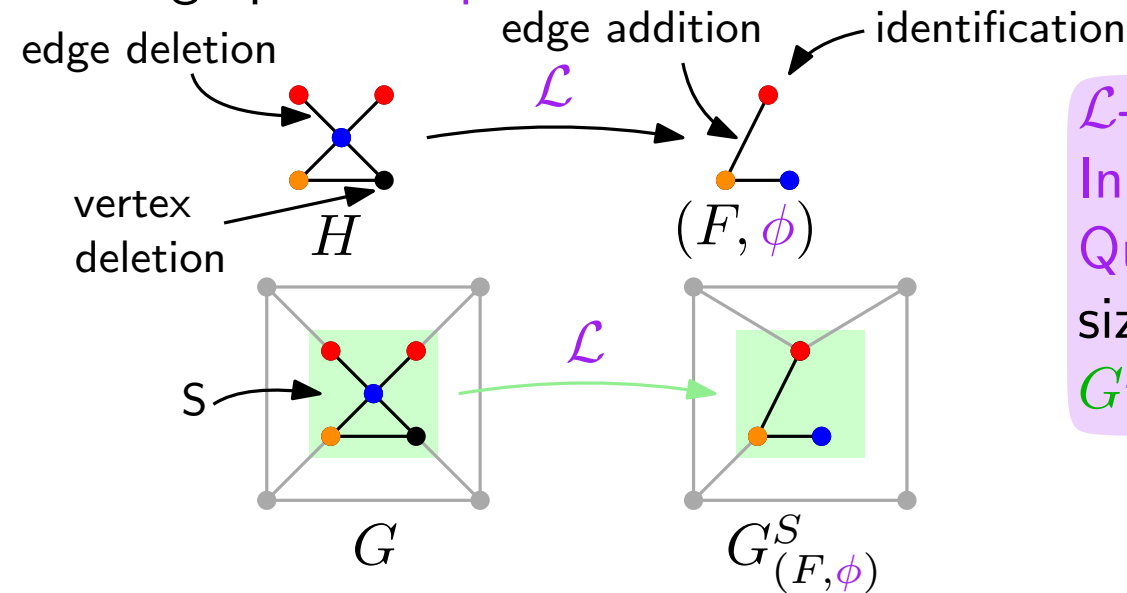
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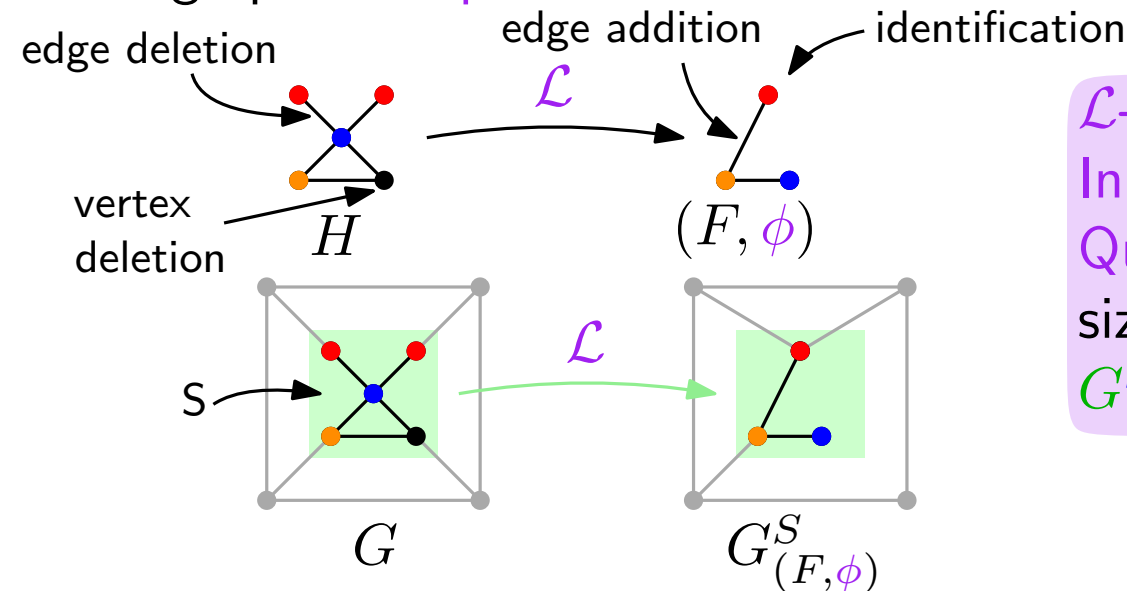
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\mathcal{H} minor-closed

[Morelle, Sau, Thilikos]

\mathcal{L} -REPLACEMENT TO \mathcal{H} is solvable in time $2^{\text{poly}_{\mathcal{H}}(k)} \cdot n^2$ for \mathcal{L} hereditary.

Measure = size of the modulator

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- EDGE DELETION TO \mathcal{H}
- EDGE CONTRACTION TO \mathcal{H}
- MATCHING DELETION TO \mathcal{H}
- MATCHING CONTRACTION TO \mathcal{H}
- INDEPENDENT SET DELETION TO \mathcal{H}
- CONNECTED VERTEX DELETION TO \mathcal{H}
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- etc.

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Sketch of the proof for VERTEX DELETION TO \mathcal{H} :

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Generalize to R-actions

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$$2^{\mathcal{O}_{\mathcal{H}}(k^2 + (k + \text{tw}) \log(k + \text{tw}))} \cdot n$$

Generalize to R-actions

new dynamic programming

Representative-based technique [Baste, Sau, Thilikos, '19]

\mathcal{H} minor-closed

[Morelle, Sau, Thilikos]

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\mathcal{H}_{Σ} = graphs embeddable on a surface Σ

[Morelle, Sau, Thilikos]

\mathcal{L} -REPLACEMENT TO \mathcal{H}_{Σ} is solvable in time $2^{\mathcal{O}_{\Sigma}(k^9)} \cdot n^2$ for \mathcal{L} hereditary.

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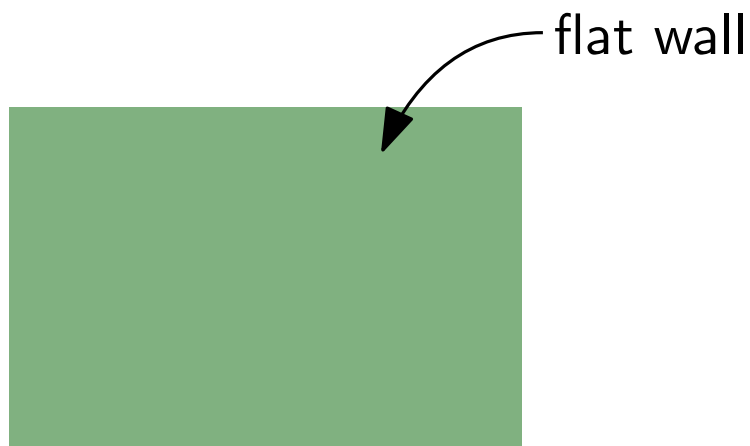
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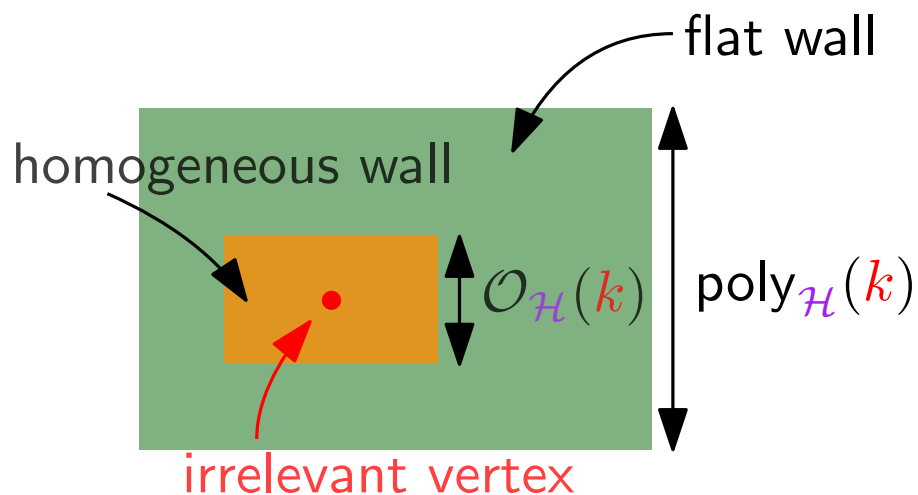
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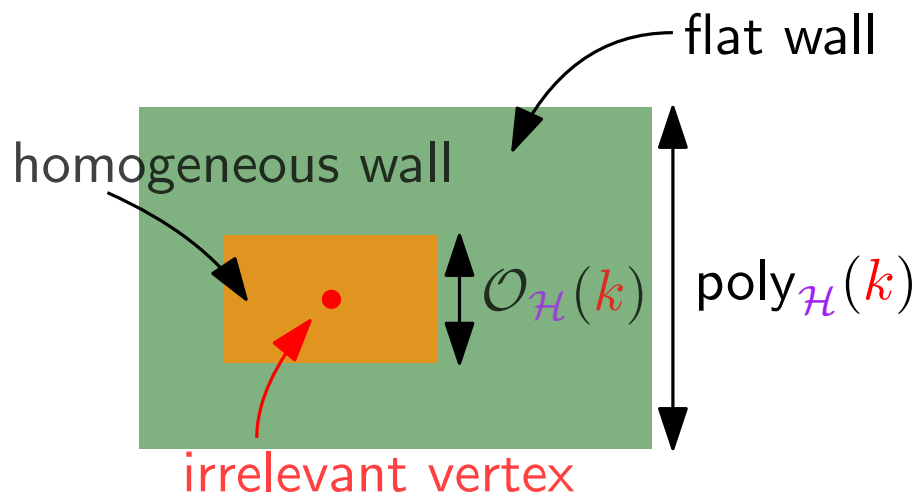
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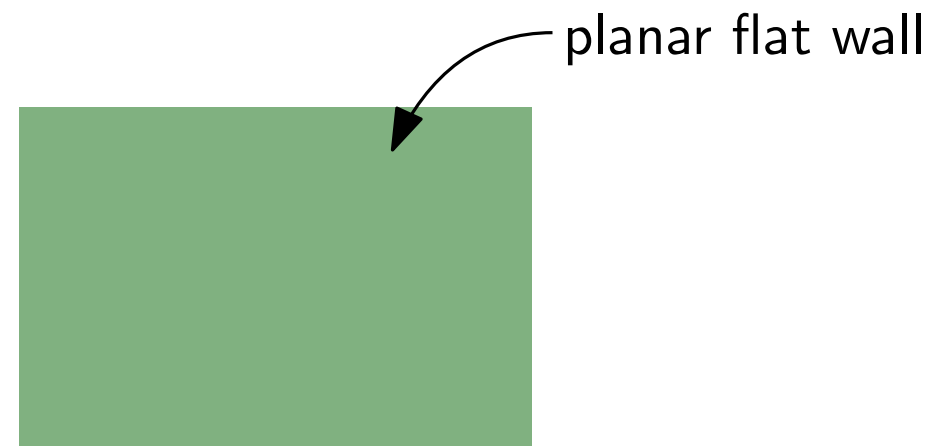
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General case:



Case of surfaces:



\mathcal{H} minor-closed

[Morelle, Sau, Thilikos]

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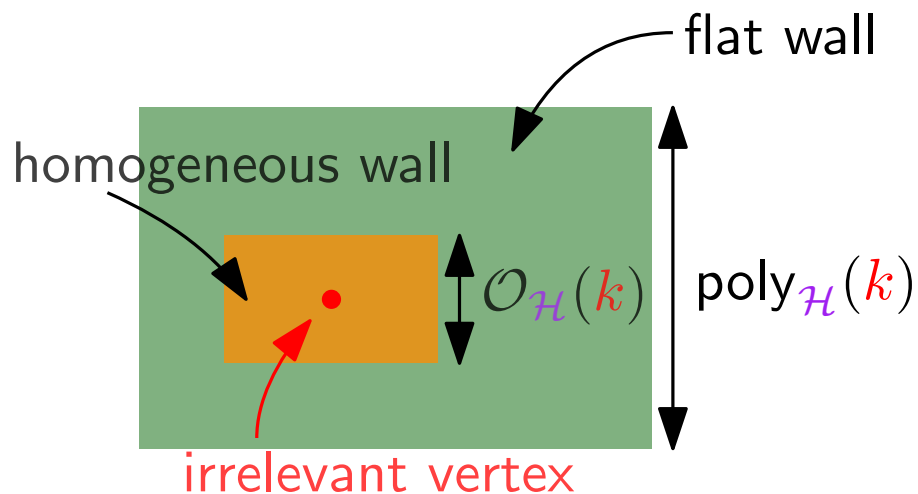
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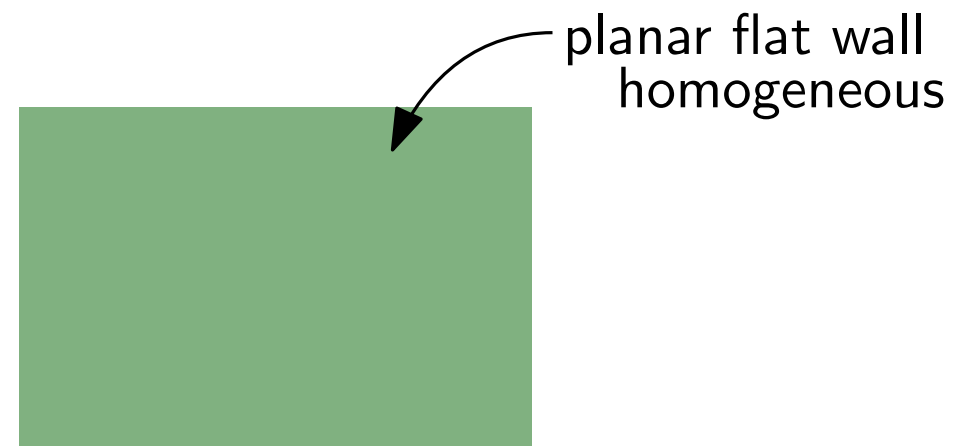
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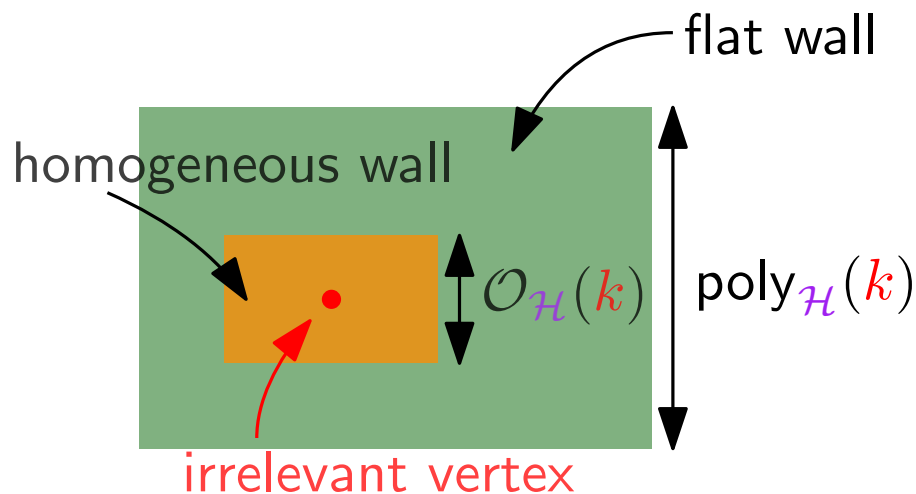
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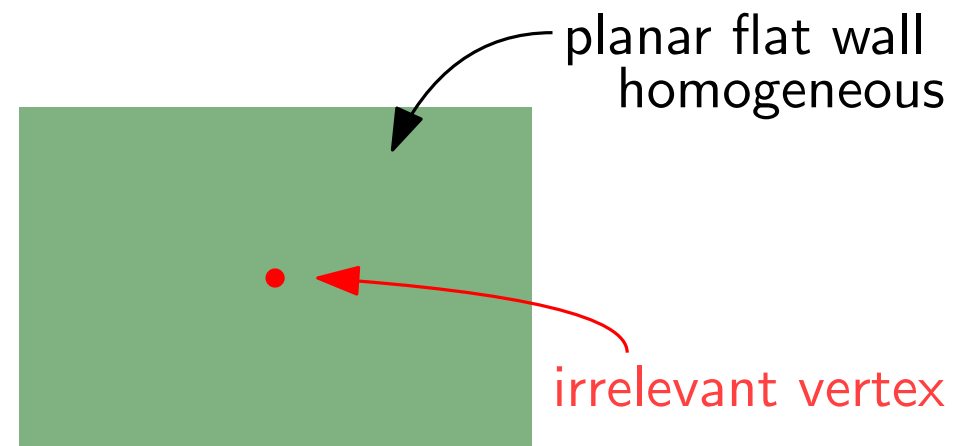
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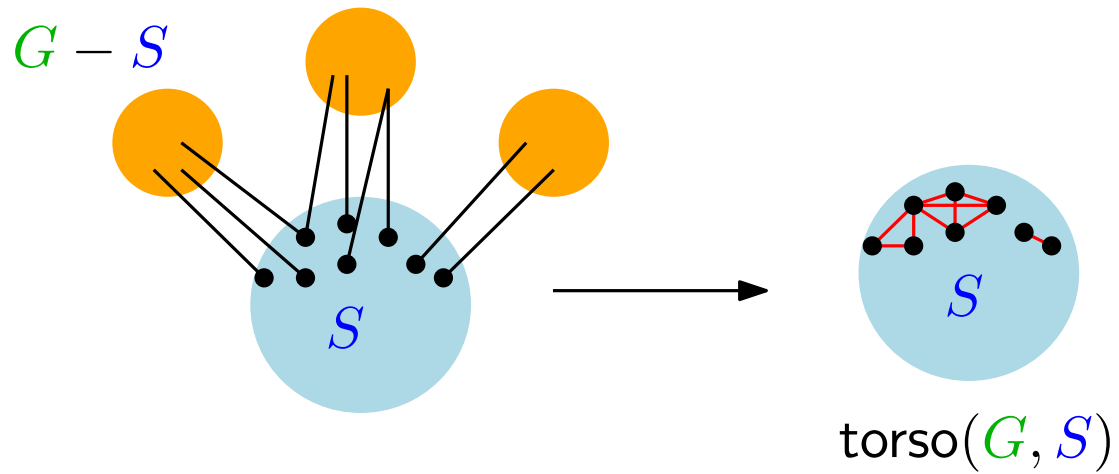


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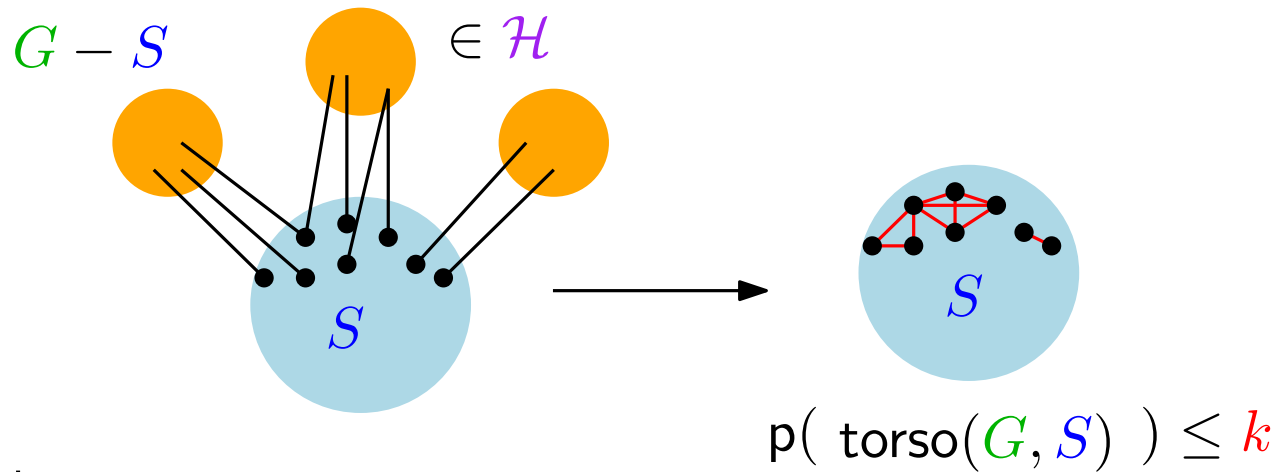


3. Measure p on the modulator

Torso of a vertex set S in a graph G :



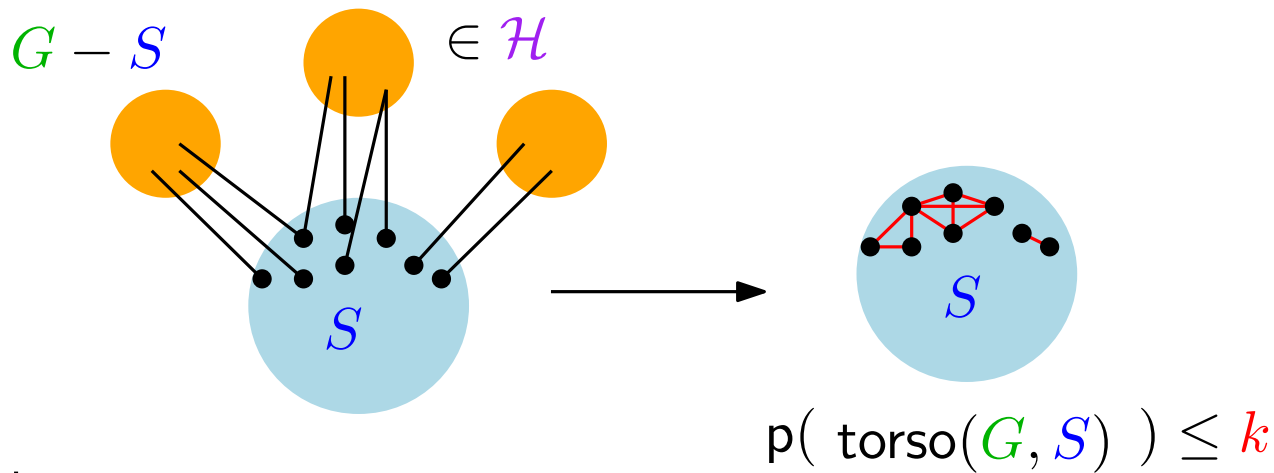
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Parameter p

$$\mathcal{H}\text{-}p(G) = \min\{k \mid \text{there is a vertex set } S \text{ s.t. } p(\text{torso}(G, S)) \leq k \text{ and the components of } G - S \text{ are in } \mathcal{H}\}$$

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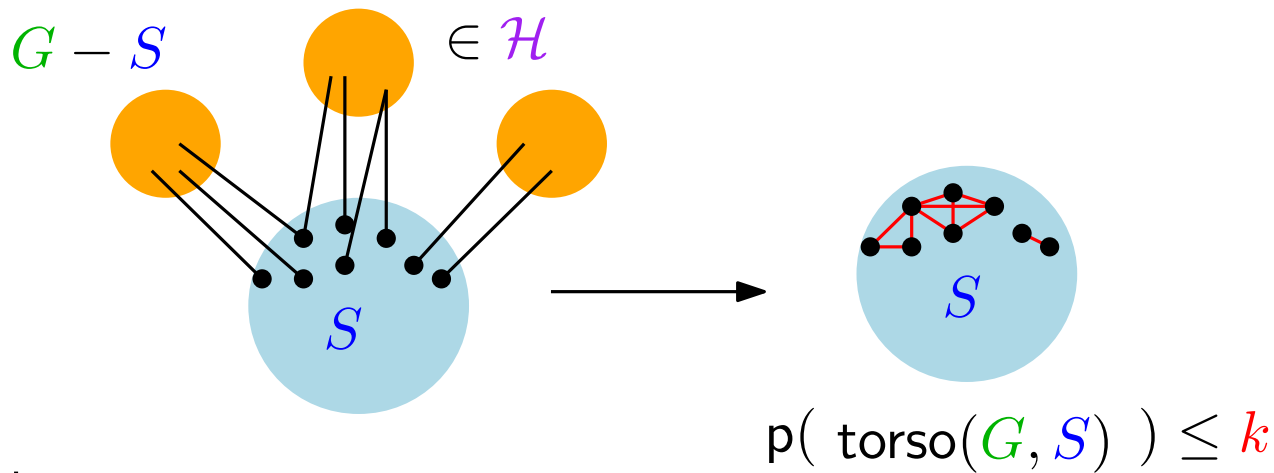


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Graph modification problem: Input: A graph G and an integer k .
Output: Is $\mathcal{H}\text{-}p(G) \leq k$?

Torso of a vertex set S in a graph G :

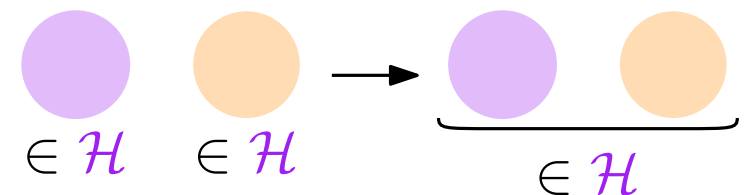


Parameter p

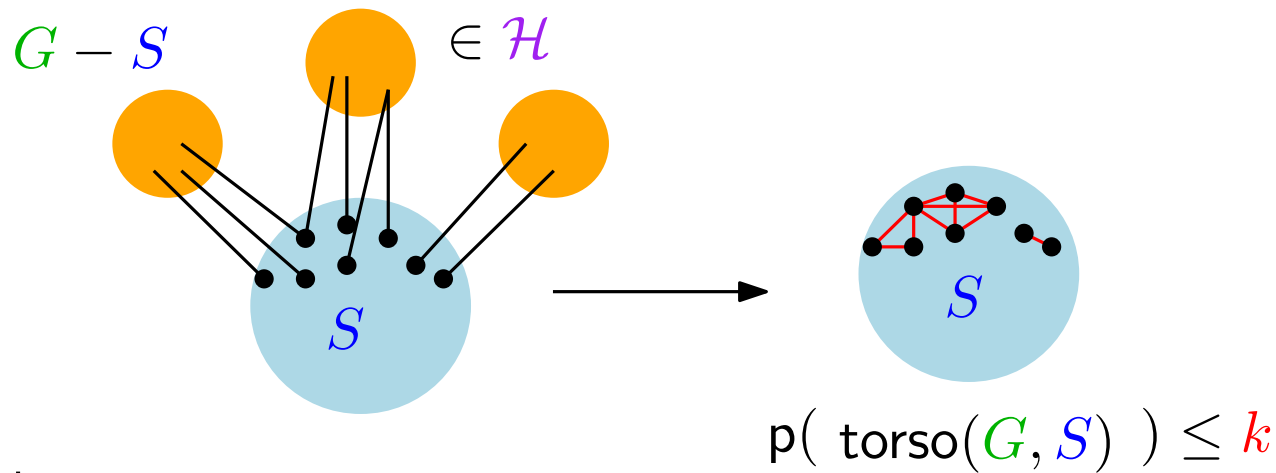
$\mathcal{H}\text{-}p(G) = \min\{k \mid \text{there is a vertex set } S \text{ s.t. } p(\text{torso}(G, S)) \leq k \text{ and the components of } G - S \text{ are in } \mathcal{H}\}$

Graph modification problem: Input: A graph G and an integer k .
Output: Is $\mathcal{H}\text{-}p(G) \leq k$?

$\mathcal{H}\text{-size} \rightarrow \text{VERTEX DELETION TO } \mathcal{H}$ if \mathcal{H} is closed under disjoint union



Torso of a vertex set S in a graph G :



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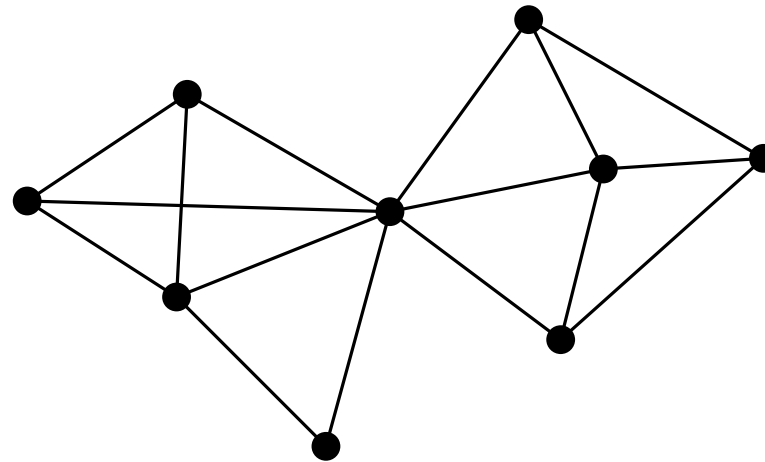
$\mathcal{H}\text{-size} \rightarrow \text{VERTEX DELETION TO } \mathcal{H}$

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Torso of a vertex set S in a graph G :

treedepth $\text{td}(G)$:

Step 0



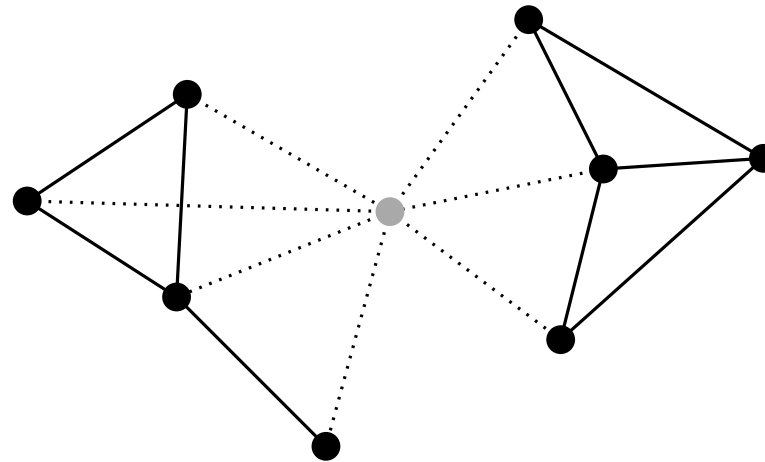
At each step, remove 1 vertex from each component

\mathcal{H} -td \rightarrow ELIMINATION DISTANCE TO \mathcal{H} [Bulian, Dawar, '16]

Torso of a vertex set S in a graph G :

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Step 1



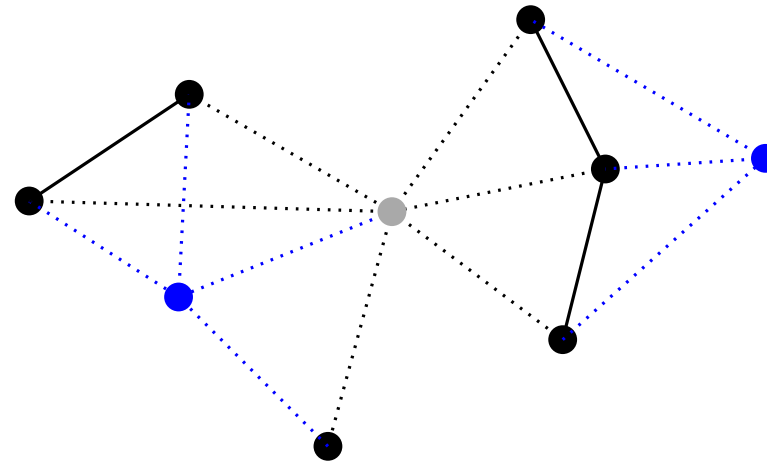
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Step 2



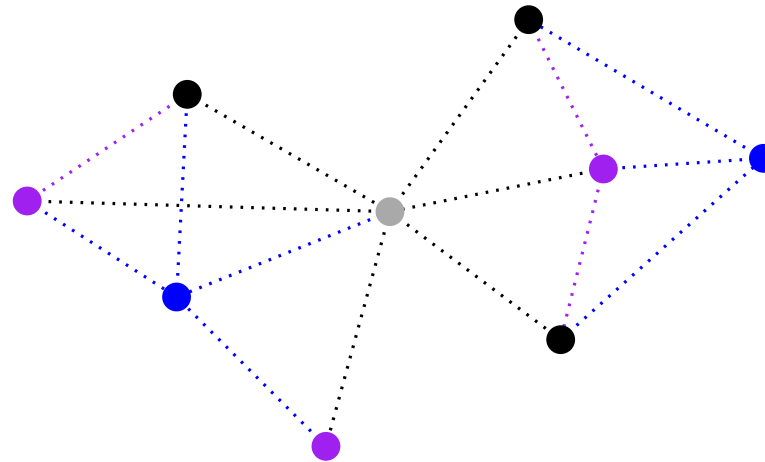
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Step 3



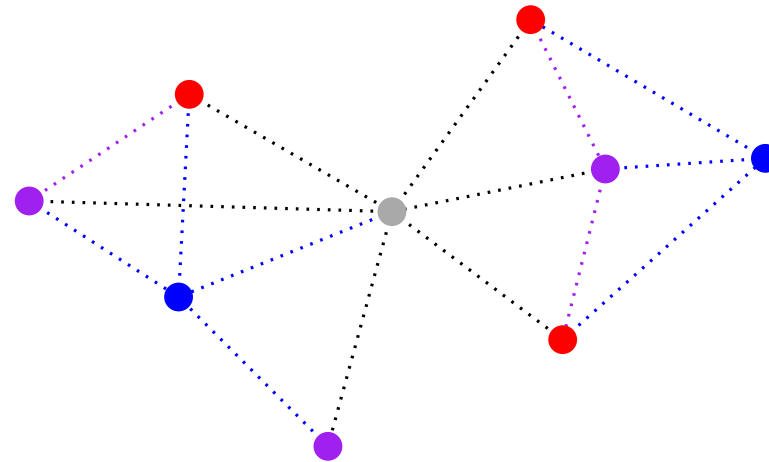
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Step 4



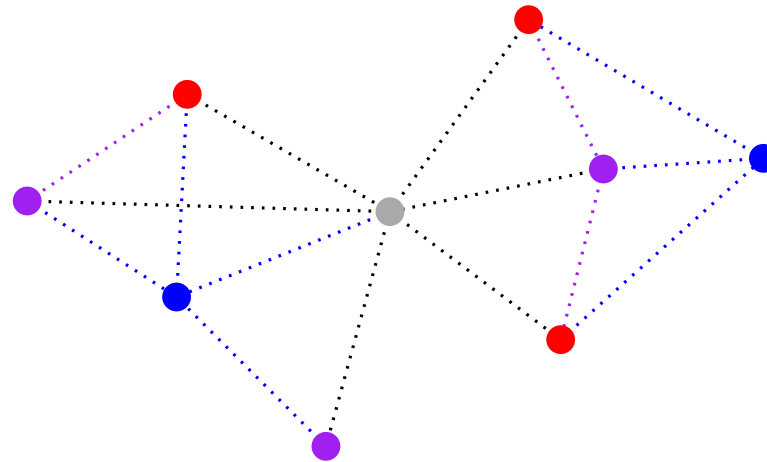
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Torso of a vertex set S in a graph G :

treedepth $\text{td}(G)$: min number of steps to remove all vertices

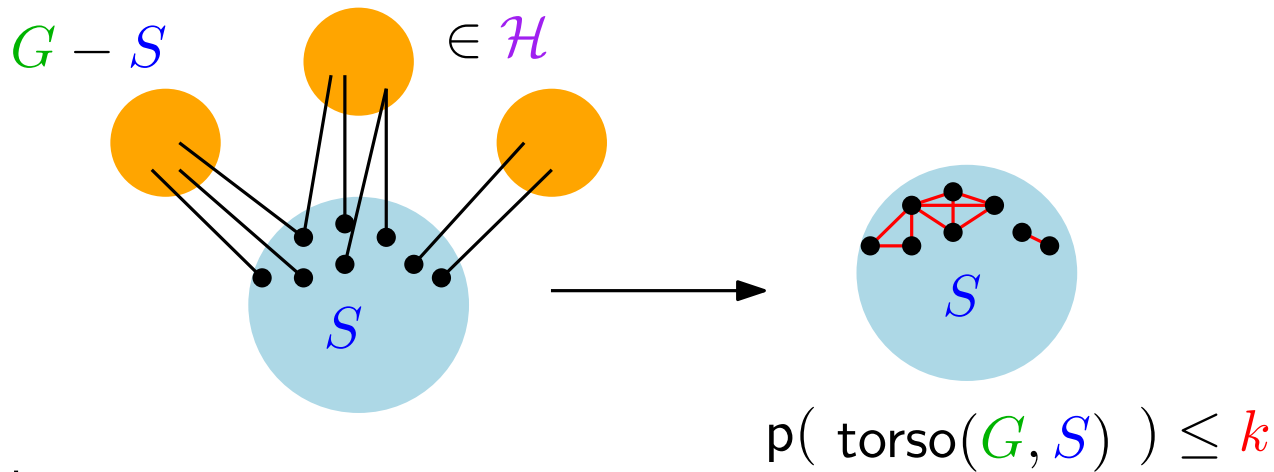
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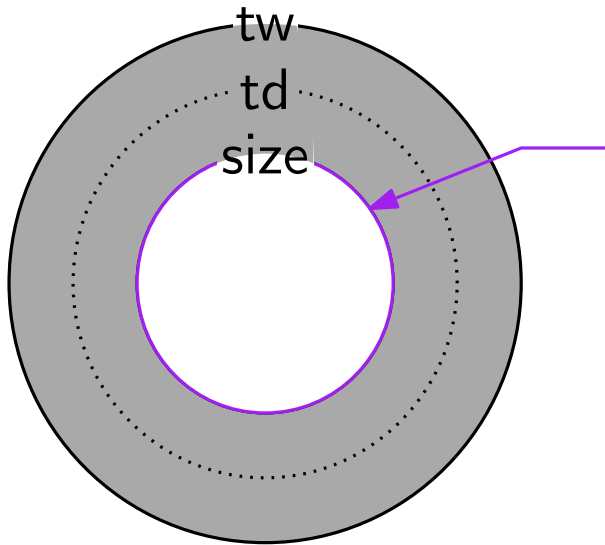
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$\mathcal{H}\text{-tw} \rightarrow \mathcal{H}\text{-TREEWIDTH}$ [Eiben, Ganian, Hamm, Kwon, '21]

for each G , $\text{tw}(G) \leq \text{td}(G) \leq \text{size}(G)$



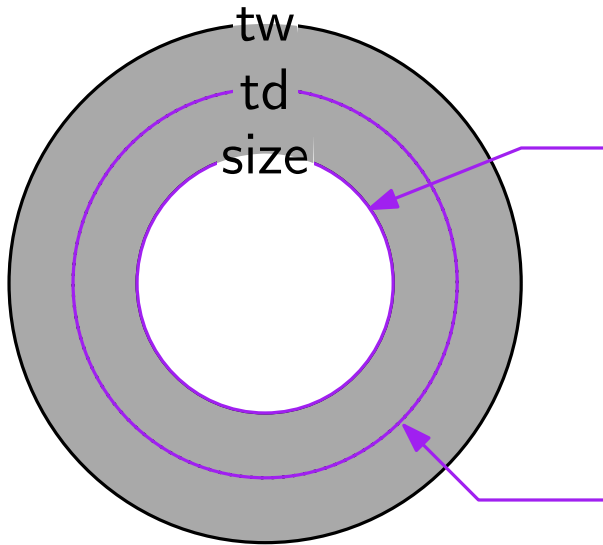
VERTEX DELETION TO \mathcal{H}

[Morelle, Sau, Stamoulis, Thilikos]

$$2^{\text{poly}_{\mathcal{H}}(k)} \cdot n^2$$

← \mathcal{H} minor-closed

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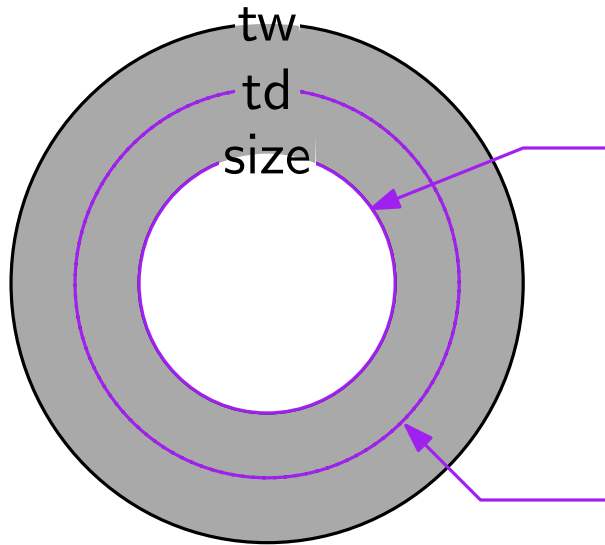
[Robertson, Seymour, '04] + [Bulian, Dawar, '17] +

[Kawarabayashi, Kobayashi, Reed, '12]

$f(k) \cdot n^2$ for some computable f

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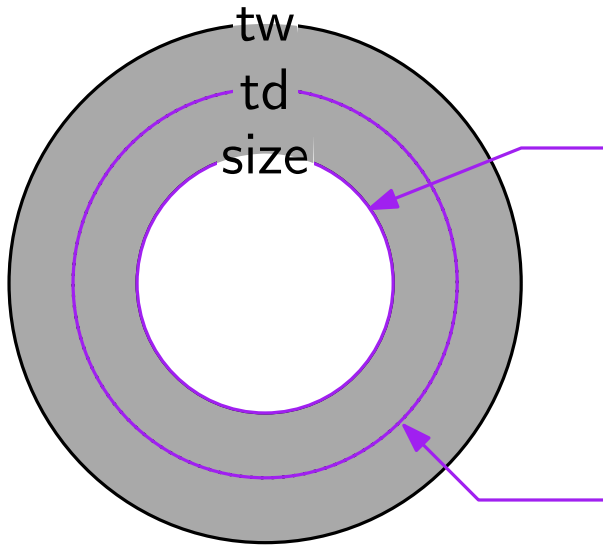
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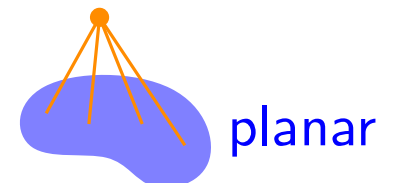
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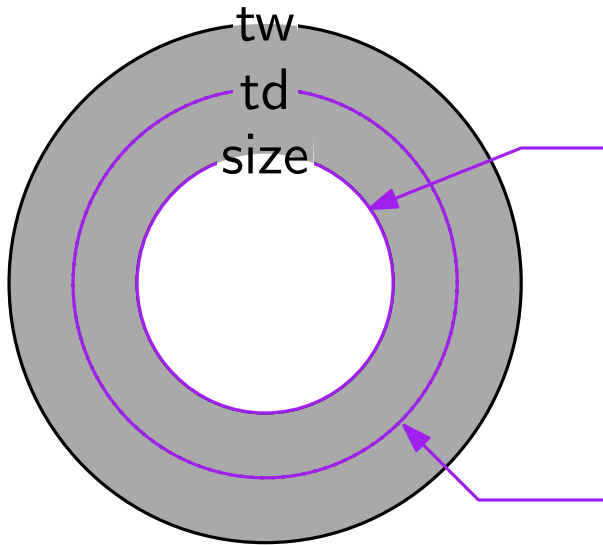
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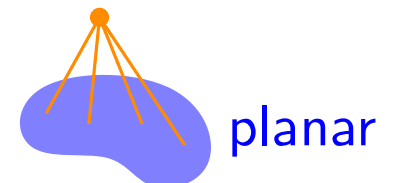
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Sketch of the proof for VERTEX DELETION TO \mathcal{H} :

Win/Win strategy on the **treewidth** $\text{tw}(G)$ of G :

If G has **big** treewidth:

then G contains a **big grid** as a minor.

If there is a **big flow** from a set A to the grid:

then $A \cap S \neq \emptyset$ “**obligatory set**”

Branching step: guess $v \in A$ s.t. $v \in S$ and **recurse** on $(G - v, k - 1)$.

Otherwise there is a **small flow** to the grid:

then G contains a “**flat wall**”

Irrelevant vertex technique: there is a vertex v in the wall s.t.

(G, k) and $(G - v, k)$ are equivalent instances. “**irrelevant vertex**”

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Representative-based technique [Baste, Sau, Thilikos, '19]

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17 - 4 DP for treedepth [Reidl, Rossmanith, Villaamil, Sikdar, '14]

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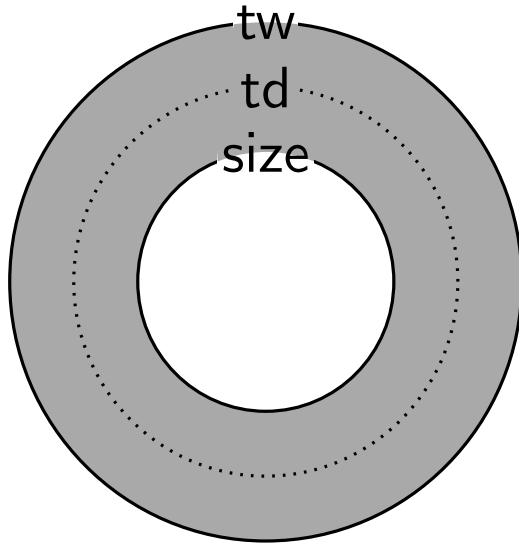
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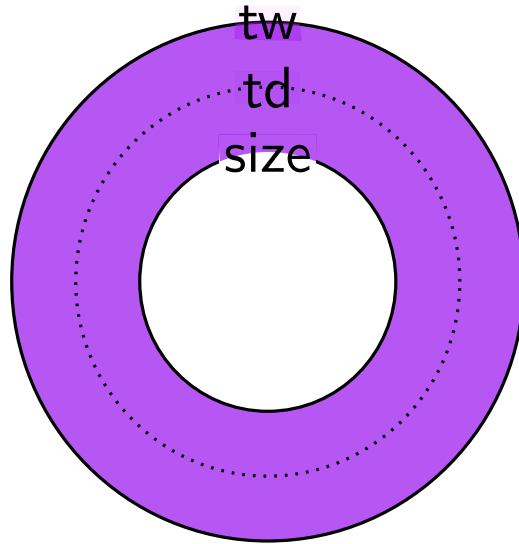
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Limit of the irrelevant vertex technique



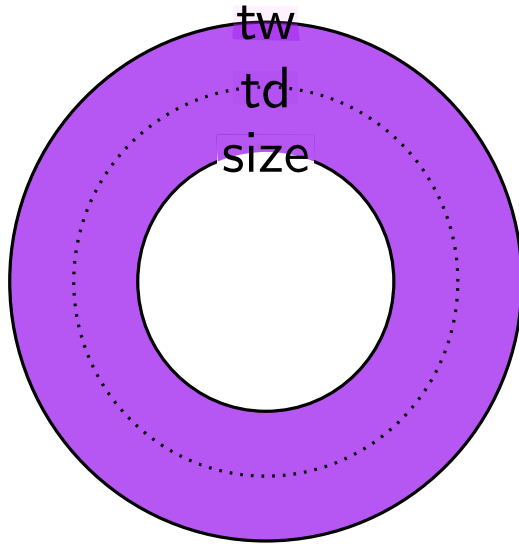
Limit of the irrelevant vertex technique



[Fomin, Golovach, Sau, Stamoulis, Thilikos, '23]

For \mathcal{H} minor-closed, the irrelevant vertex technique works for any parameter \mathcal{H} -p such that $\text{size} \geq p \geq \text{tw}$.

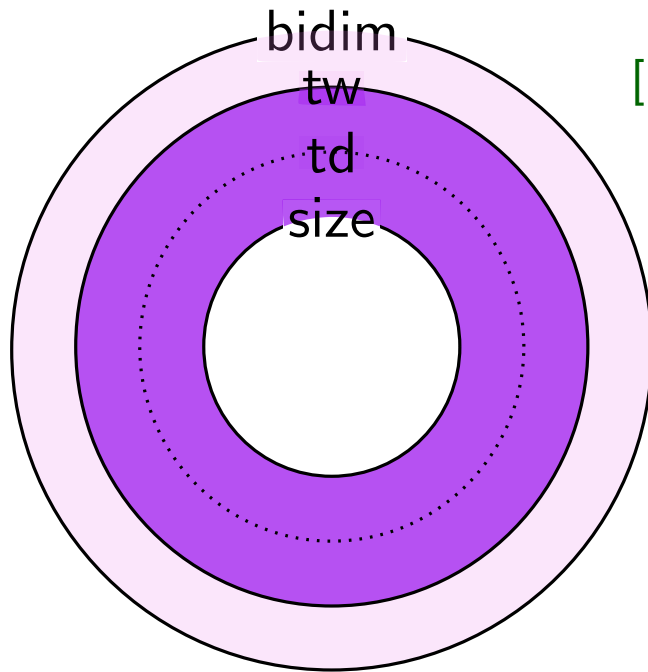
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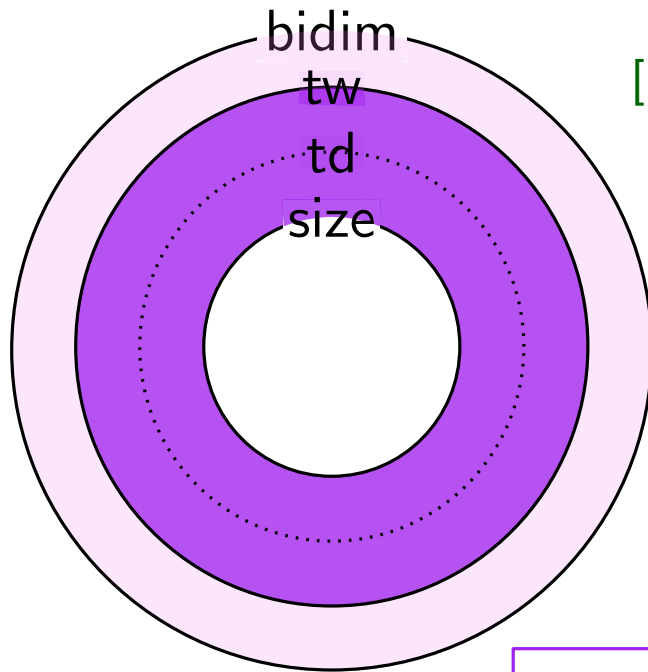
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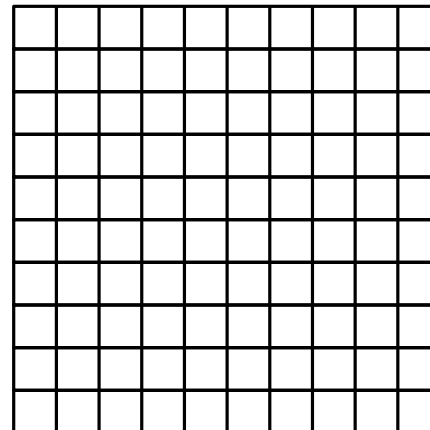
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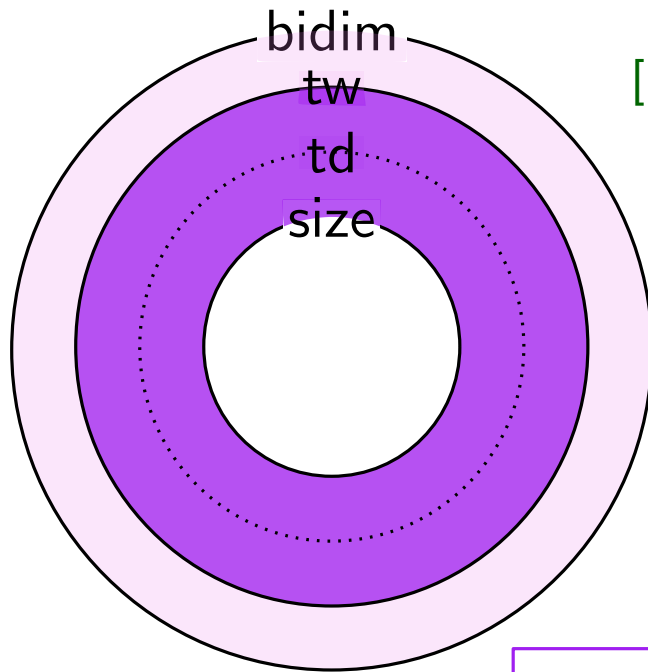
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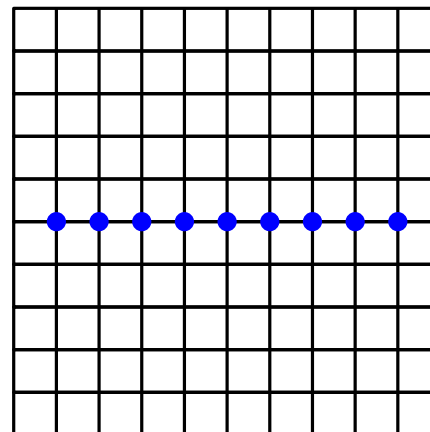
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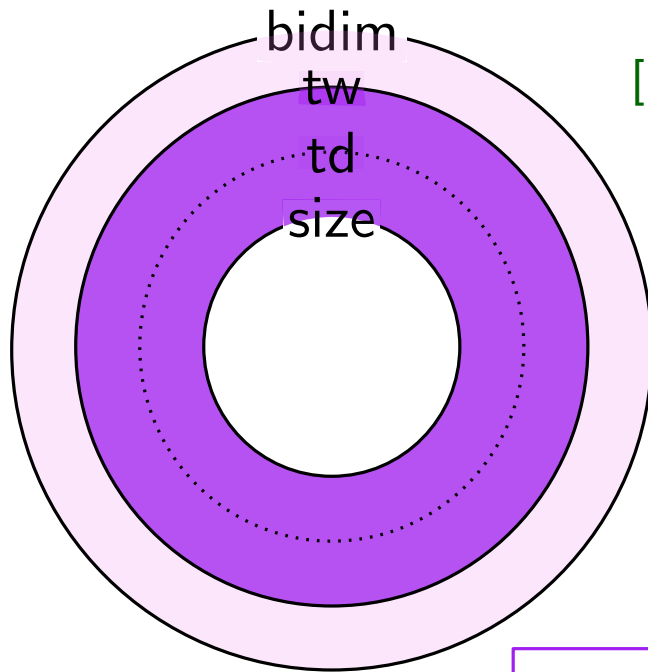
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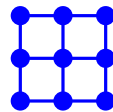
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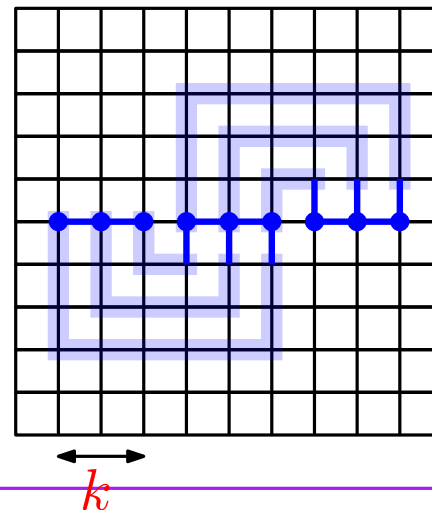
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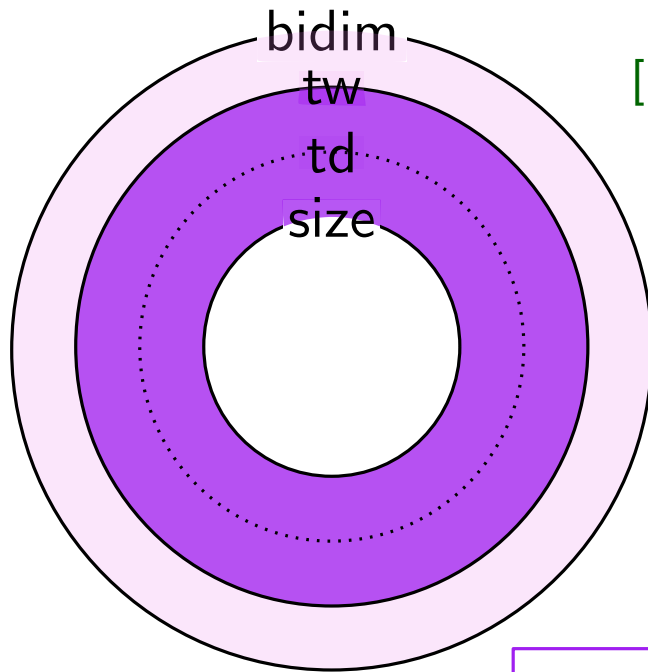
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$\text{bidim}(G, S) = k$



Limit of the irrelevant vertex technique



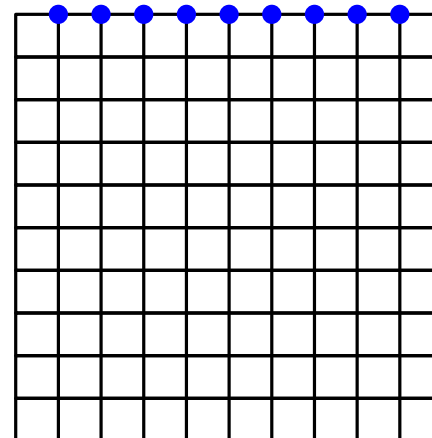
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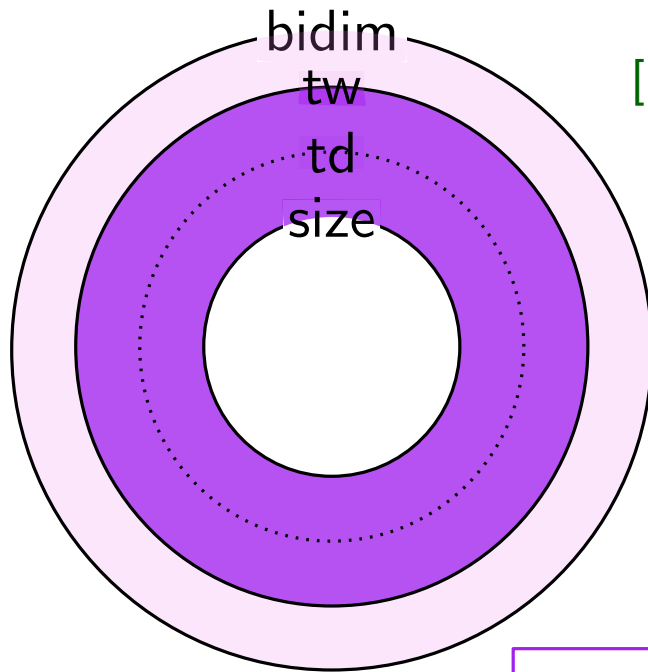
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Limit of the irrelevant vertex technique



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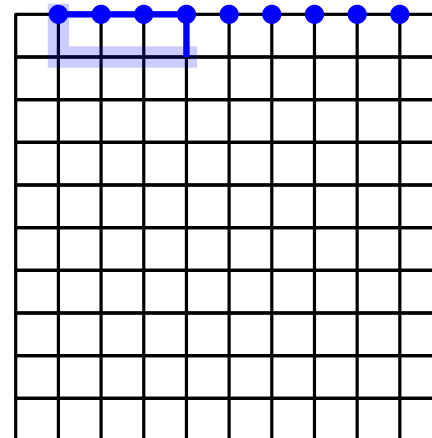
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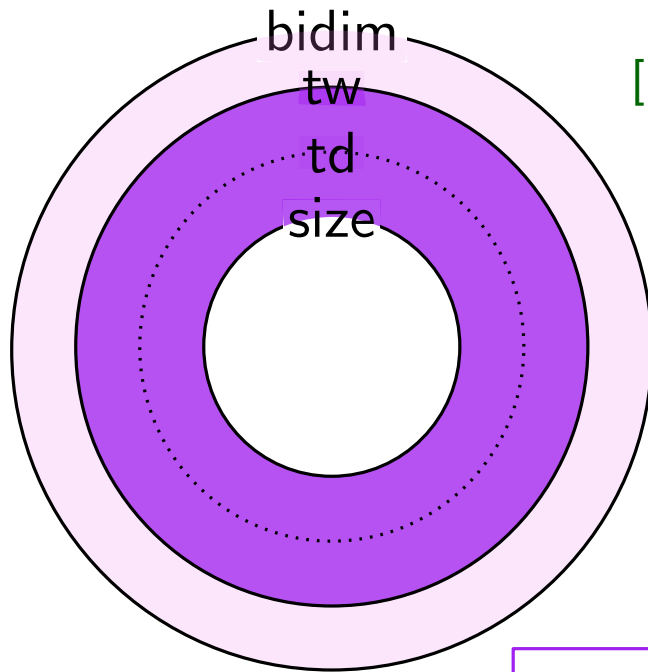
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$$\text{bidim}(G, S) = 2$$



Limit of the irrelevant vertex technique



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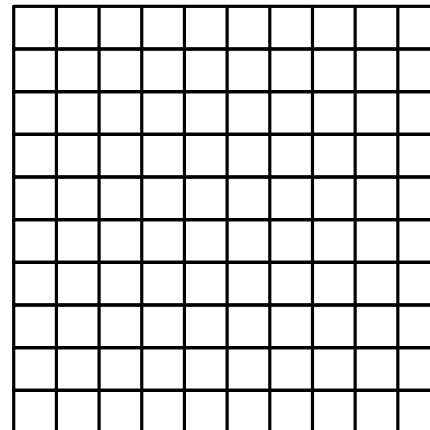
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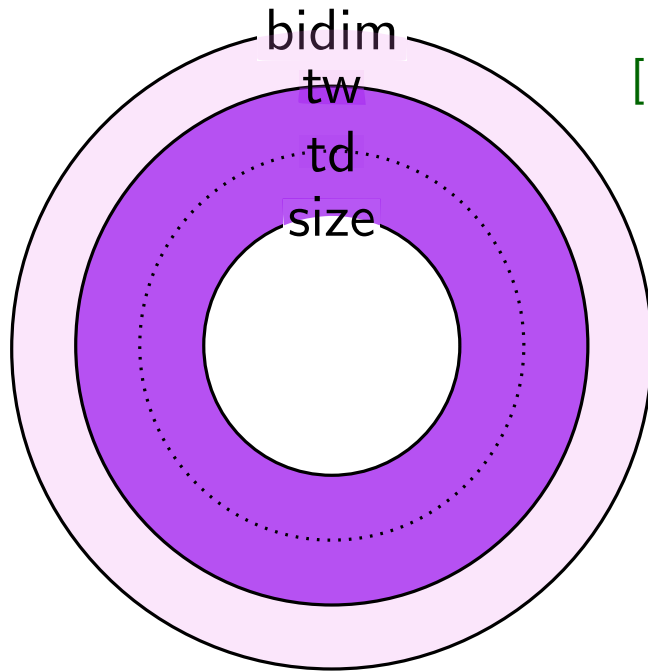
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“max size of a grid
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Limit of the irrelevant vertex technique



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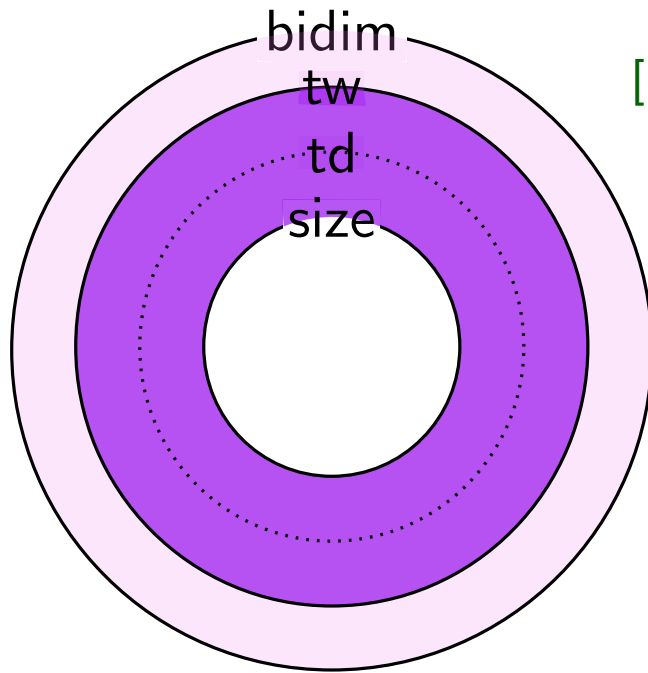
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For \mathcal{H} minor-closed, the irrelevant vertex technique works up to modulators of bounded **bidimensionality**.

Any **graph modification problem** where:

- the **modulator** has bounded bidimensionality
 - the **target class** is minor-closed
 - the set of allowed **modifications** is expressible in CMSO logic
- can be solved in time $f(k) \cdot n^2$, for some computable f .

Limit of the irrelevant vertex technique



[Fomin, Golovach, Sau, Stamoulis, Thilikos, '23]

For \mathcal{H} minor-closed, the irrelevant vertex technique works for any parameter \mathcal{H} -p such that $\text{size} \geq p \geq \text{tw}$. “up to modulators of bounded tw”

[Sau, Stamoulis, Thilikos, '25]

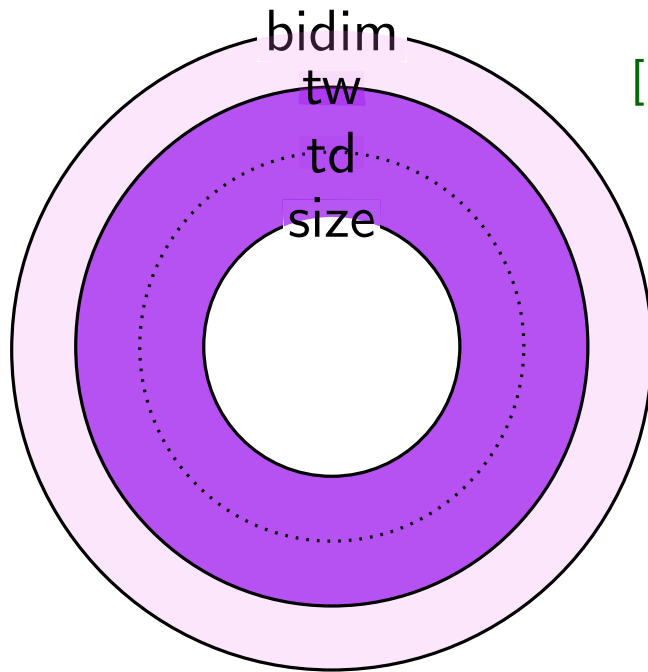
For \mathcal{H} minor-closed, the irrelevant vertex technique works up to modulators of bounded **bidimensionality**.

Any **graph modification problem** where:

- the **modulator** has **bounded bidimensionality**
 - the **target class** is **minor-closed**
 - the set of allowed **modifications** is expressible in **CMSO logic**
- can be solved in time $f(k) \cdot n^2$, for some computable f .

variables v, e, V, E
quantifiers \forall, \exists
connectives $\wedge, \vee, \Rightarrow, \neg, \in$
relations $\text{inc}(\cdot), |\cdot| = q \bmod r$

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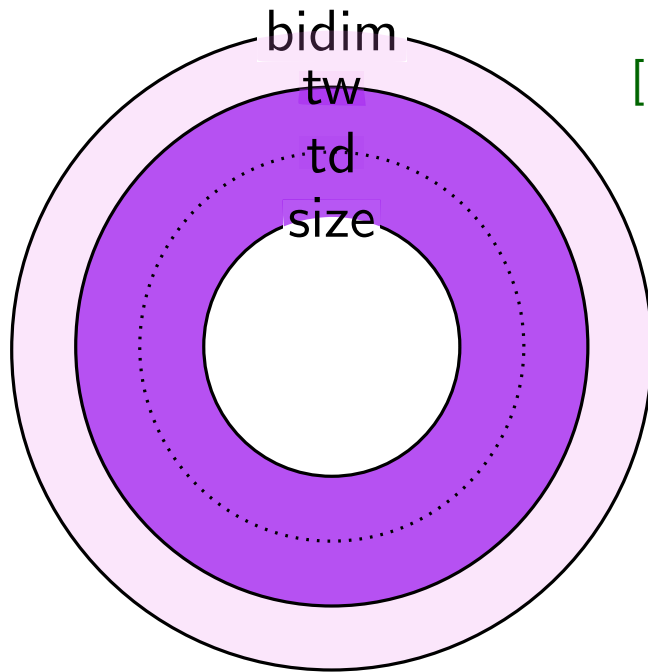
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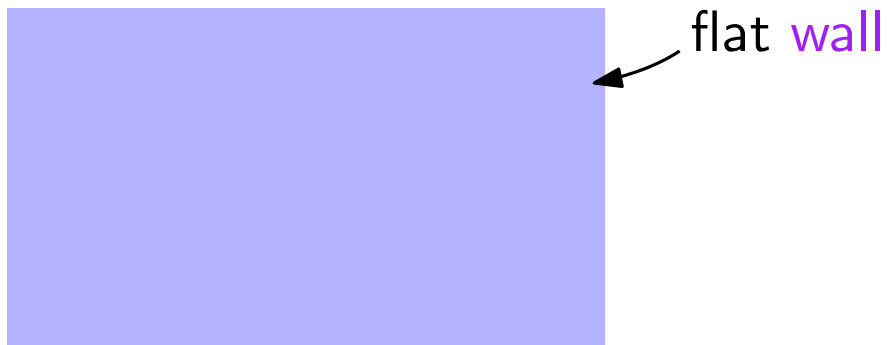
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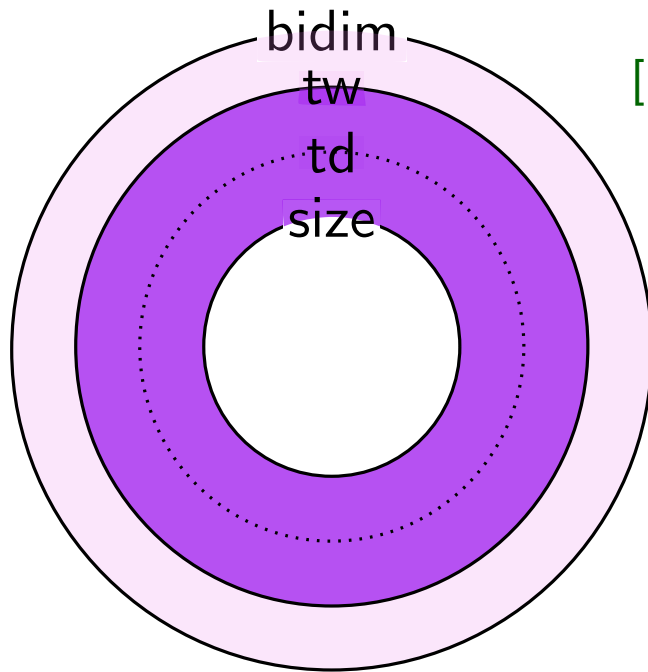
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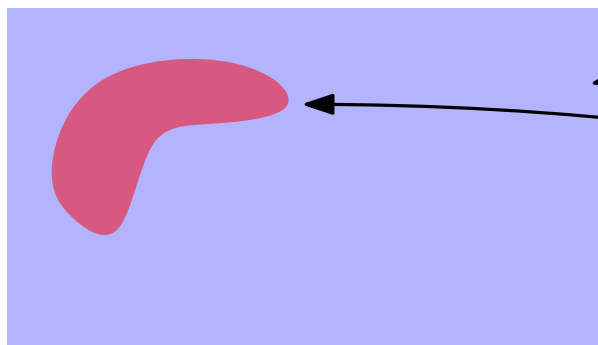
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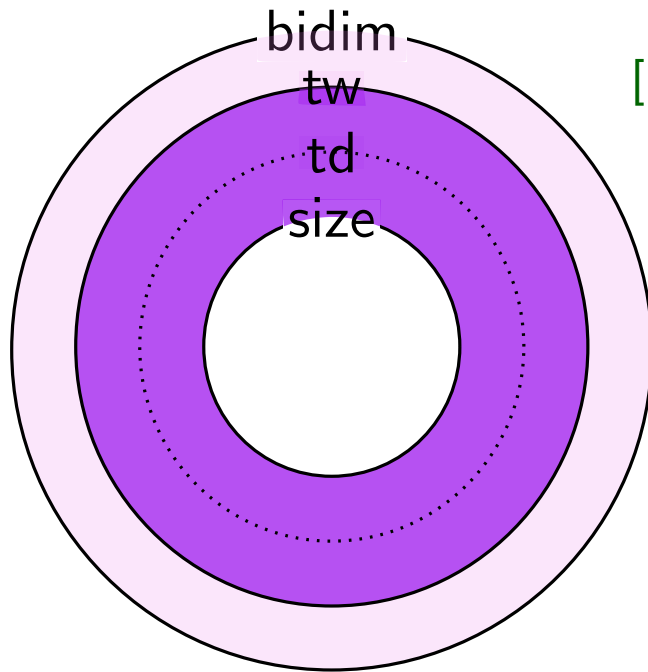
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flat wall

no matter how we delete/modify the modulator

Limit of the irrelevant vertex technique



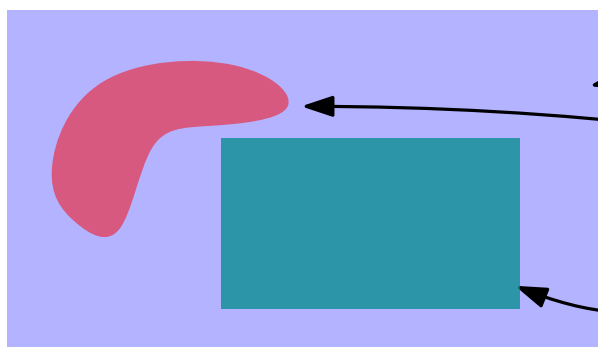
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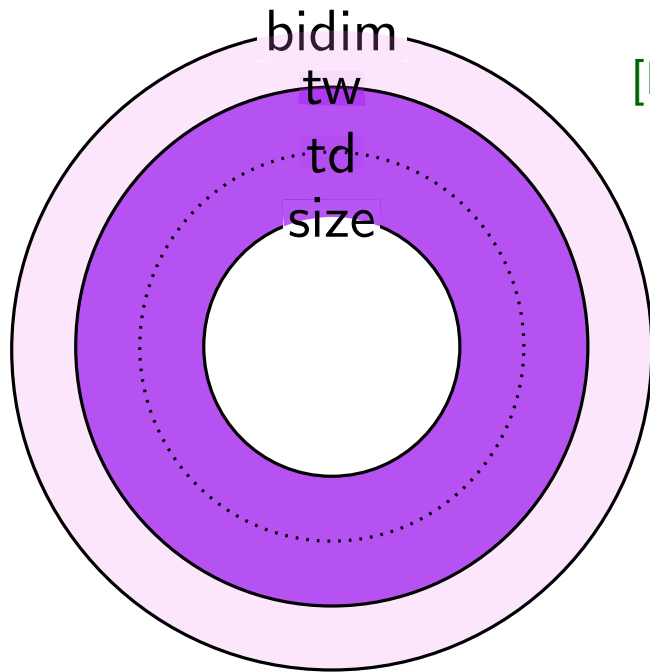


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no matter how we delete/modify the modulator

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Limit of the irrelevant vertex technique



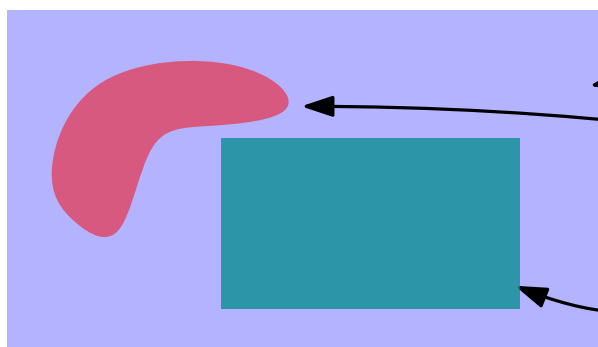
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Breaking the limit

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How to solve a graph modification problem where the modulator has unbounded bidimensionality?

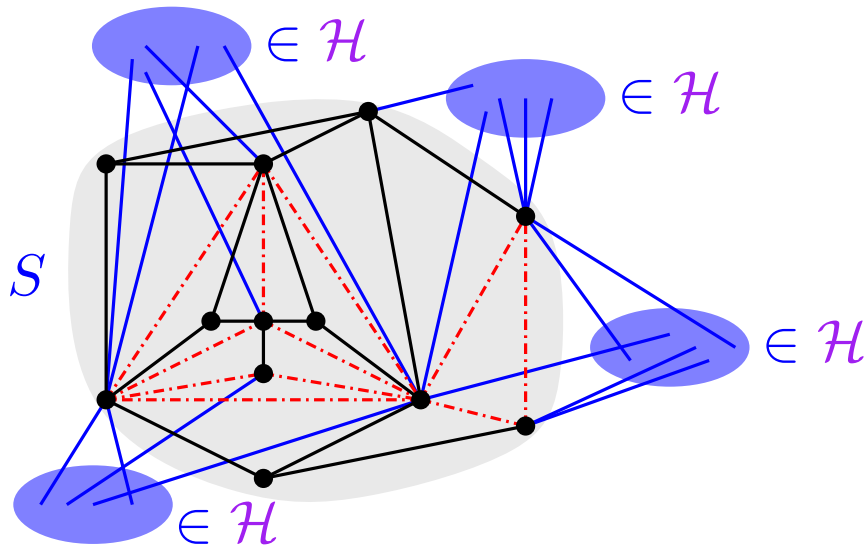
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How to solve a graph modification problem where the modulator has **unbounded bidimensionality**?

\mathcal{H} -PLANARITY

Input: A graph G .

Output: Is there a vertex set S whose torso is **planar** and s.t. the connected components of $G - S$ are in \mathcal{H} ?



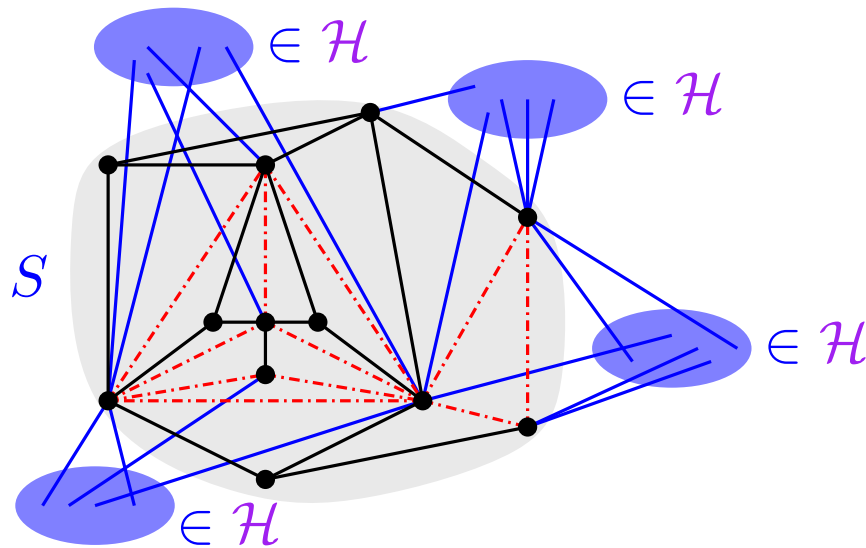
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If \mathcal{H} is hereditary, CMSO-definable, and decidable in time $\mathcal{O}(n^c)$, then \mathcal{H} -PLANARITY is solvable in time $\mathcal{O}(n^4 + n^c \log n)$.

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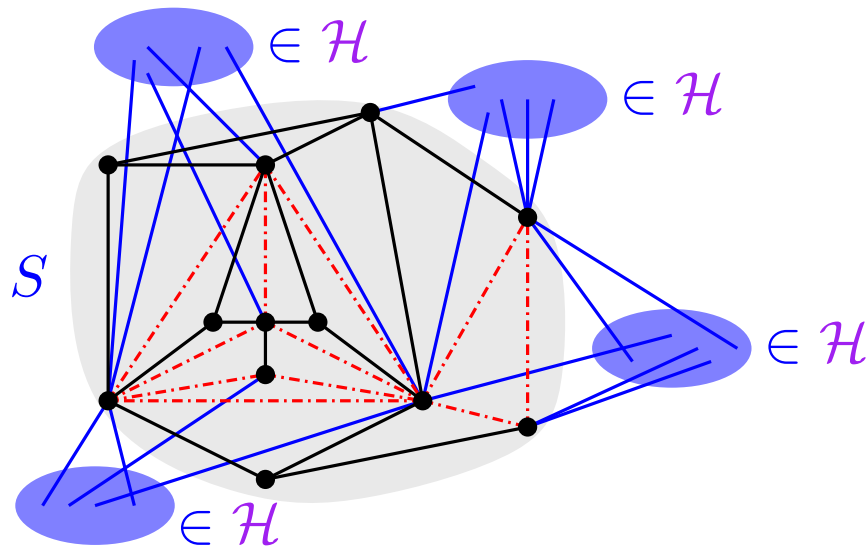
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if $G \in \mathcal{H}$, then $G - v \in \mathcal{H}$



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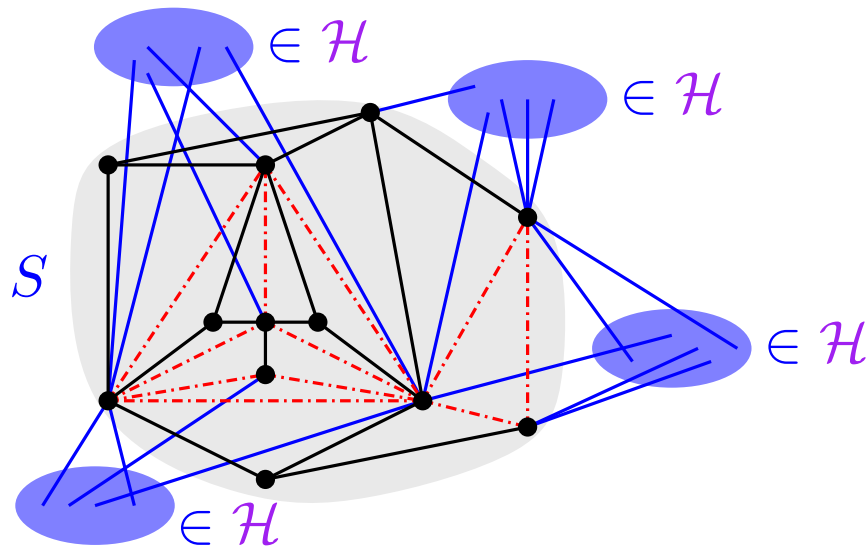
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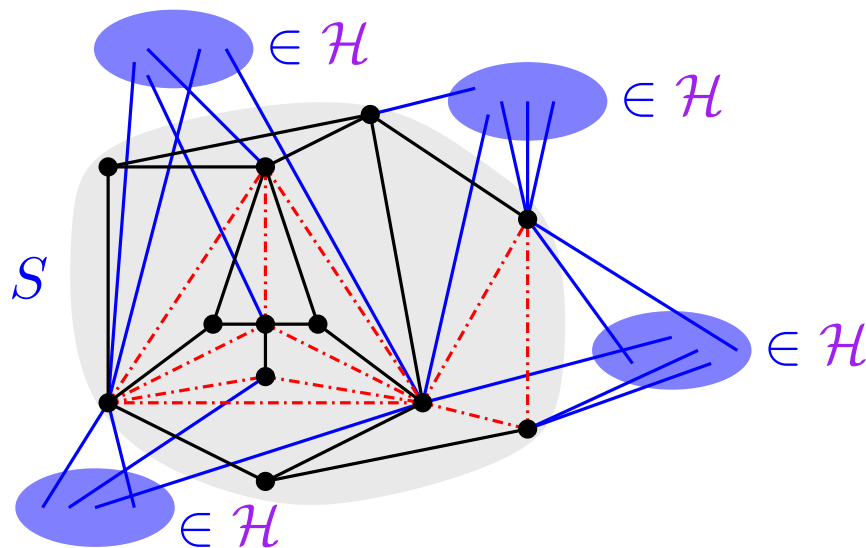
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→ new irrelevant vertex technique

Sketch of the proof

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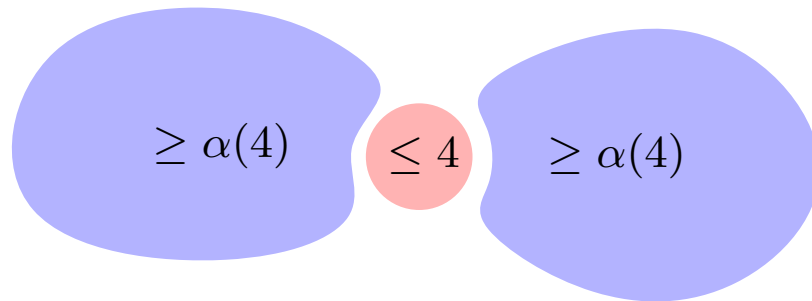
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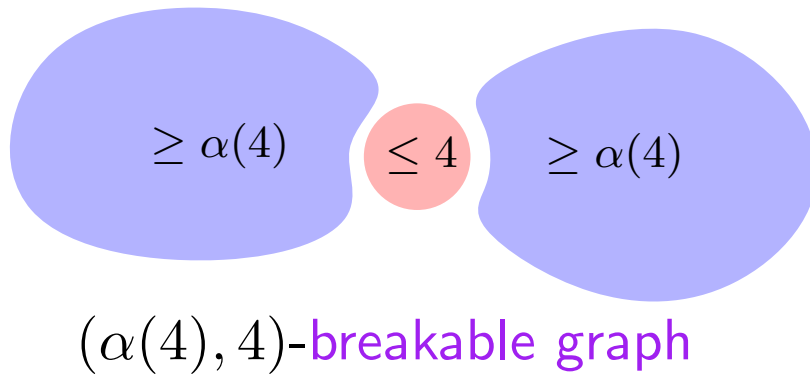


$(\alpha(4), 4)$ -**breakable graph**

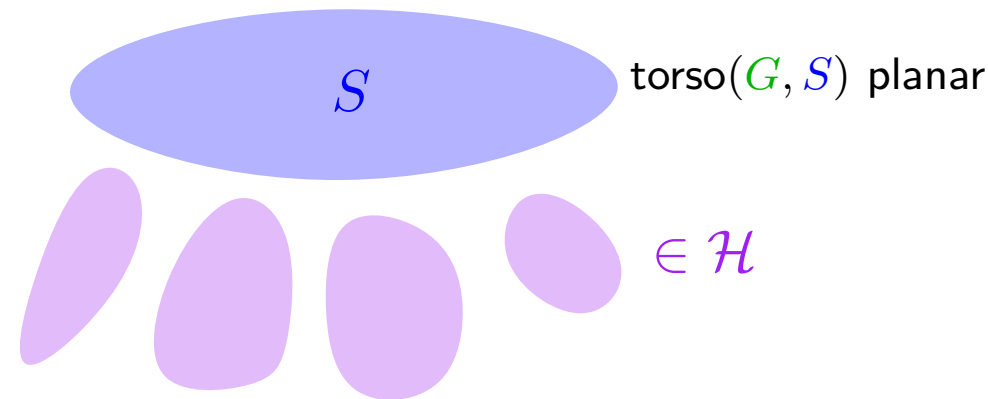
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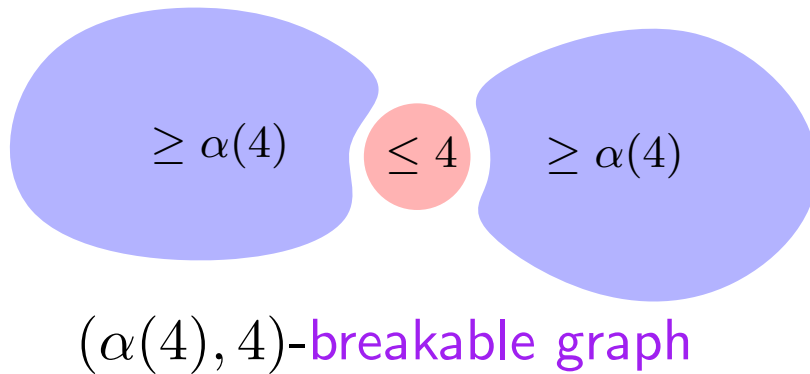
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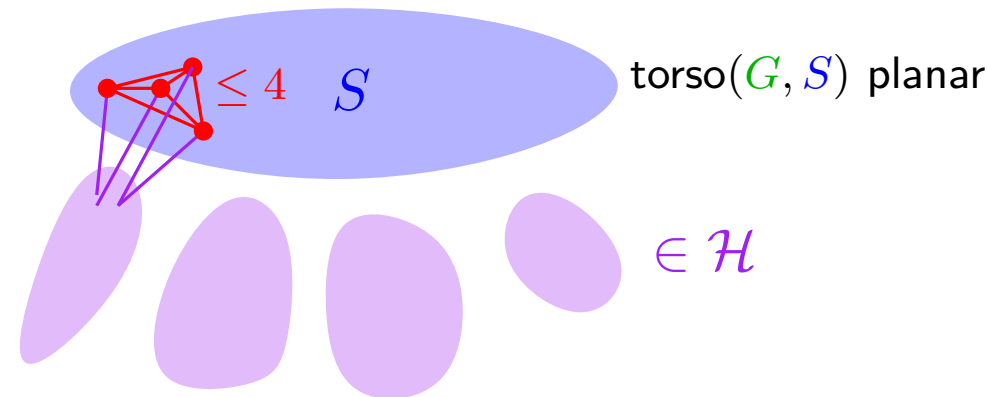
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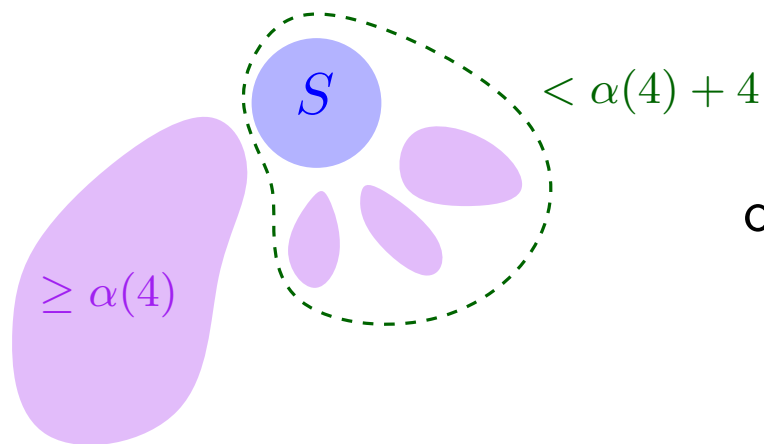
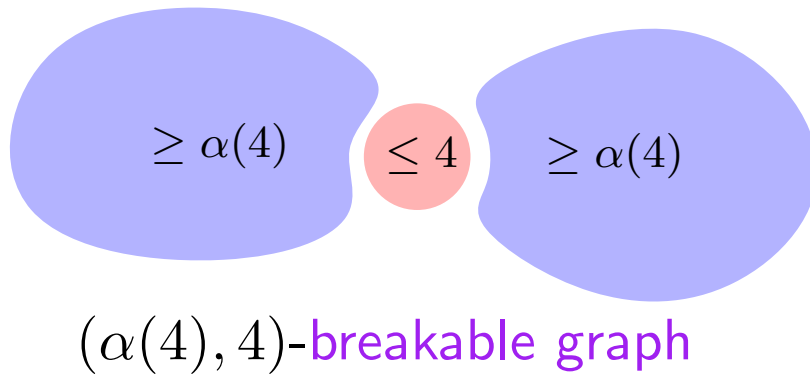
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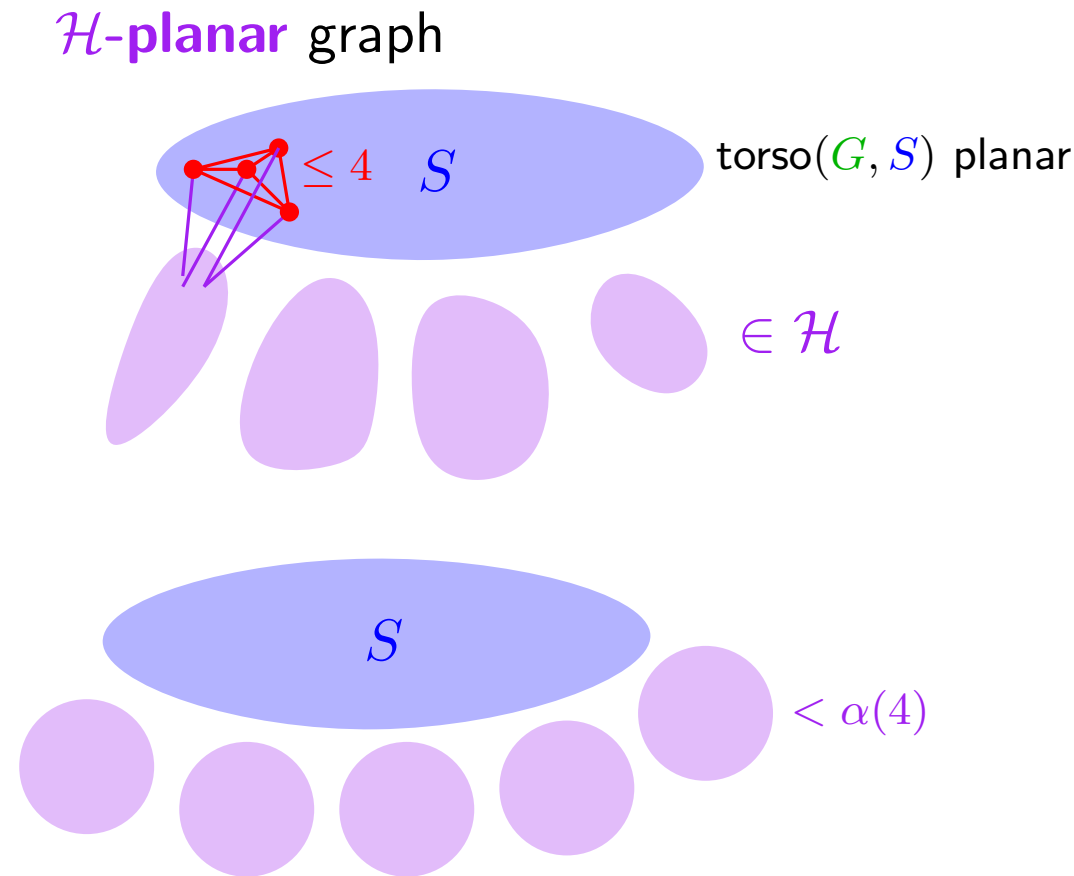
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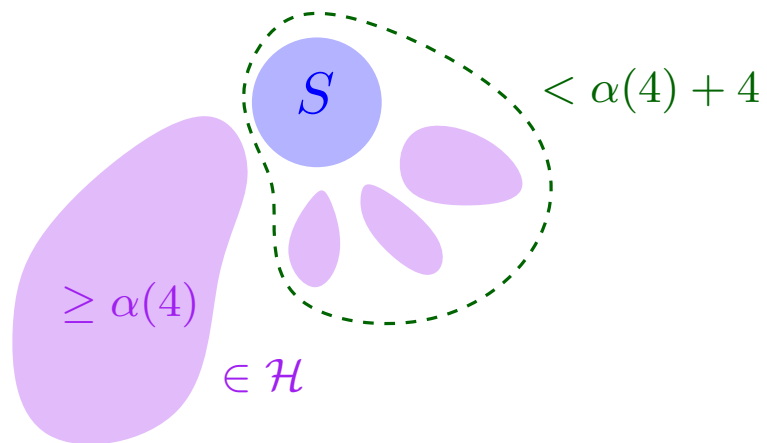
or



Sketch of the proof

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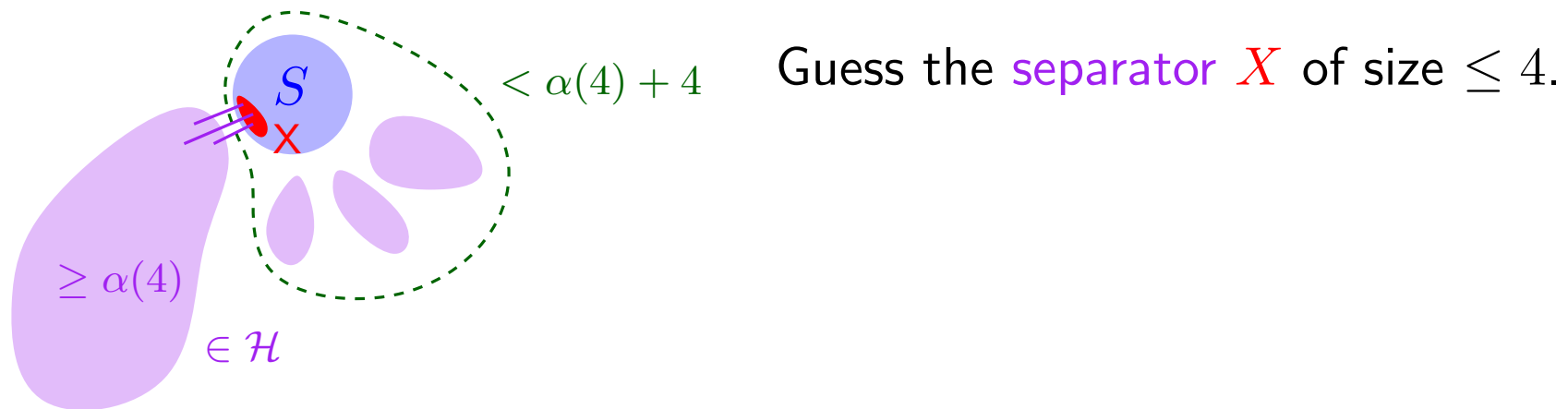
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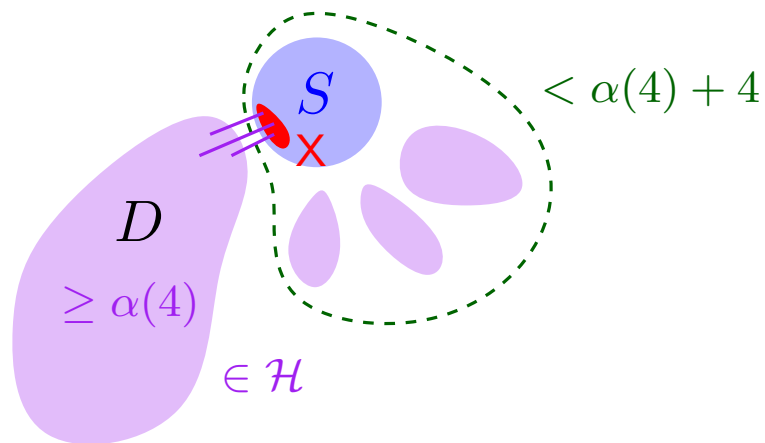
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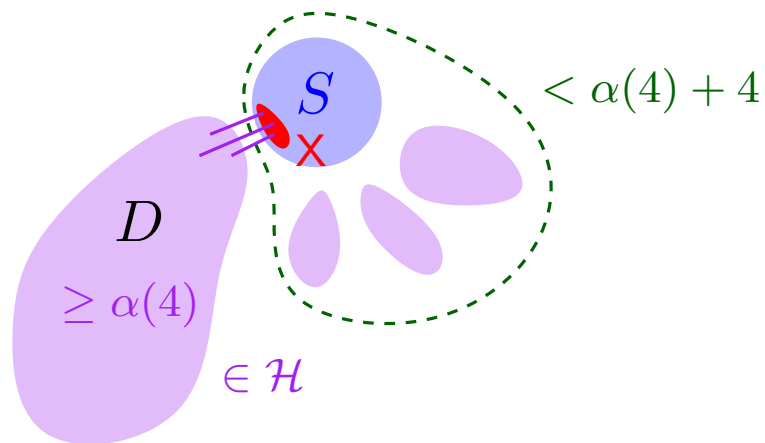
Guess the separator X of size ≤ 4 .

Check if there is a unique component D in $G - X$ of size $\geq \alpha(4)$.

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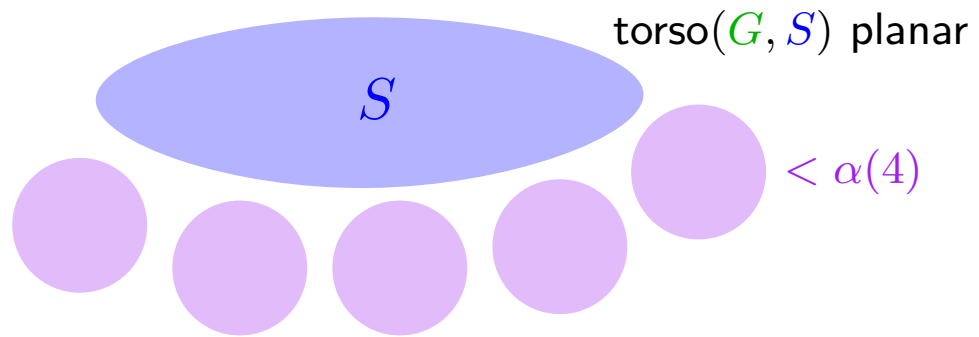


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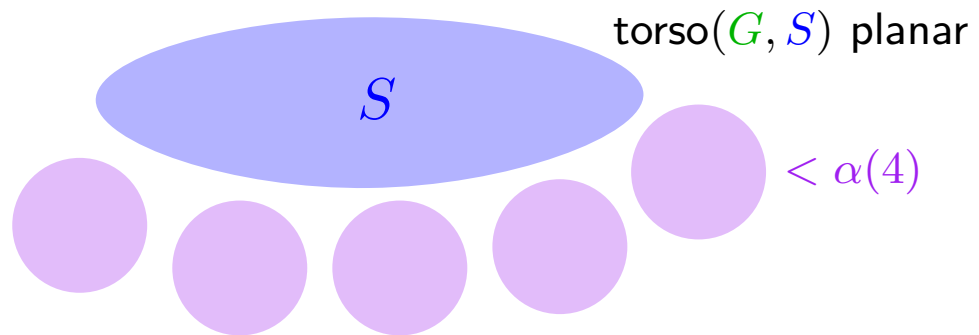
Check if there is a unique component D in $G - X$ of size $\geq \alpha(4)$.

Guess the set $S \supseteq X$ in $G - D$ and check if the **torso** of S is **planar** and if the components of $G - S$ are in \mathcal{H} .

Sketch of the proof

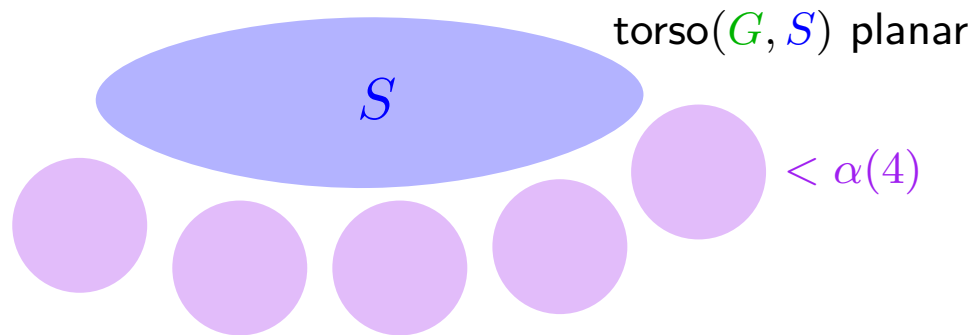


Sketch of the proof



SMALL-LEAVES \mathcal{H} -PLANARITY

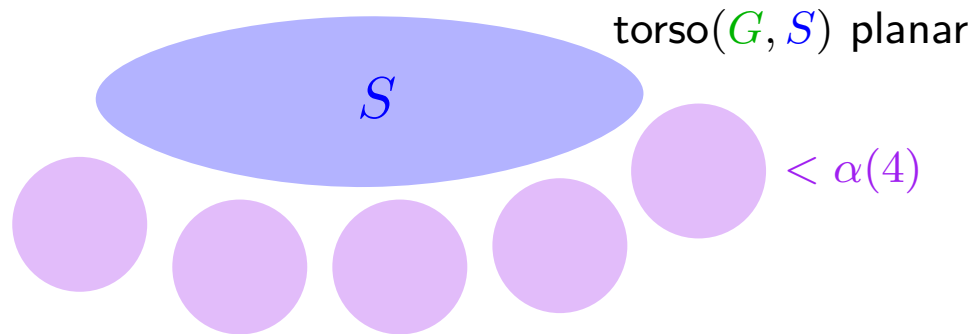
Sketch of the proof



SMALL-LEAVES \mathcal{H} -PLANARITY

Restate the problem

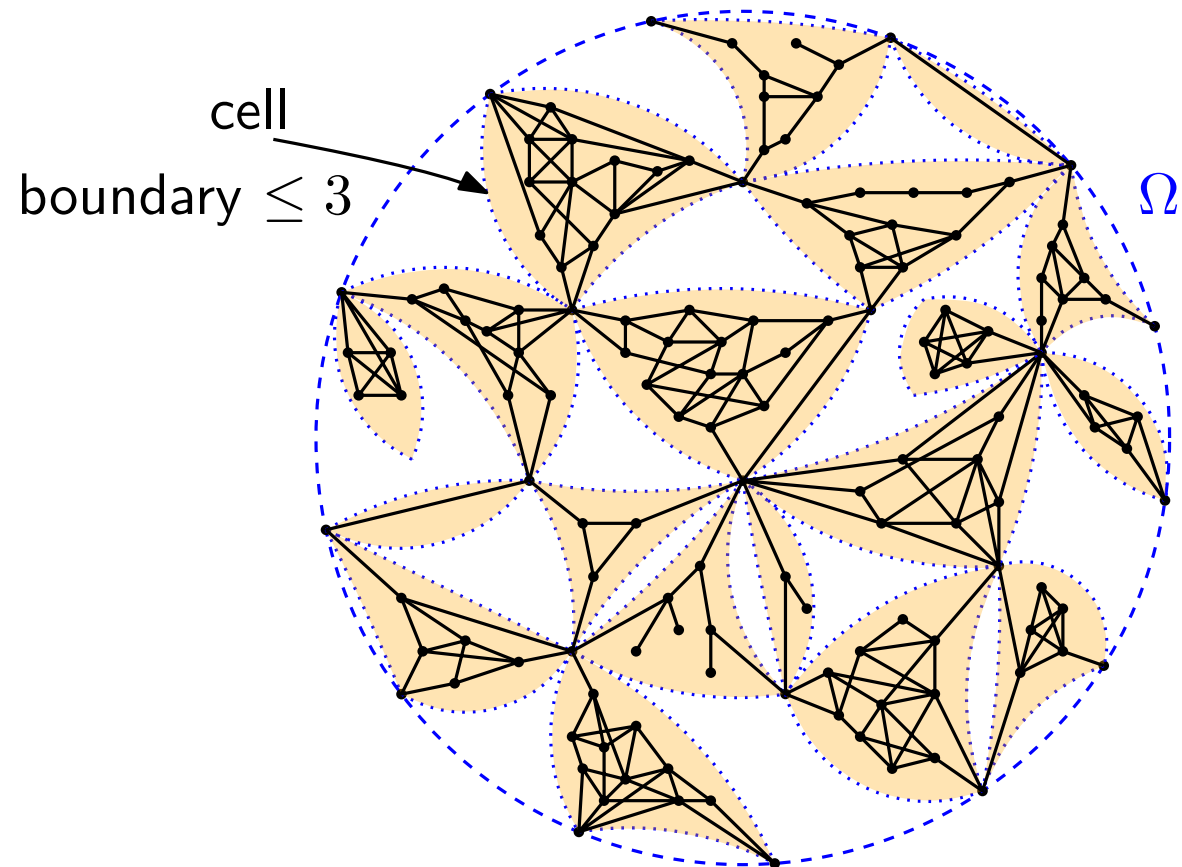
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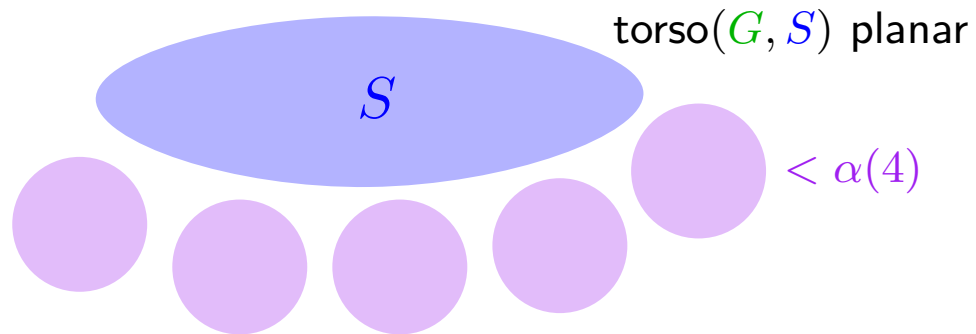
SMALL-LEAVES \mathcal{H} -PLANARITY

Restate the problem

Rendition of (G, Ω)



Sketch of the proof



SMALL-LEAVES \mathcal{H} -PLANARITY

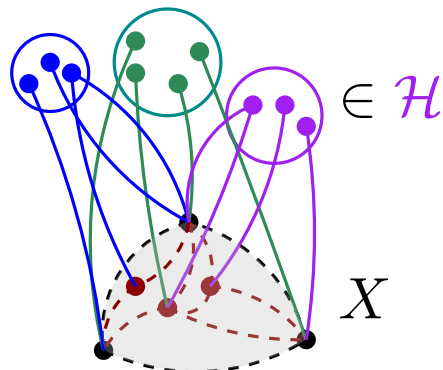
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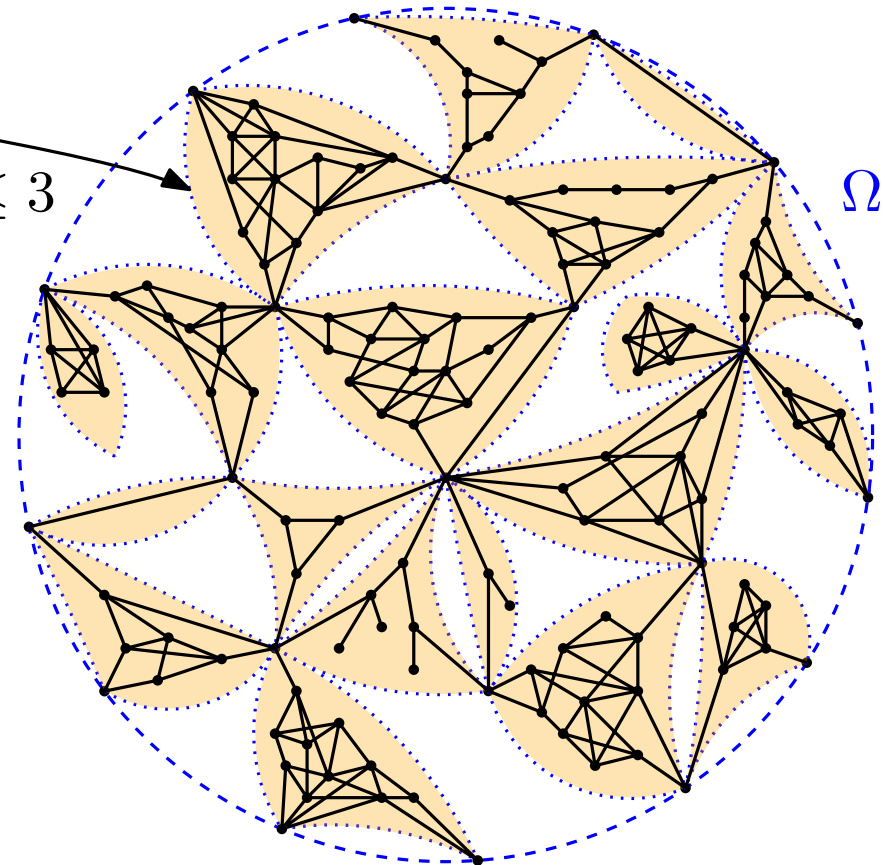
G is a **yes**-instance

\Leftrightarrow

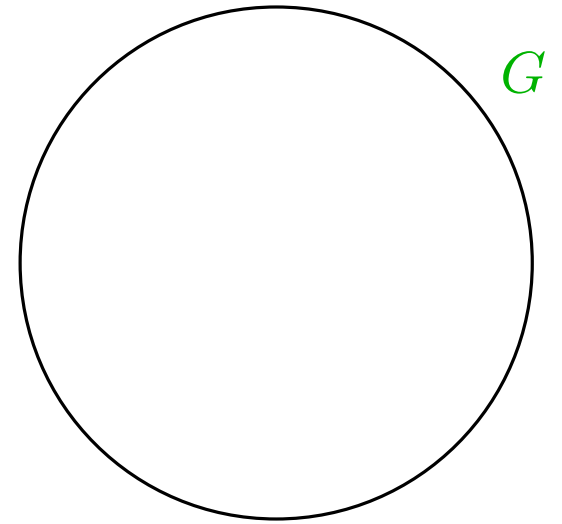
G has a **rendition** whose cells are **\mathcal{H} -compatible**.



cell
boundary ≤ 3

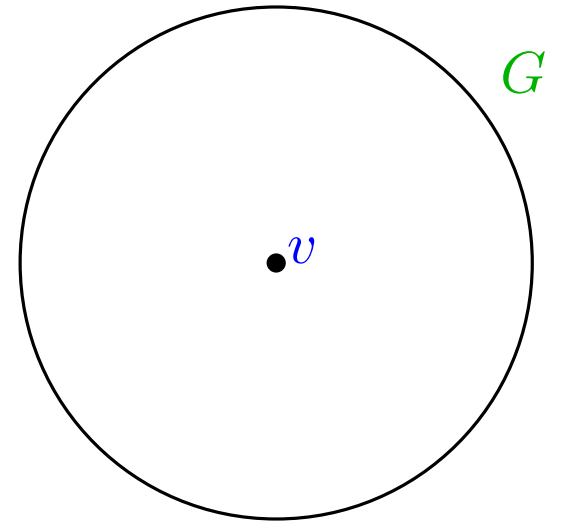


Idea:



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Pick a vertex v .

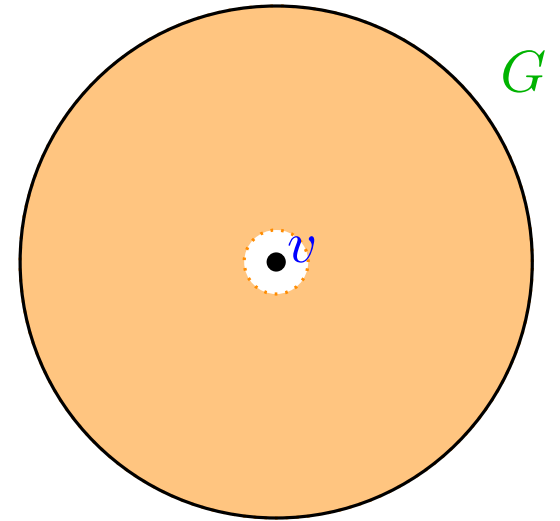


Idea:

Pick a vertex v .

Solve recursively on $G - v$.

Rendition ρ_1 of $G - v$ whose cells are \mathcal{H} -compatible.



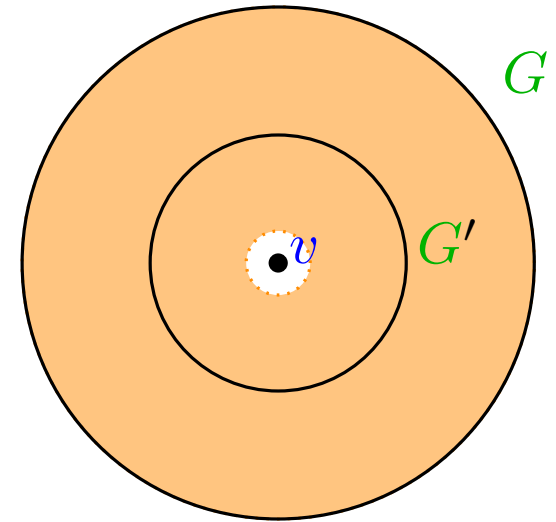
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Take a region G' around v of small **treewidth**.



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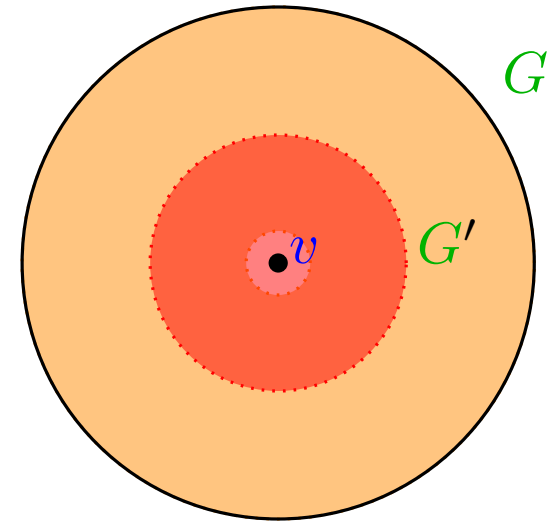
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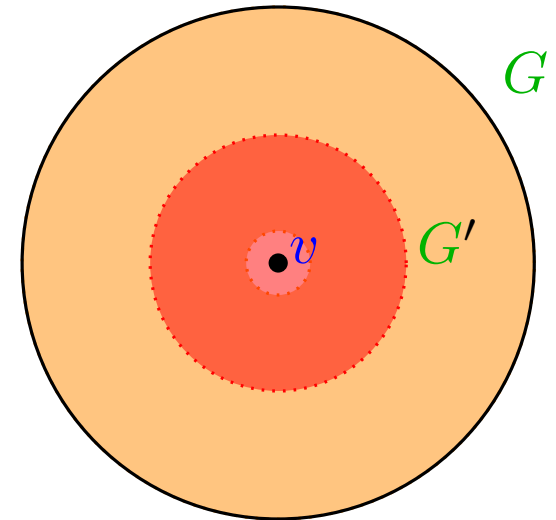
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→ want to combine ρ_1 and ρ_2 into a rendition of G whose cells are \mathcal{H} -compatible.



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Rendition ρ_1 of $G - v$ whose cells are \mathcal{H} -compatible.

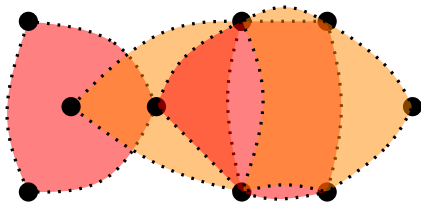
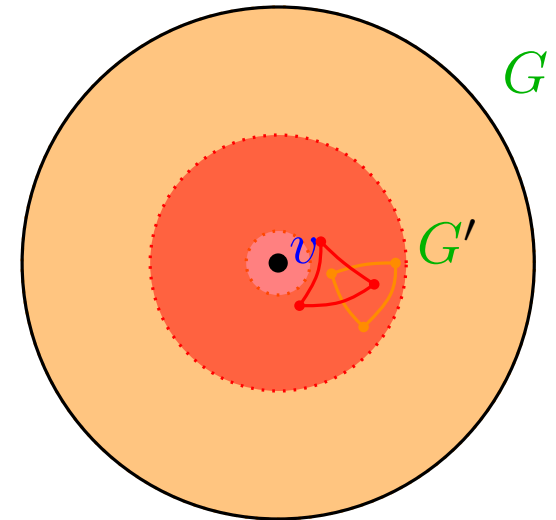
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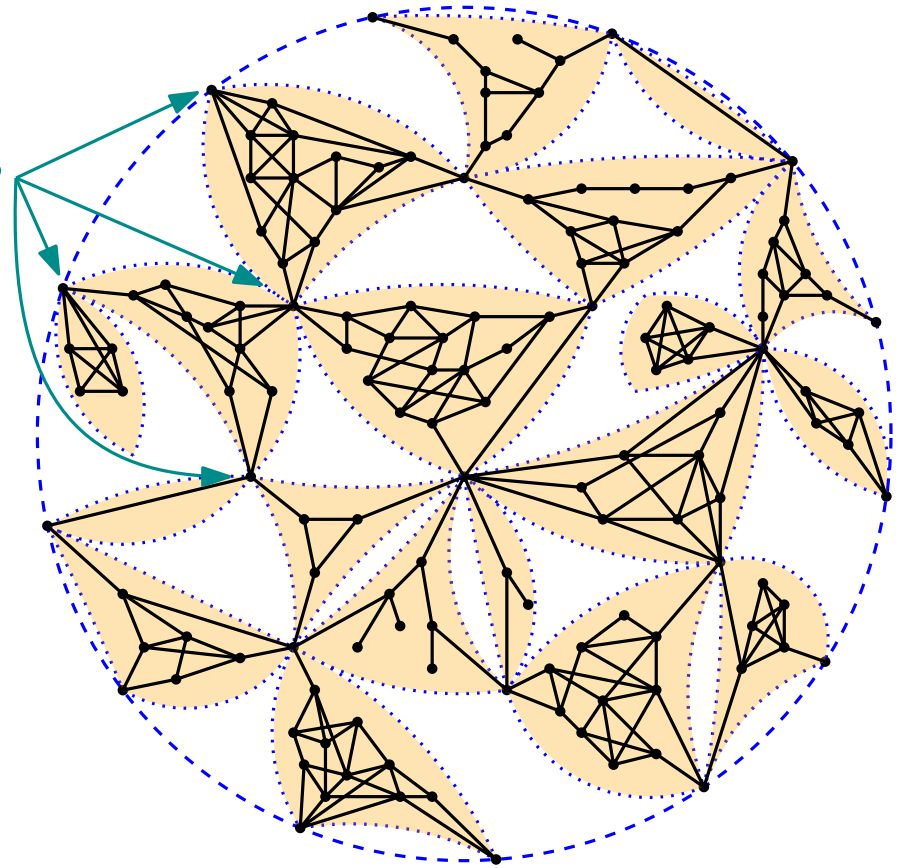
→ want to combine ρ_1 and ρ_2 into a rendition of G whose cells are \mathcal{H} -compatible.

Problem: How to glue correctly?

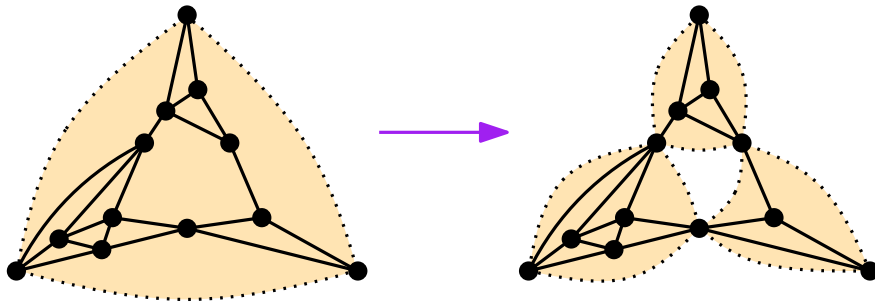


no “canonical rendition” of a graph

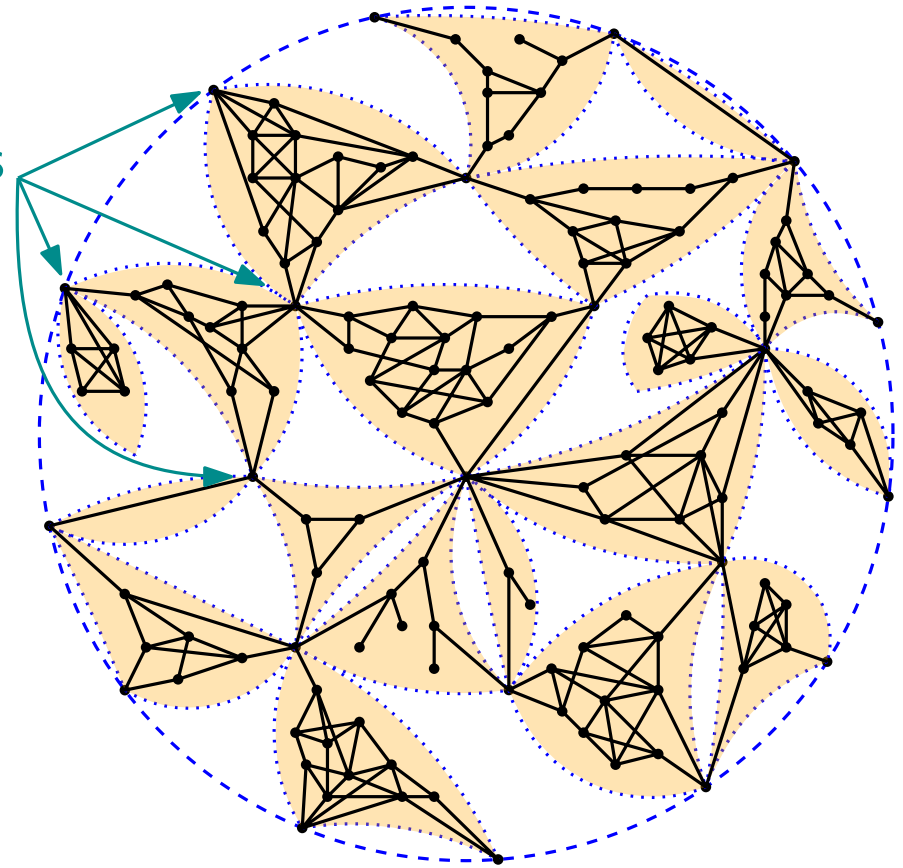
ground vertices



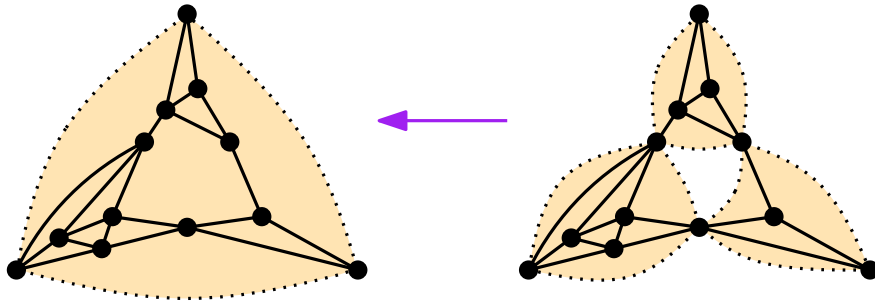
ground-maximal rendition:
cannot add more vertices to the ground



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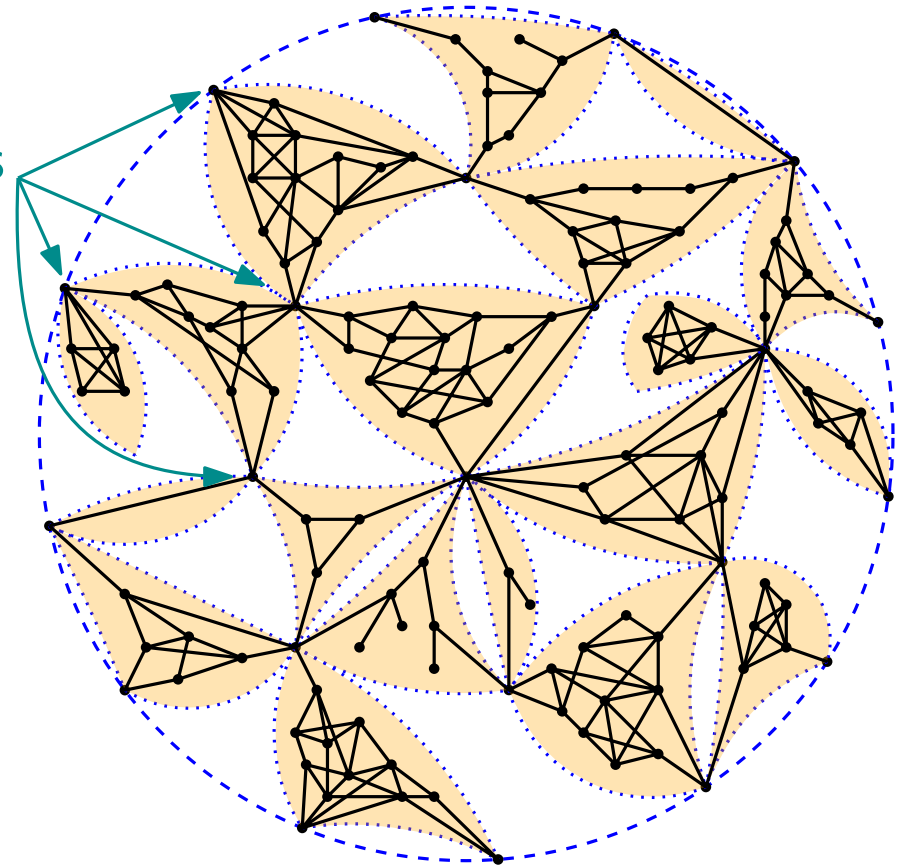


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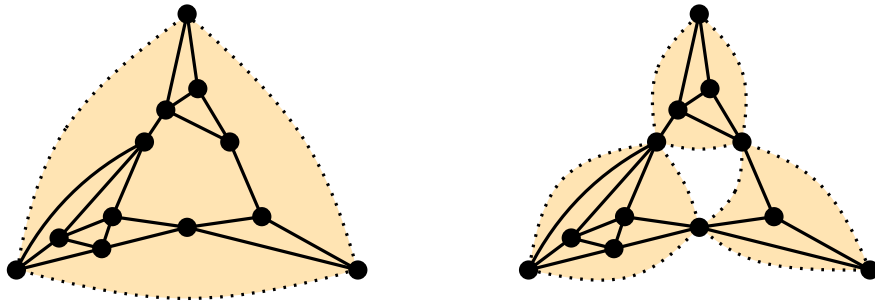


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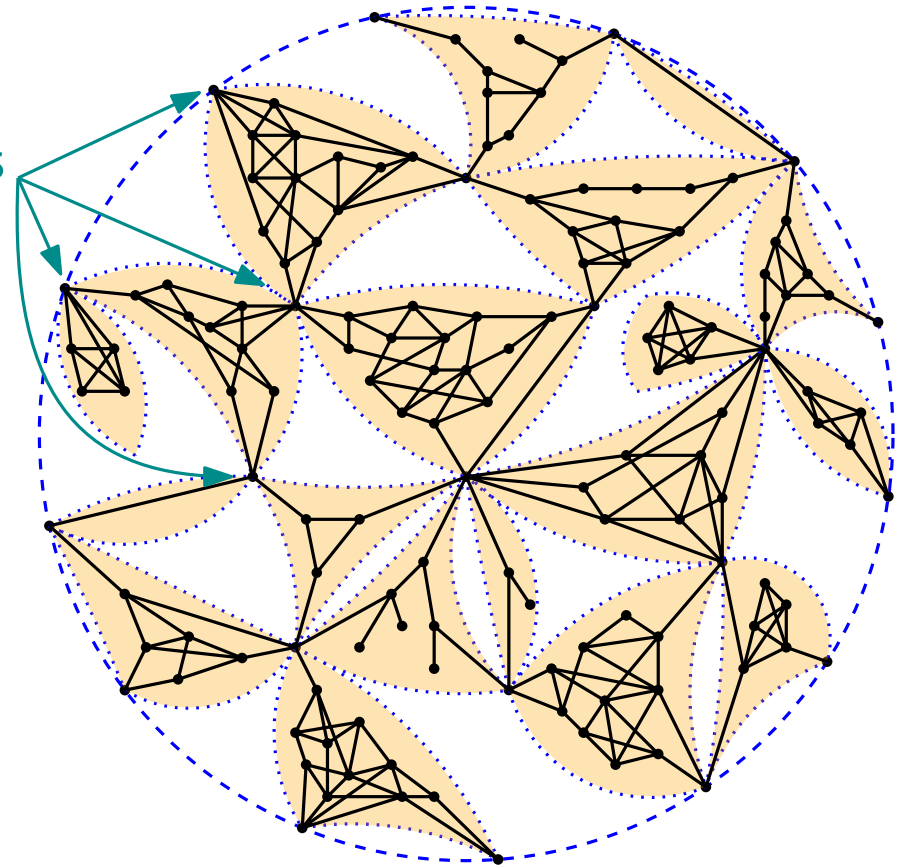
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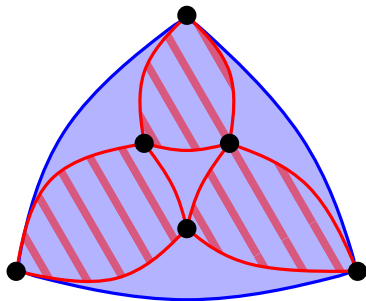


ground vertices



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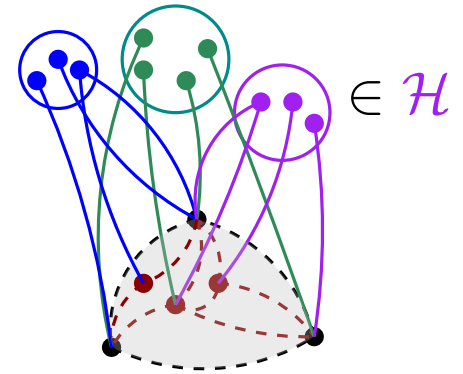
Every cell of **ground-maximal** rendition is contained in a cell of a **ground-minimal** rendition.

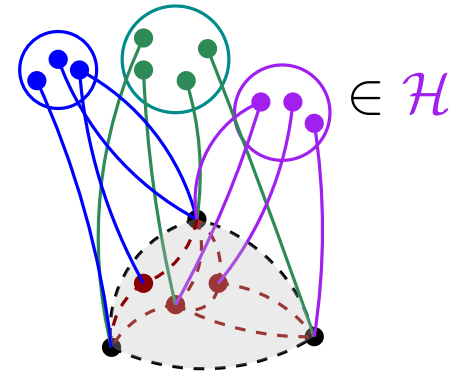


G is a **yes**-instance of SMALL-LEAVES \mathcal{H} -PLANARITY

\Leftrightarrow

G has a **rendition** whose cells are \mathcal{H} -compatible.





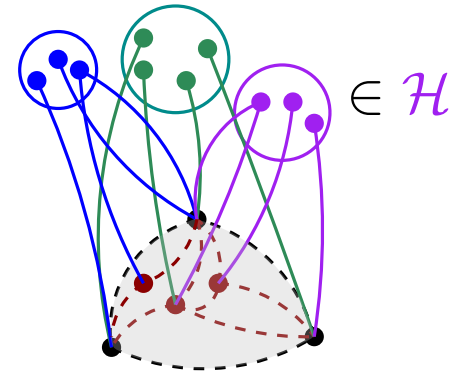
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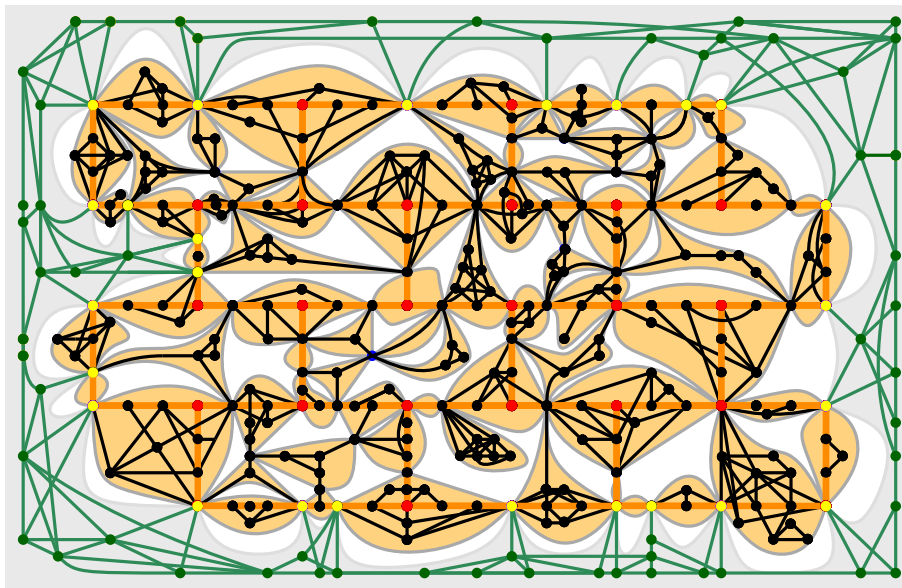
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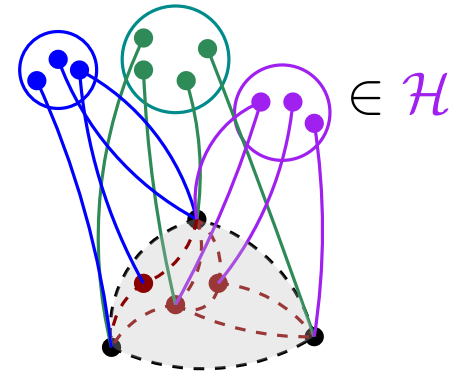
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G has a **ground-maximal** **rendition** whose cells are \mathcal{H} -**compatible**.

flat wall



[figure by Dimitrios M. Thilikos]



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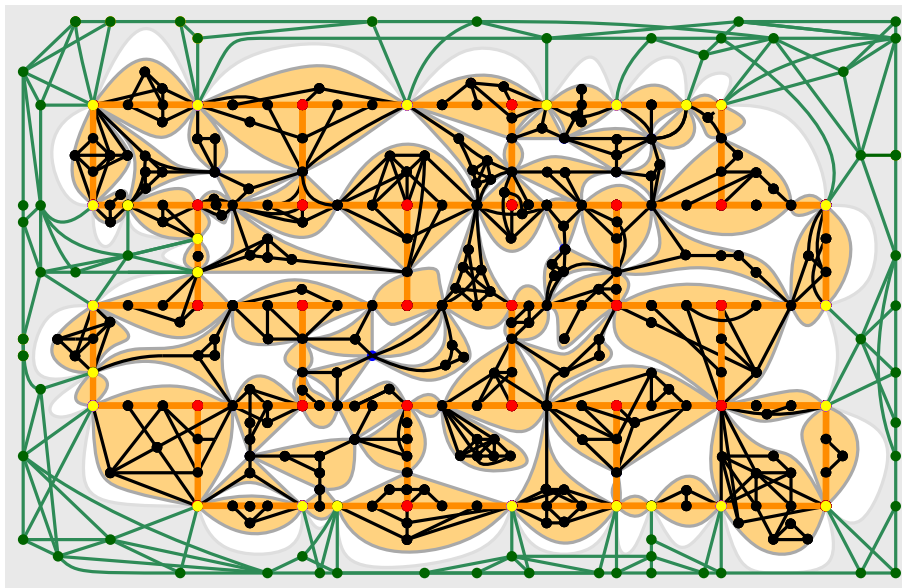
\Leftrightarrow

G has a **rendition** whose cells are \mathcal{H} -**compatible**.

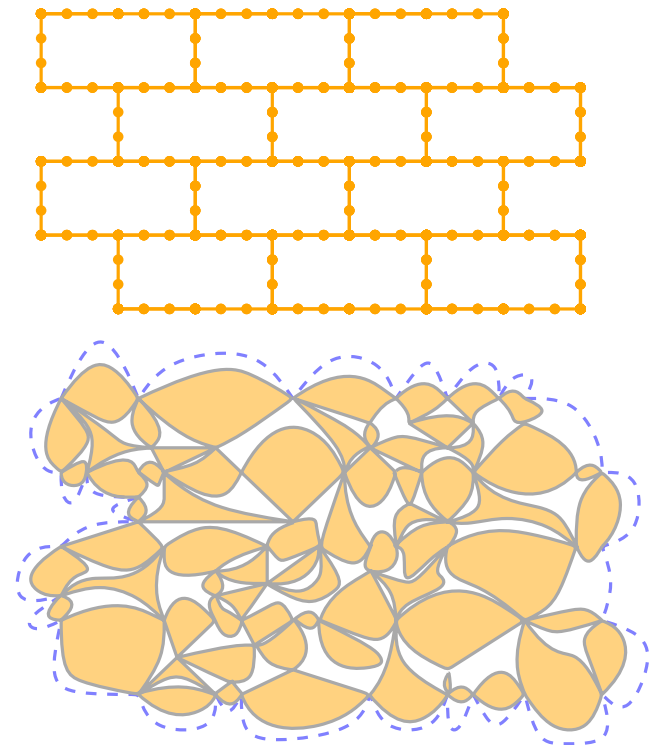
\Leftrightarrow

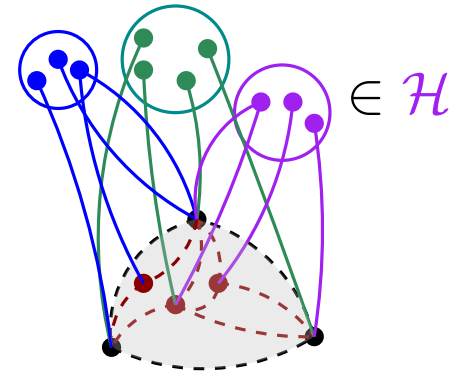
G has a **ground-maximal** **rendition** whose cells are \mathcal{H} -**compatible**.

flat wall = **wall** + **rendition**



[figure by Dimitrios M. Thilikos]





G is a **yes**-instance of SMALL-LEAVES \mathcal{H} -PLANARITY

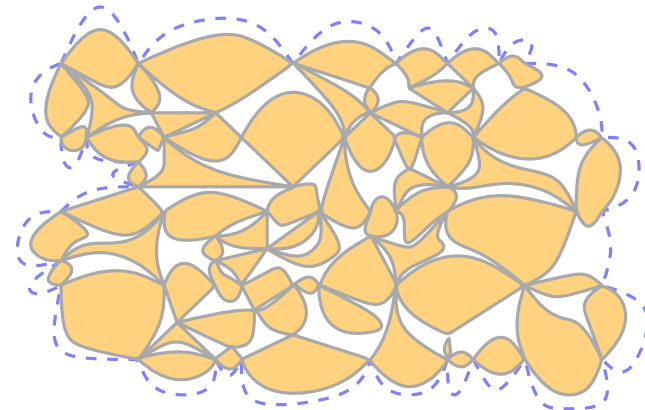
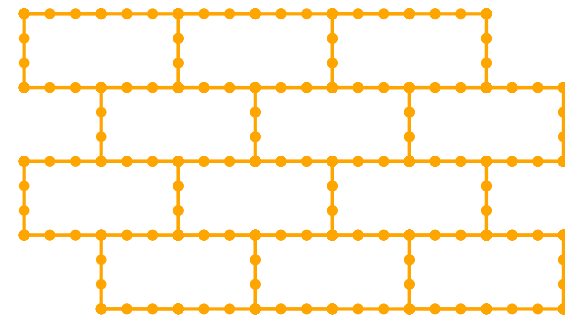
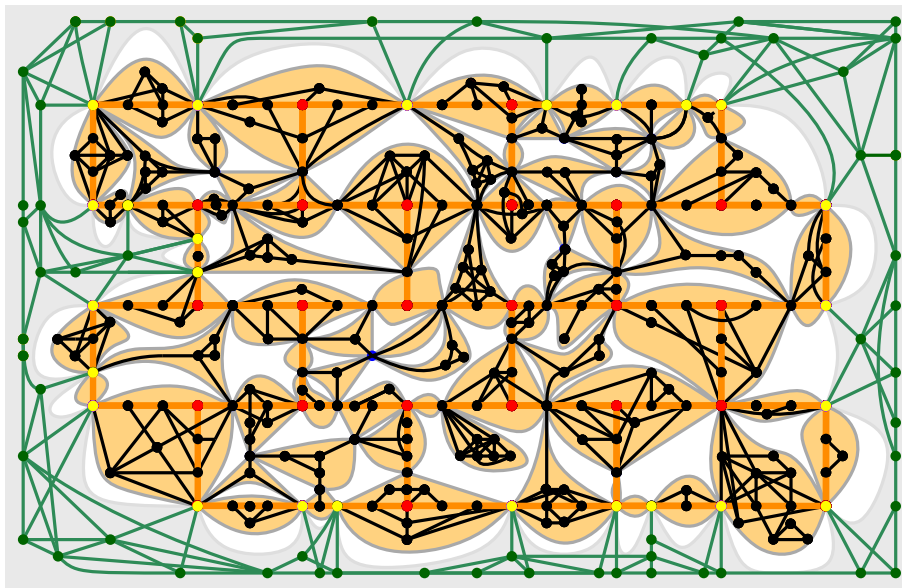
\Leftrightarrow

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\Leftrightarrow

G has a **ground-maximal** **rendition** whose cells are \mathcal{H} -**compatible**.

flat wall = wall + **rendition** ↖ can choose ground-minimal



[figure by Dimitrios M. Thilikos]

Pick a vertex v

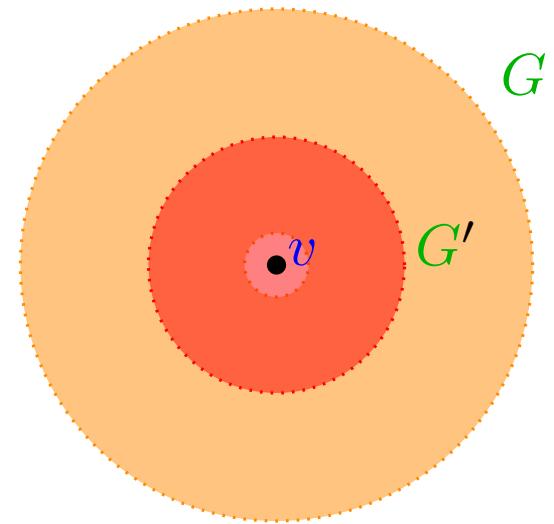
Solve recursively on $G - v$.

Ground-maximal rendition ρ_1 of $G - v$ whose cells are \mathcal{H} -compatible.

Take a region G' around v of small treewidth.

Solve on G' . [Courcelle, '90]

Ground-maximal rendition ρ_2 of G' whose cells are \mathcal{H} -compatible.



Find a flat wall W in G whose interior G' has bounded treewidth (or conclude).

Ground-minimal rendition ρ' in G' .

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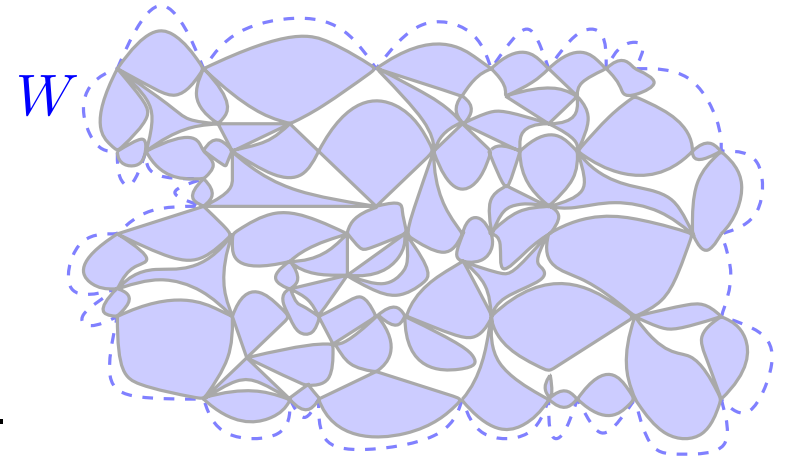
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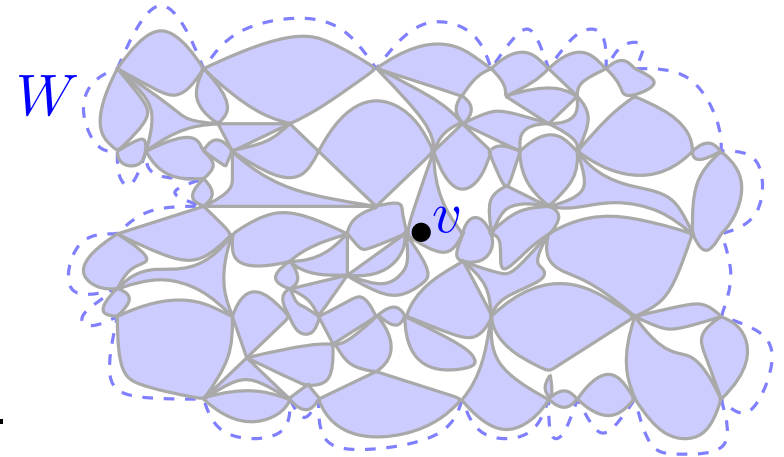
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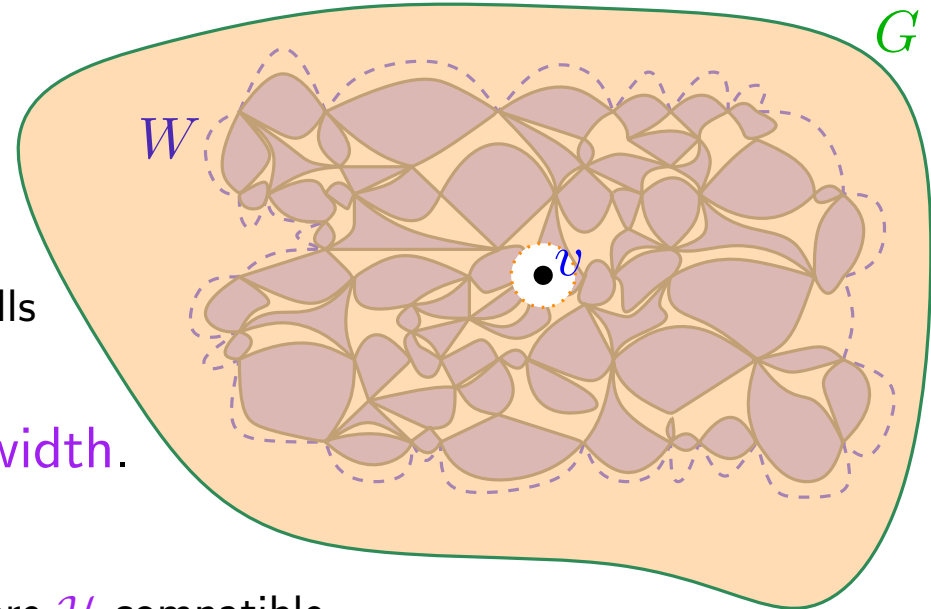
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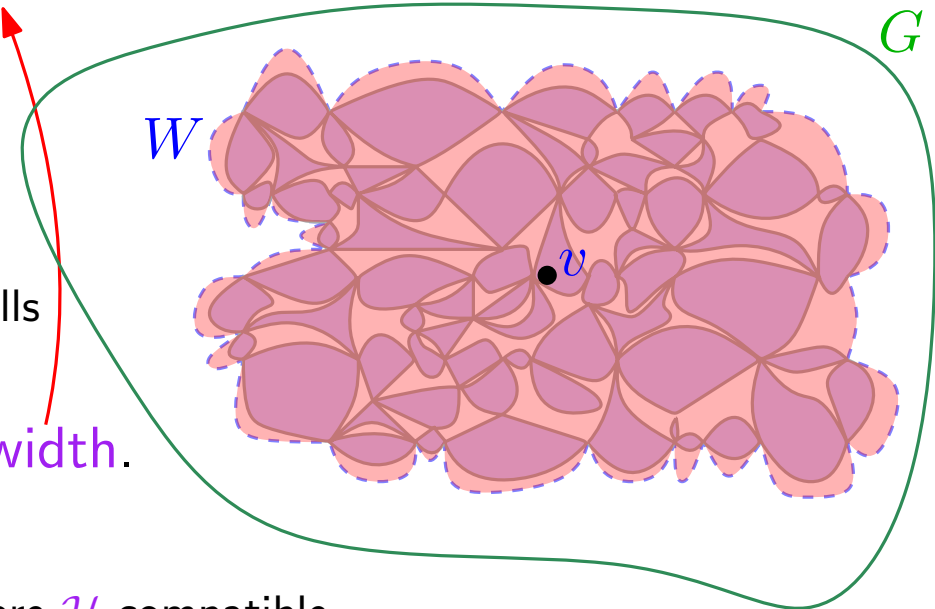
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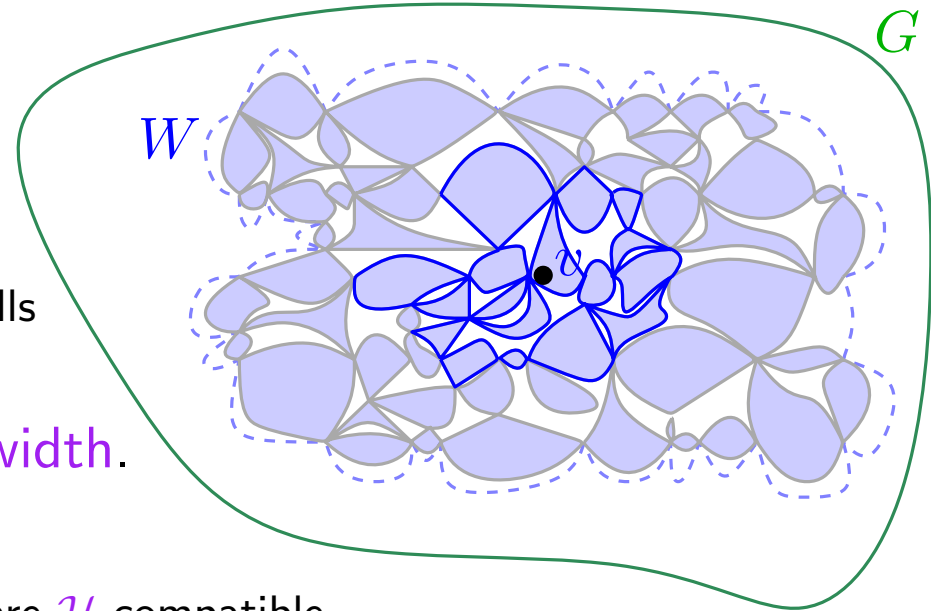
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Pick a vertex v in the center of W .

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Ground-maximal rendition ρ_1 of $G - v$ whose cells are \mathcal{H} -compatible.

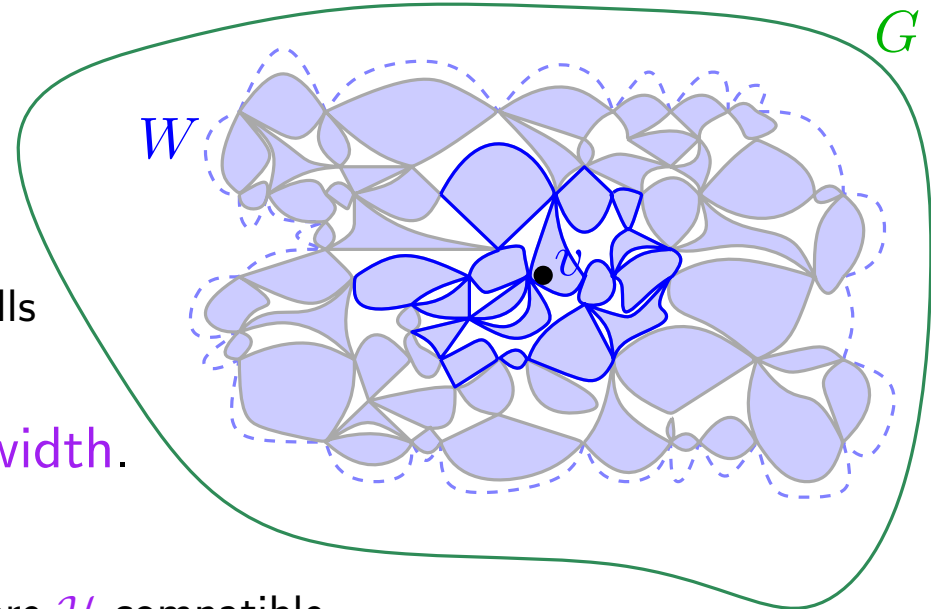
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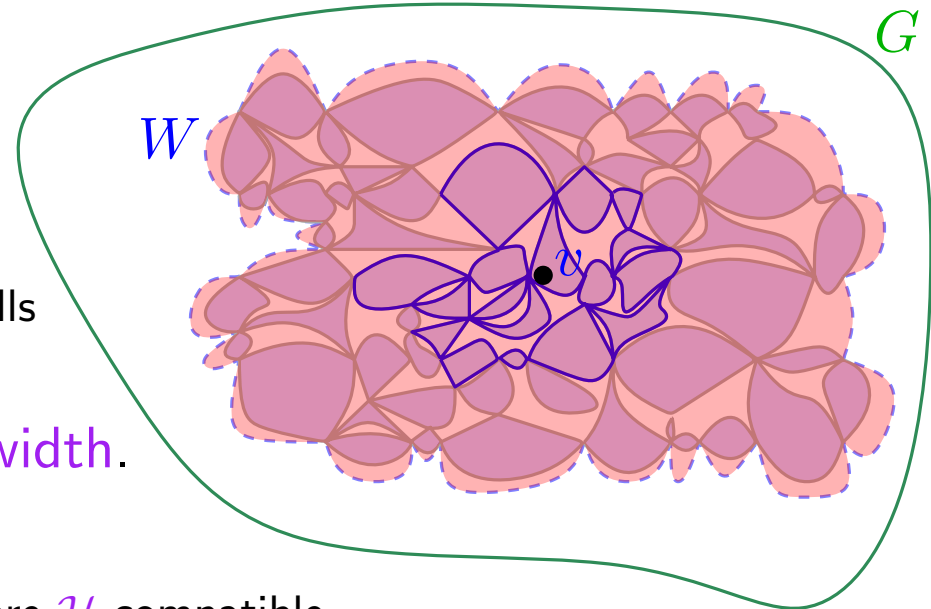
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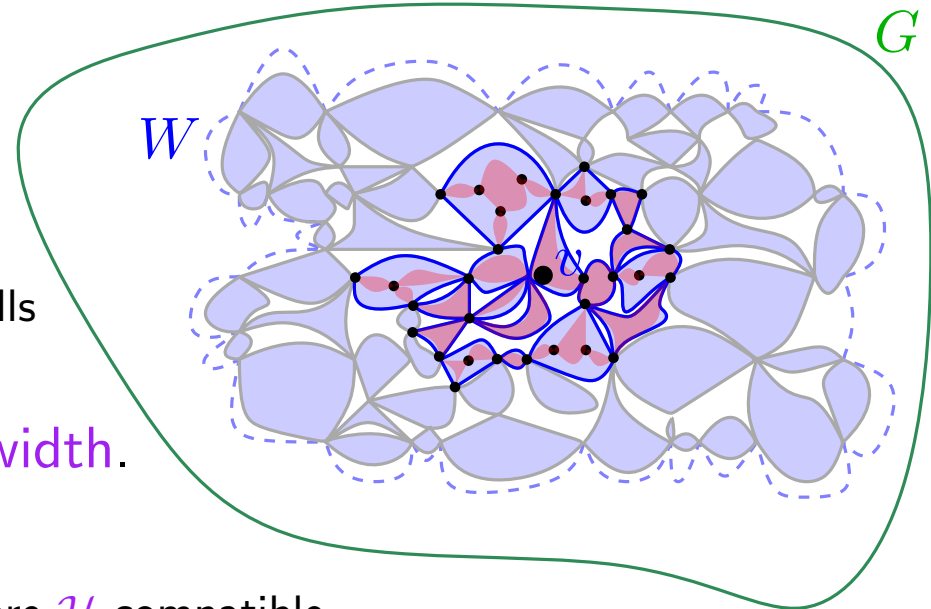
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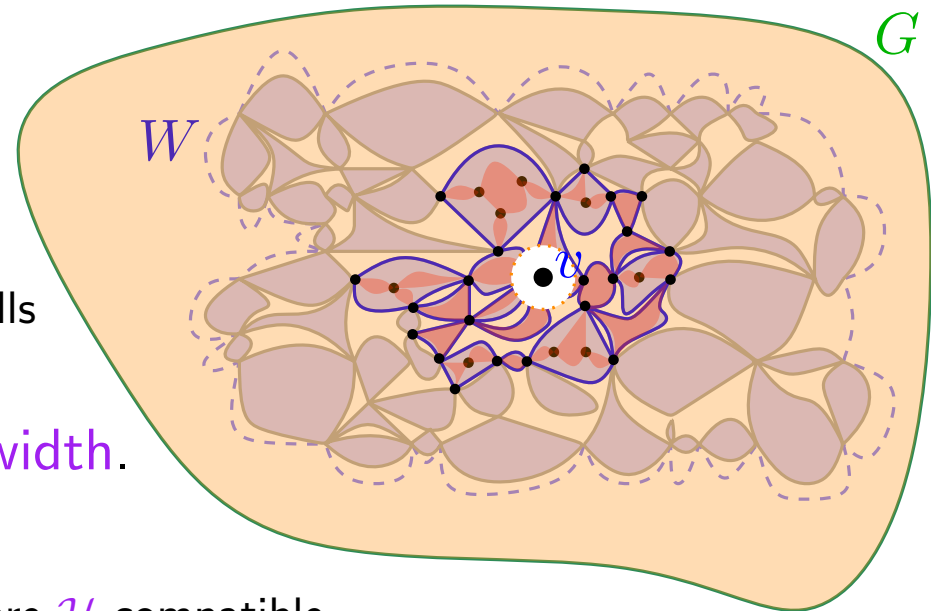
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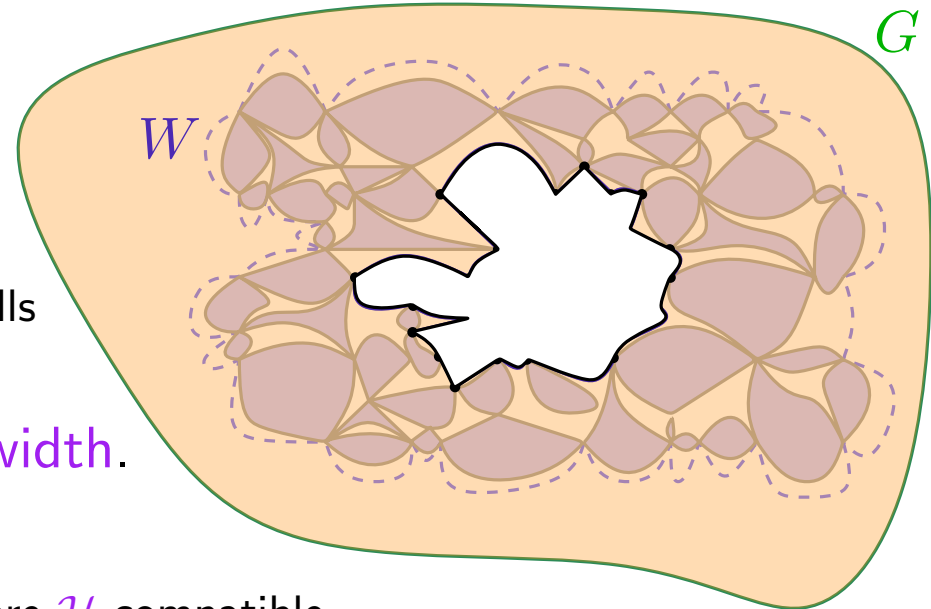
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Find a flat wall W in G whose interior G' has bounded treewidth (or conclude).

Ground-minimal rendition ρ' in G' .

Pick a vertex v in the center of W .

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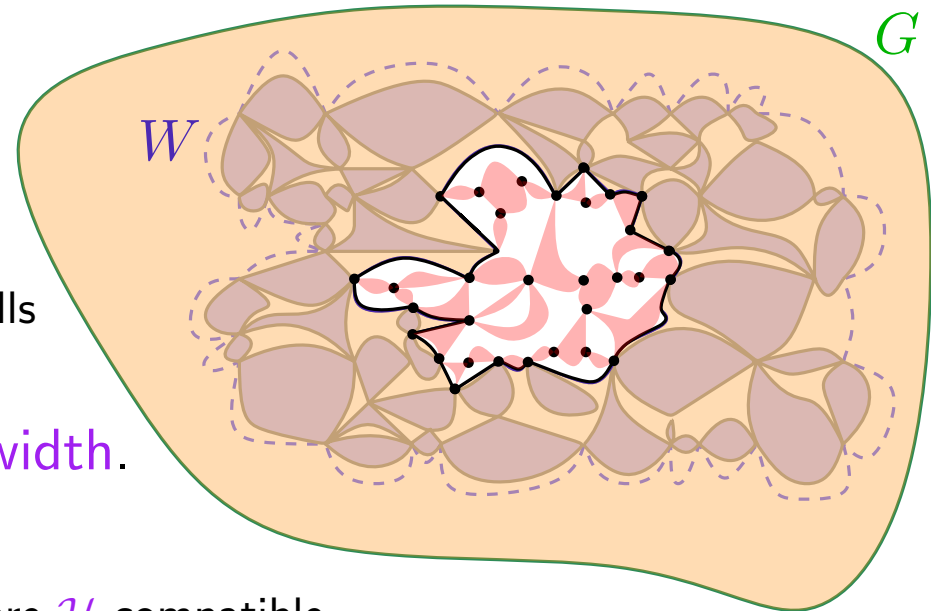
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\Rightarrow rendition ρ of G whose cells are \mathcal{H} -compatible.



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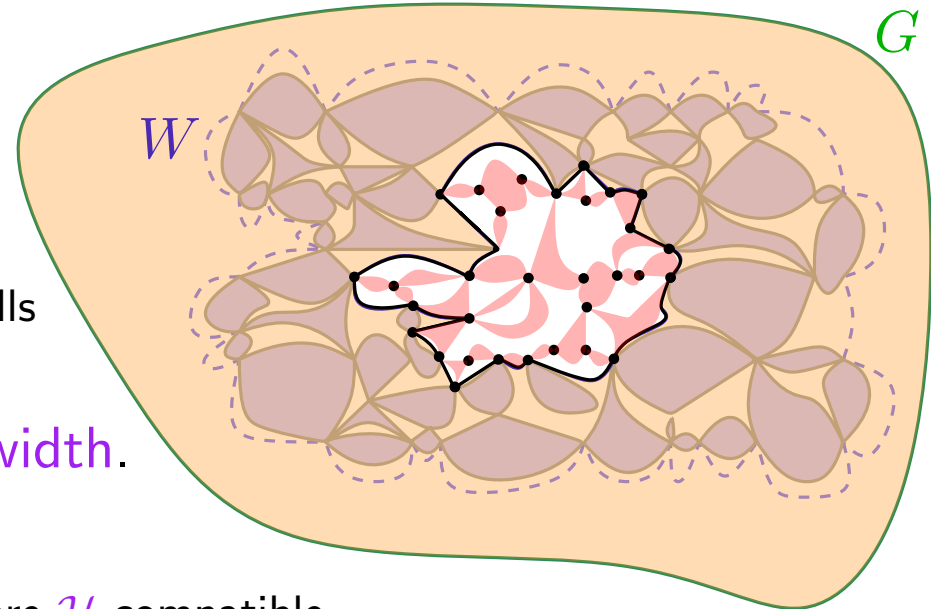
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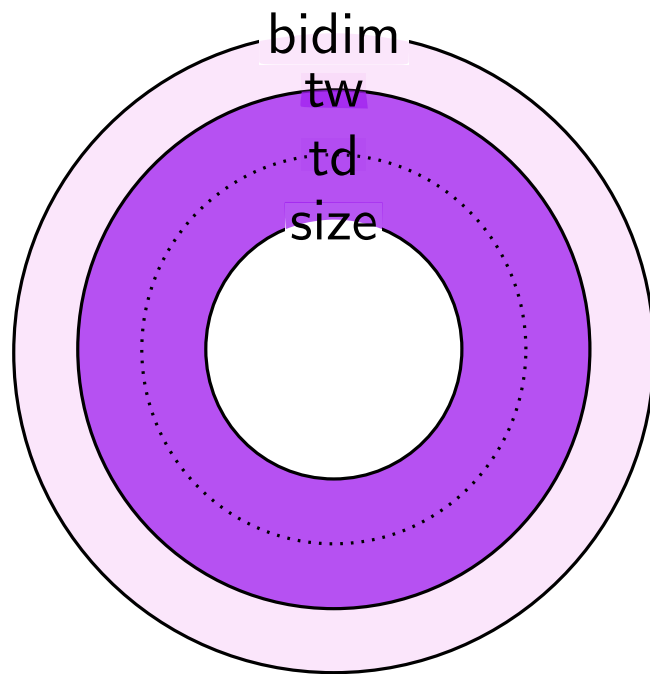
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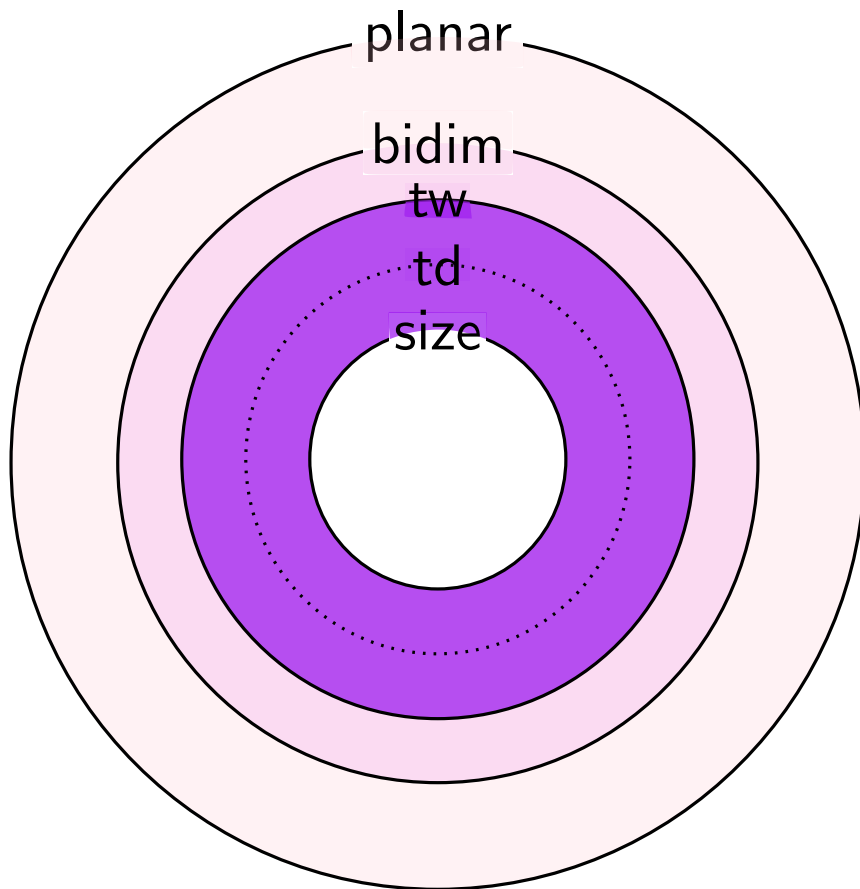
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Going even further



Going even further



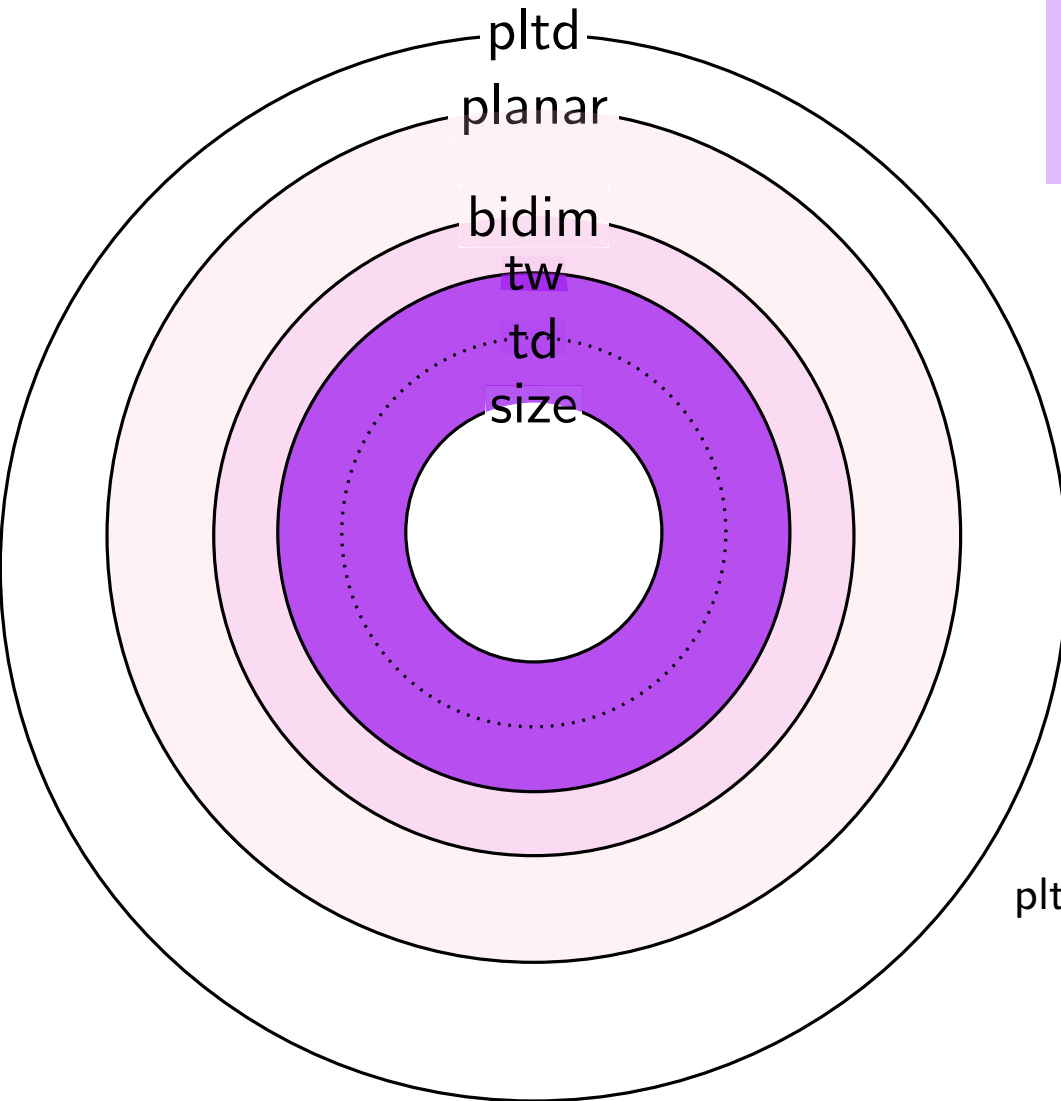
Going even further

Graph class \mathcal{H}

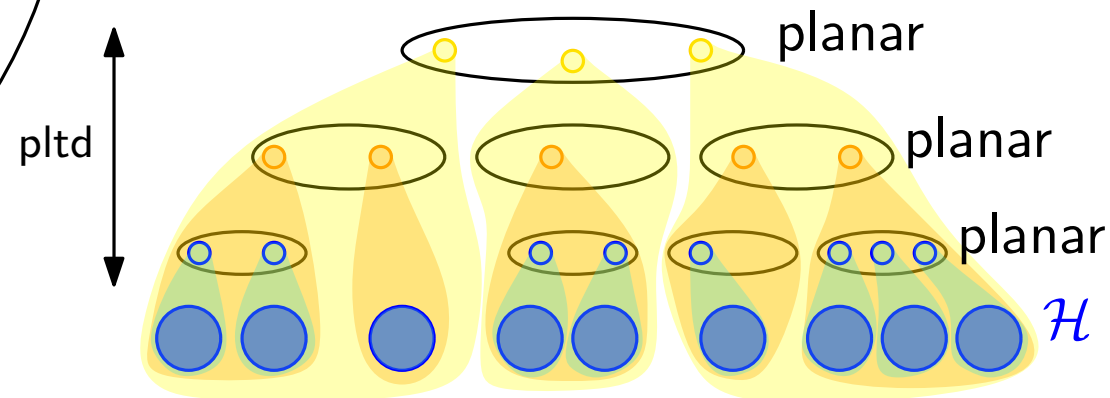
- hereditary,
- closed under disjoint union,
- CMSO-definable, and
- VERTEX DELETION TO \mathcal{H} in time $\mathcal{O}_k(n^c)$.

[Fomin, Golovach, Morelle, Thilikos]

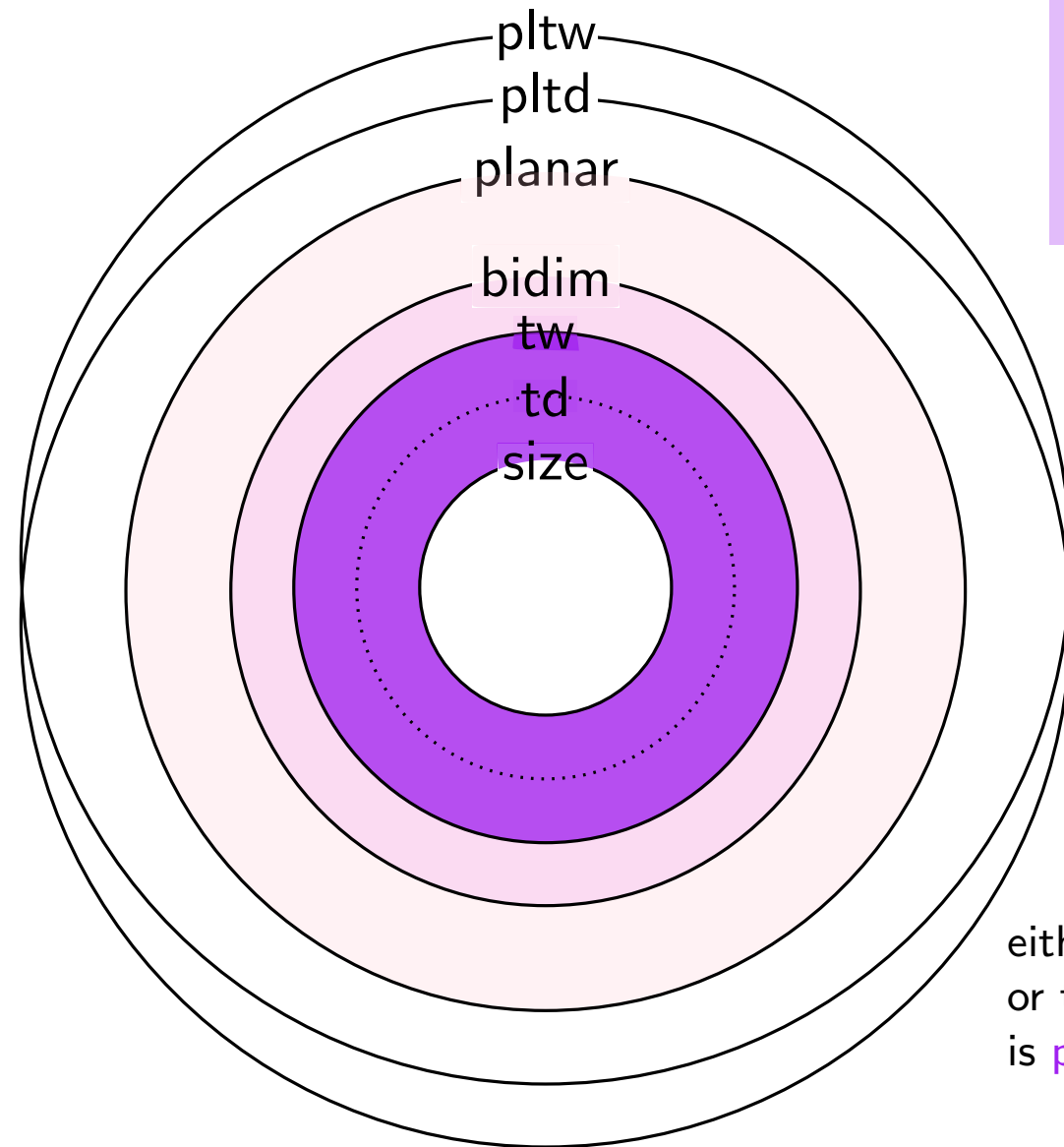
One can decide if \mathcal{H} -pltd(G) $\leq k$ in time $\mathcal{O}_k(n^4 + n^c \log n)$.



Planar treedepth pltd



Going even further



Graph class \mathcal{H}

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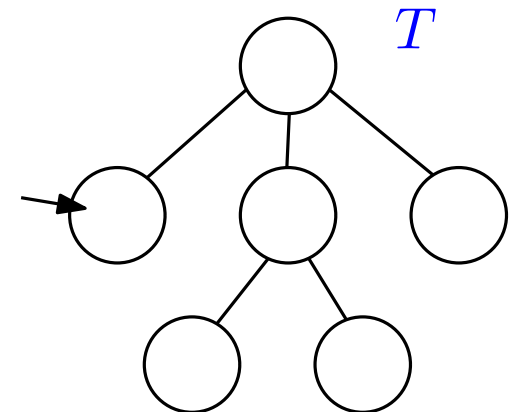
[Fomin, Golovach, Morelle, Thilikos]

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Planar treewidth pltw

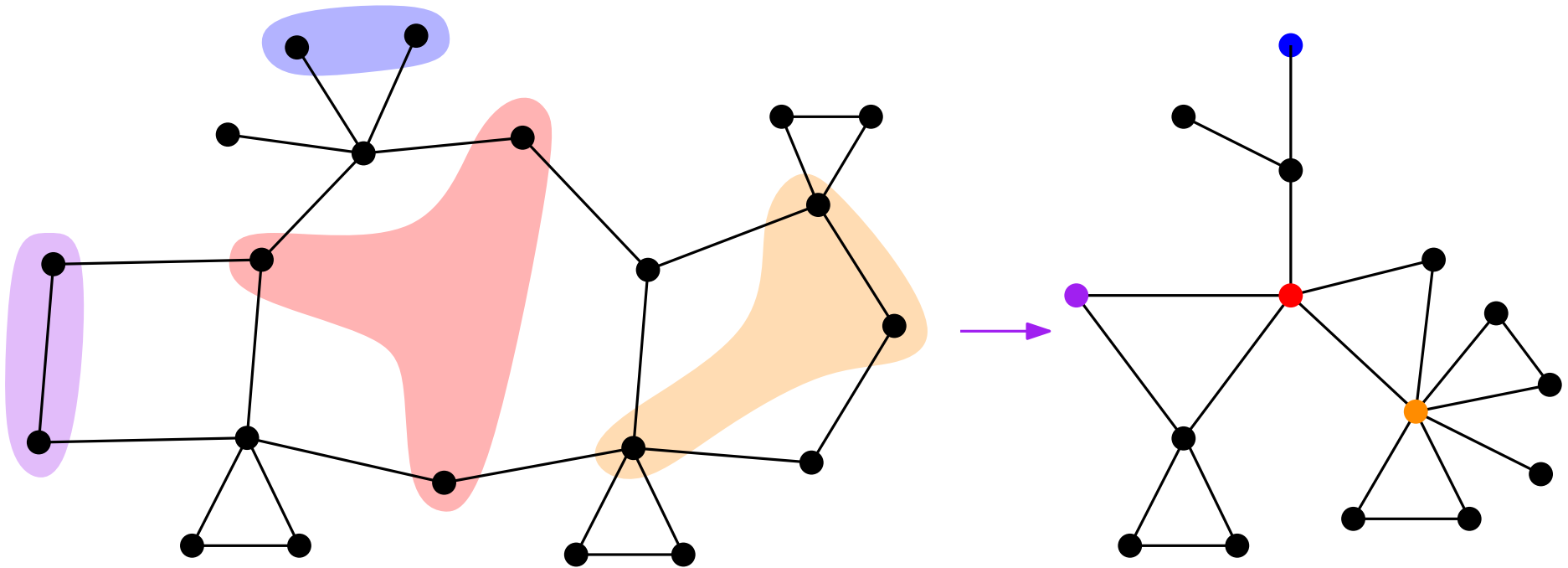
Tree decomposition $(T, \{B_t\}_t)$ of G

either $|B_t| \leq k + 1$
or the torso of B_t
is planar



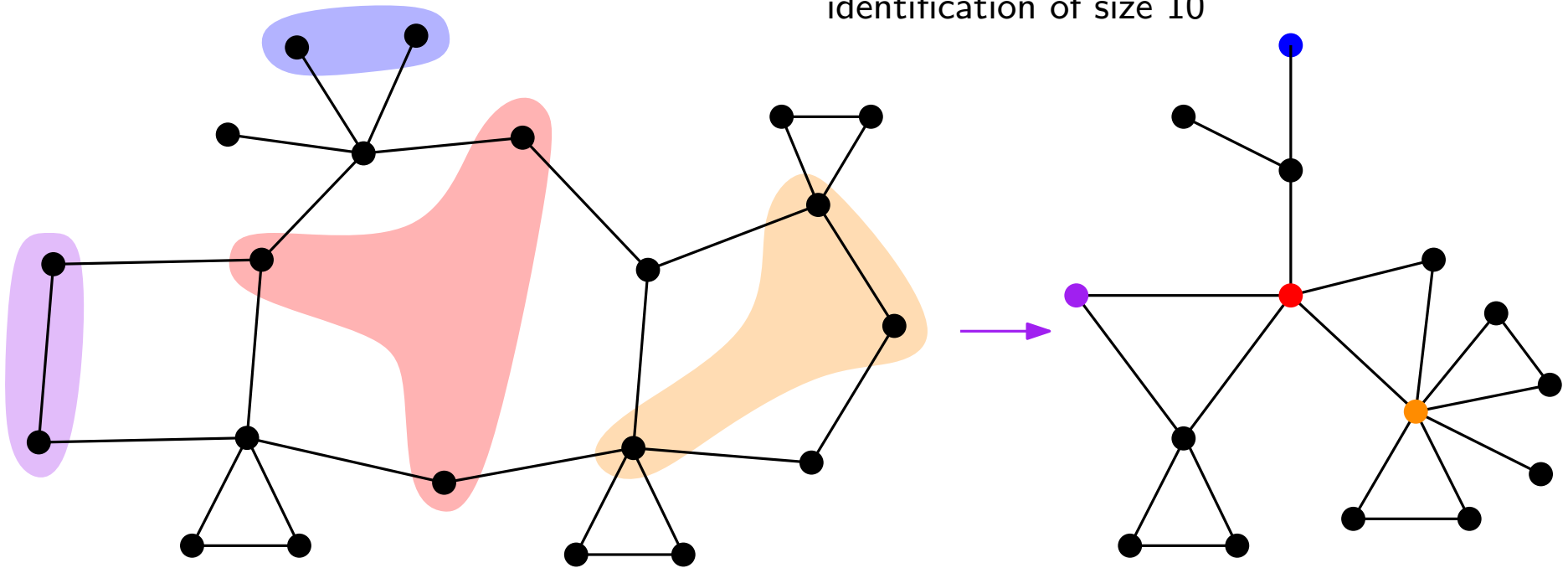
4. A new modification: vertex identification

Vertex identification



Vertex identification

identification of size 10



Size of the identification = number of vertices involved in the identification

Why identifications?

Structure theorems meet graph modification problems

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Structure theorems meet graph modification problems

[Robertson, Seymour, '03]+[Thilikos, Wiederrecht, '23]

If G excludes a graph H as a **minor**, then:

⋮

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Why identifications?

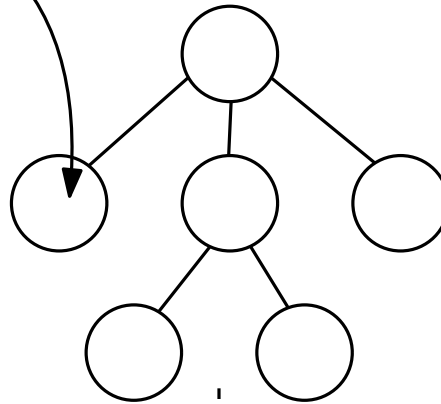
Structure theorems meet graph modification problems

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If G excludes a graph H as a **minor**, then:

G has a tree decomposition s.t.
the **torso** of each bag

$$h = |V(H)|$$



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Structure theorems meet graph modification problems

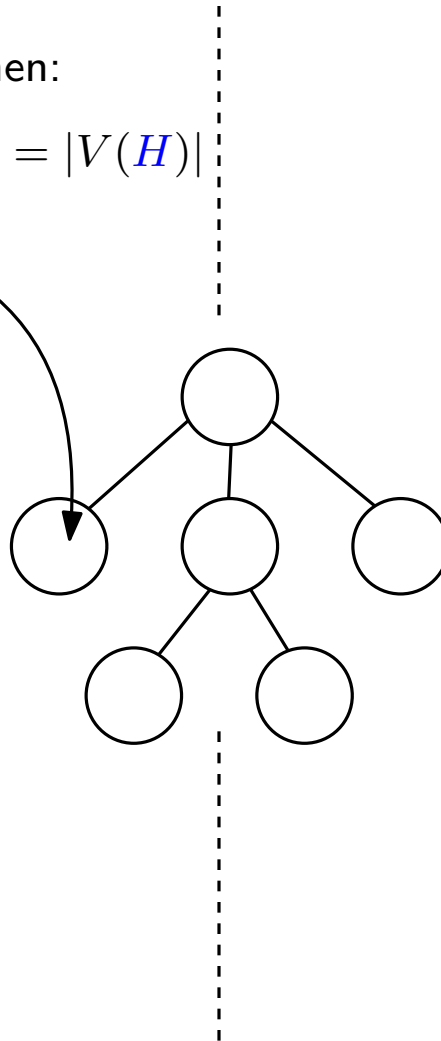
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If G excludes a graph H as a **minor**, then:

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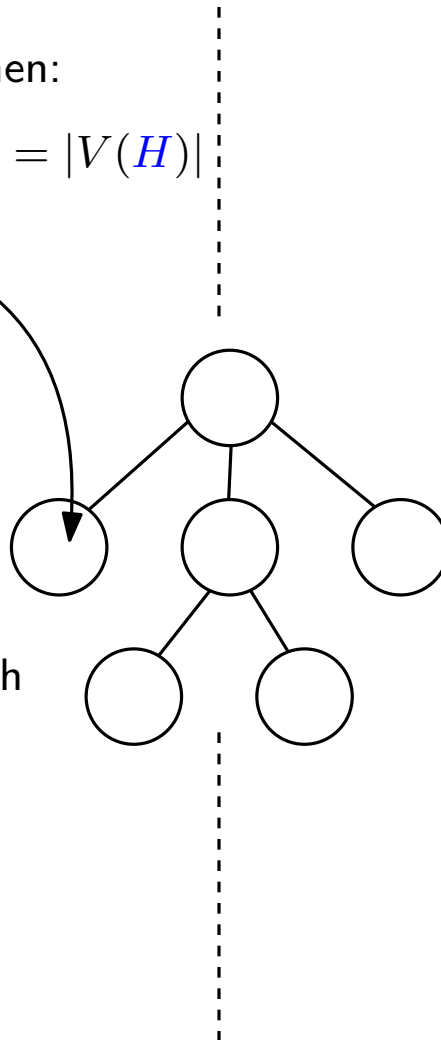
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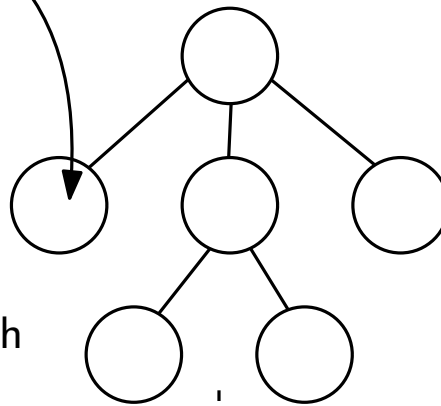
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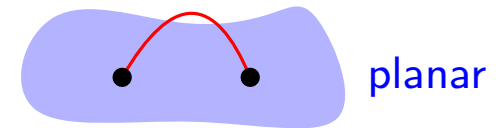
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[Morelle, Protopapas, Thilikos, Wiederrecht]

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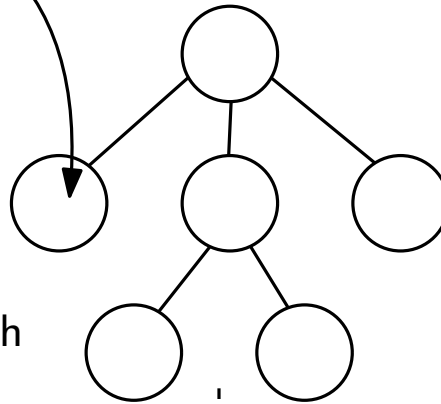
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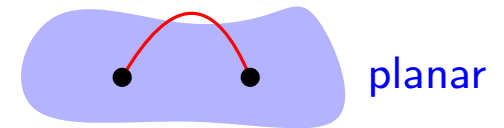
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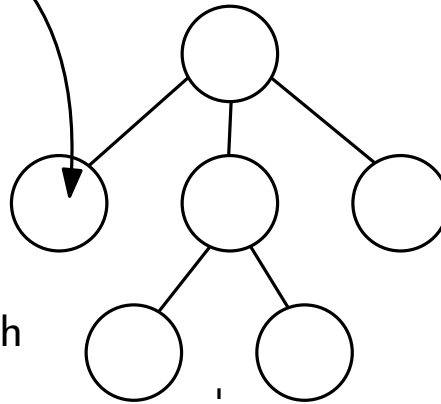
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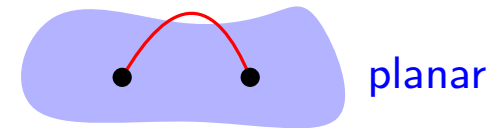
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G has a tree decomposition s.t.
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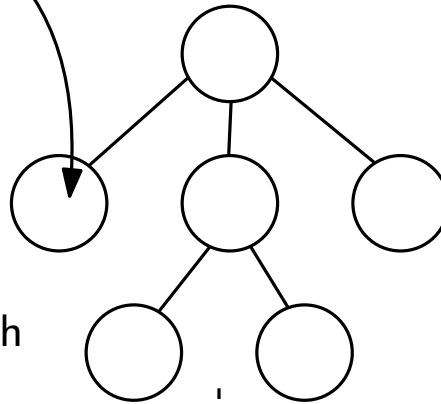
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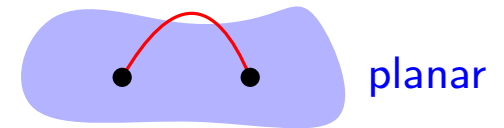
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Results on identifications

[Morelle, Sau, Thilikos]

VERTEX IDENTIFICATION TO FORESTS is solvable in time $\mathcal{O}(1.2738^k + k\sqrt{\log k} \cdot n)$.

[Morelle, Sau, Thilikos]

If \mathcal{H} is minor-closed, then \mathcal{L} -REPLACEMENT TO \mathcal{H} is solvable in time $2^{\text{poly}_{\mathcal{H}}(k)} \cdot n^2$ for \mathcal{L} hereditary.

→ includes VERTEX IDENTIFICATION TO \mathcal{H}

Further research

Direction 1: Efficiency

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Can we improve the running time of the different algorithms?

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In particular, VERTEX DELETION TO \mathcal{H}

$$2^{k^{\mathcal{O}(\mathcal{H})}} \cdot n^2$$

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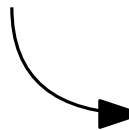
In particular, VERTEX DELETION TO \mathcal{H}

$$2^{k^{\mathcal{O}(\mathcal{H})}} \cdot n^2 \longrightarrow n^{1+o(1)}? \quad [\text{Korhonen, Pilipczuk, Stamoulis, '24}]$$

Direction 1: Efficiency

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In particular, VERTEX DELETION TO \mathcal{H}

$$2^{\mathbf{k}^{\mathcal{H}(1)}} \cdot \mathbf{n}^2 \longrightarrow \mathbf{n}^{1+o(1)}? \quad [\text{Korhonen, Pilipczuk, Stamoulis, '24}]$$

$$2^{\mathcal{O}_{\mathcal{H}}(\mathbf{k}^c)}?$$

Direction 2: Generalization

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Graph class \mathcal{H} hereditary, closed under disjoint union, and CMSO-definable.
Parameter p minor-monotone.

→ for each minor H of G , $p(H) \leq p(G)$

Conjecture: If VERTEX DELETION TO \mathcal{H} is FPT, then checking $\mathcal{H}\text{-}p(G) \leq k$ is also FPT.

Direction 2: Generalization

Graph class \mathcal{H} hereditary, closed under disjoint union, and CMSO-definable.
Parameter p minor-monotone.

→ for each minor H of G , $p(H) \leq p(G)$

Conjecture: If VERTEX DELETION TO \mathcal{H} is FPT, then checking $\mathcal{H}\text{-}p(G) \leq k$ is also FPT.

Proved for $p \in \{\text{td}, \text{tw}\}$ → likely to hold for any p with $\text{tw} \leq p \leq \text{size}$.

[Agrawal, Kanesh, Lokshtanov, Panolan, Ramanujan, Saurabh, Zehavi, '22]

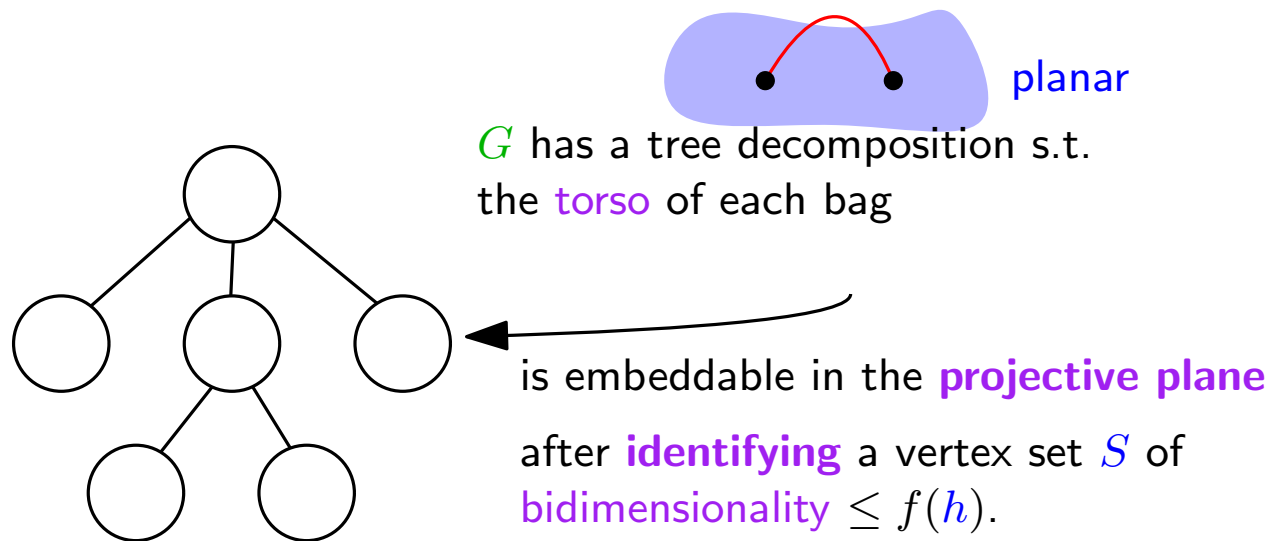
and $p \in \{\text{pltd}, \text{pltw}\}$ → extension for any p ?

[Fomin, Golovach, Morelle, Thilikos]

Direction 3: Structure theorems

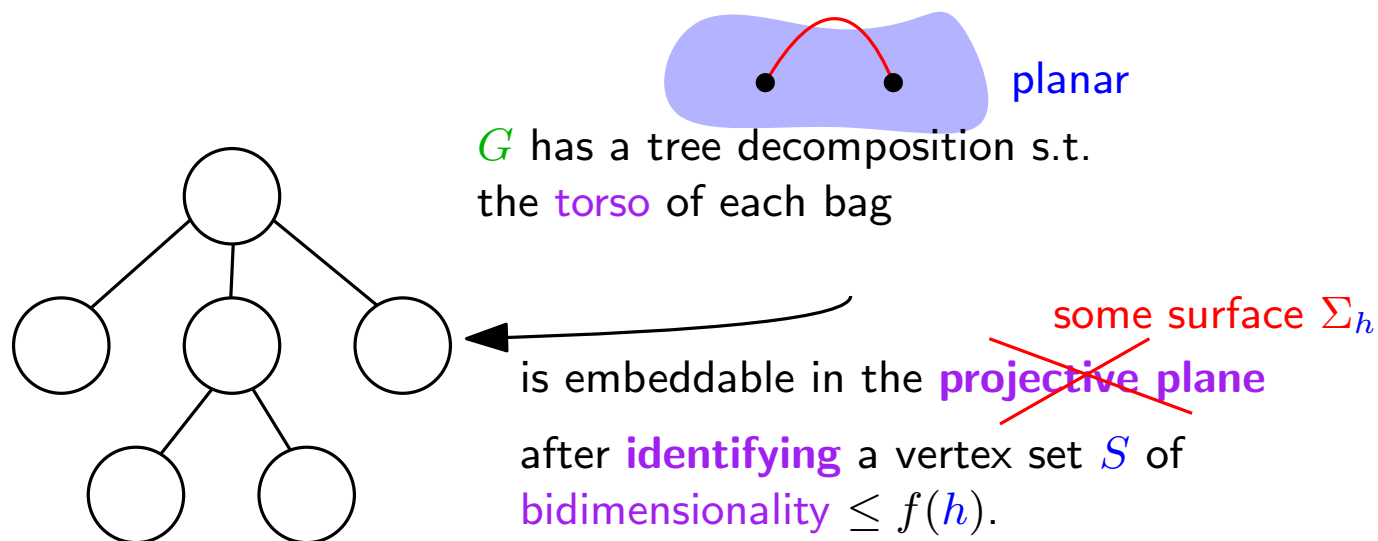
Direction 3: Structure theorems

If G excludes an **edge-apex** graph H as a **minor**,
then:



Direction 3: Structure theorems

If G excludes an ~~edge-apex~~[?] graph H as a minor, then:



Thank you!

- **Faster parameterized algorithms for modification problems to minor-closed classes**, with Ignasi Sau, Giannos Stamoulis, and Dimitrios M. Thilikos. [ICALP 2023](#), [TheoretiCS 2024](#).
- **Dynamic programming on bipartite tree decompositions**, with Lars Jaffke, Ignasi Sau, and Dimitrios M. Thilikos. [IPEC 2023](#), [submitted to a journal](#).
- **PACE Solver Description: Touiwidth**, with Gaétan Berthe, Yoann Coudert–Osmont, Alexander Dobler, Amadeus Reinald, and Mathis Rocton. [IPEC 2023](#).
- **A note on locating sets in twin-free graphs**, with Nicolas Bousquet, Quentin Chuet, Victor Falgas-Ravry, and Amaury Jacques. [Discrete Mathematics 2025](#).
- **On the parameterized complexity of computing good edge-labelings**, with Davi de Andrade, Júlio Araújo, Ignasi Sau, and Ana Silva. [Submitted to a journal](#).
- **Vertex identification to a forest**, with Ignasi Sau and Dimitrios M. Thilikos. [Discrete Mathematics 2026](#).
- **Graph modification of bounded size to minor-closed classes as fast as vertex deletion**, with Ignasi Sau and Dimitrios M. Thilikos. [ESA 2025](#).
- **Excluding Pinched Spheres**, with Evangelos Protopapas, Dimitrios M. Thilikos, and Sebastian Wiederrecht. [Submitted to a journal](#).
- **When does FTP become FPT?**, with Matthias Bentert, Fedor V. Fomin, and Petr A. Golovach. [WG 2025](#).
- **Fault-Tolerant Matroid Bases**, with Matthias Bentert, Fedor V. Fomin, and Petr A. Golovach. [ESA 2025](#).
- **H-Planarity and Parametric Extensions: when Modulators Act Globally**, with Fedor V. Fomin, Petr A. Golovach, and Dimitrios M. Thilikos. [Submitted to a conference](#).
- **Faster Algorithms for the Pre-Assignment Problem for Unique Minimum Vertex Cover**, with Marthe Bonamy, Timothé Picavet, and Alexander Scott. [Submitted to a conference](#).