

Algorithms for graph modification problems: towards generality and efficiency

Laure Morelle

September 23rd, 2025

Committee

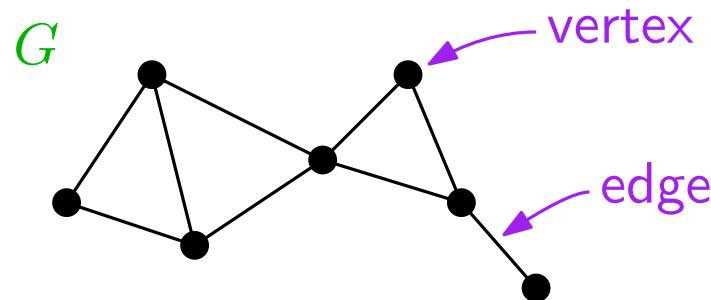
Robert Ganian	Reviewer
Eunjung Kim	Reviewer
Archontia Giannopoulou	Examiner
Petr Golovach	Examiner
Frédéric Havet	Examiner
Ignasi Sau	Supervisor
Dimitrios M. Thilikos	Supervisor

Graphs and Algorithms

Our research:

Design fast **algorithms** to solve **computational** problems.

Model of abstraction: **graphs**



$V(G)$ = set of vertices of G

$E(G)$ = set of edges of G

Graph modification problems

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Require:

Graph modification problems

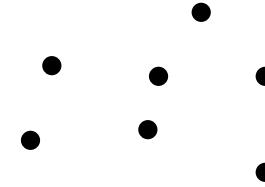
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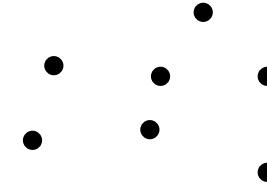
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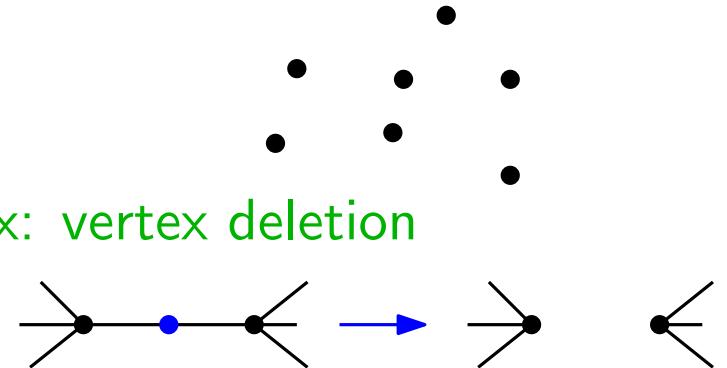
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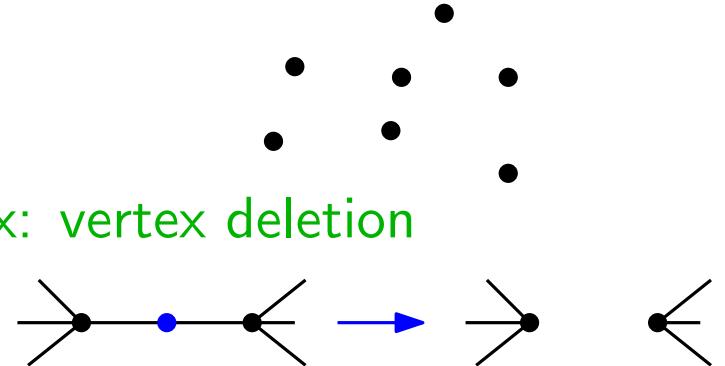
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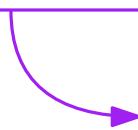
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3. A **measure** p on the modulator

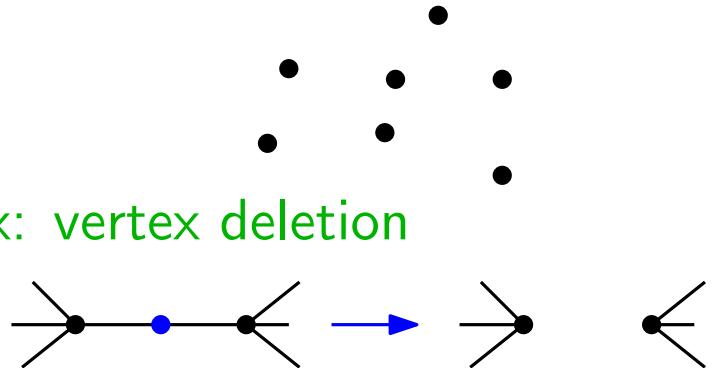


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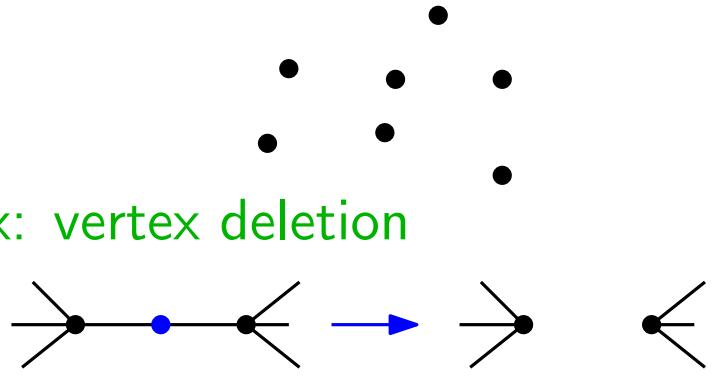
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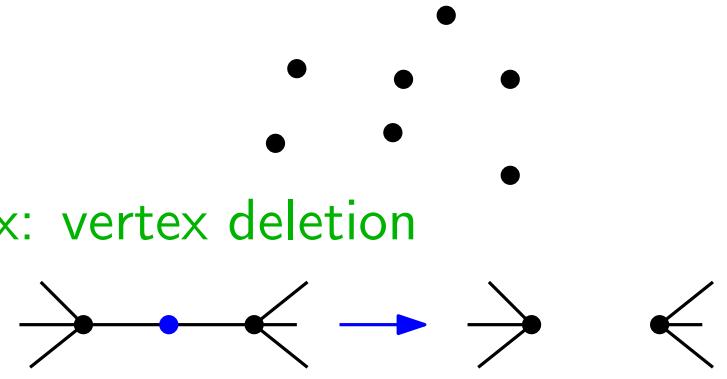


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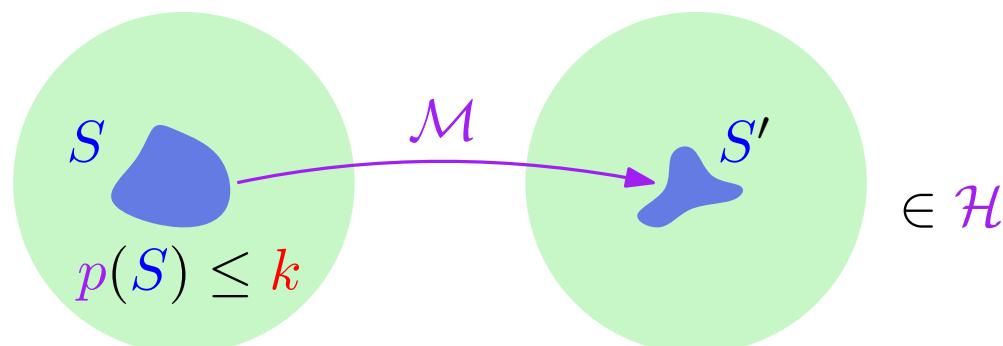
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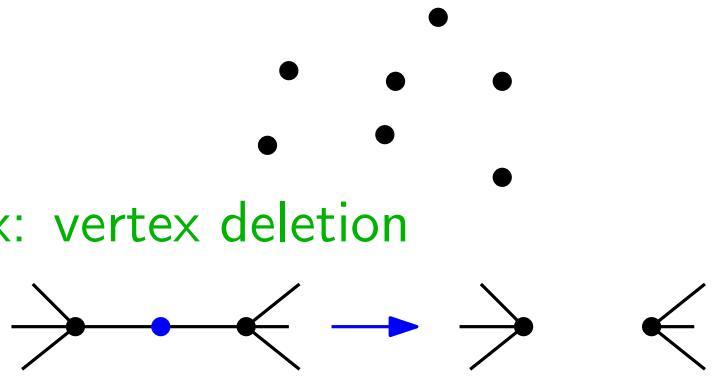
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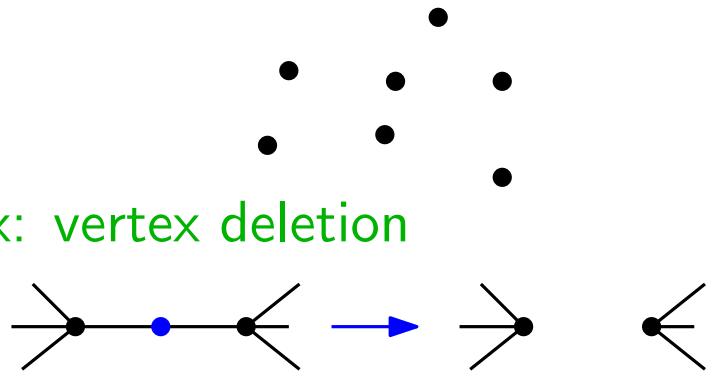
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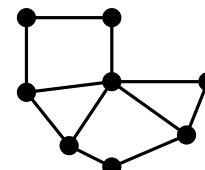


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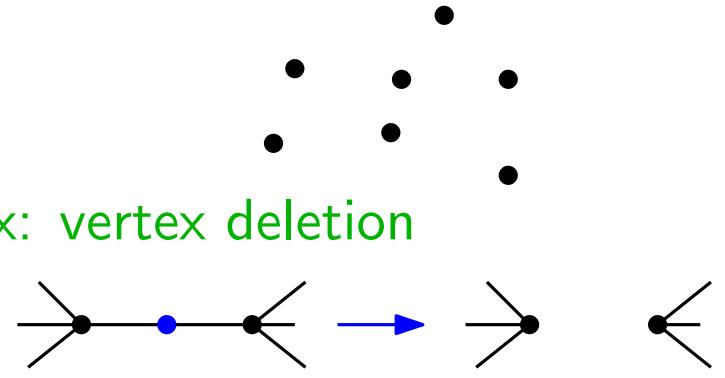
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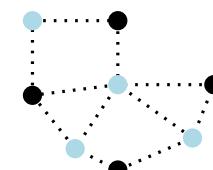
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[Chen, Kanj, Jia, '06]

There is an algorithm solving VERTEX COVER in time $\mathcal{O}(1.2738^k + k \cdot n)$.

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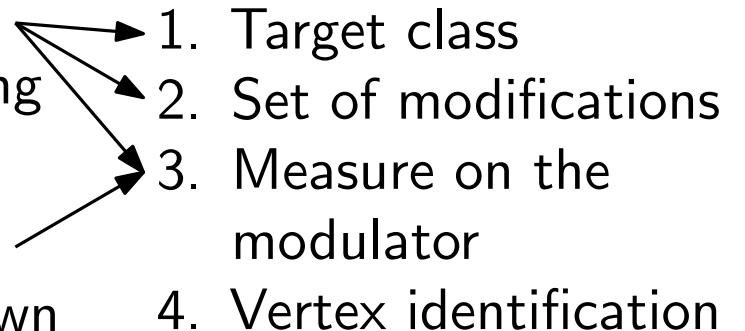
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Organization



1. Target class
2. Set of modifications
3. Measure on the modulator
4. Vertex identification

1. Target graph class \mathcal{H}

Modification = vertex deletion

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VERTEX DELETION TO \mathcal{H}

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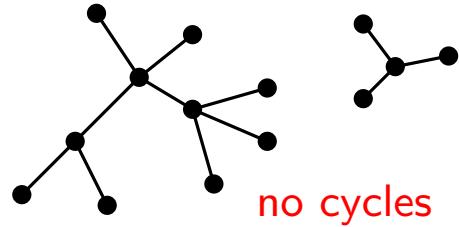
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FEEDBACK VERTEX SET

[Li, Nederlof, '22]

solvable in time $\mathcal{O}(2.7^k \cdot n)$

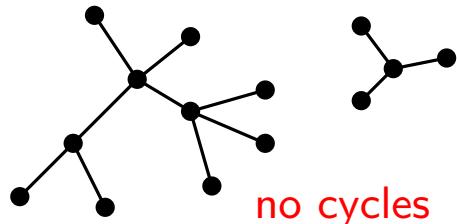
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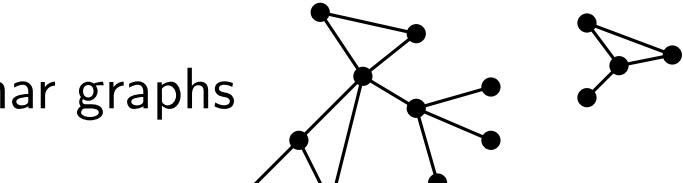
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\cap

\mathcal{H} = planar graphs



embeddable on the sphere =

can be drawn on the sphere with no edges crossing

PLANARIZATION

[Jansen, Lokshtanov, Saurabh, '14]

solvable in time $2^{\mathcal{O}(k \log k)} \cdot n$

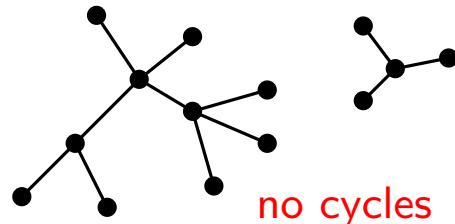
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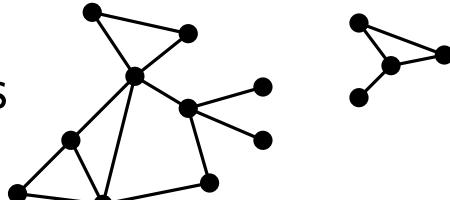


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\mathcal{H} = graphs embeddable on the surface Σ

[Kociumaka, Pilipczuk, '19]

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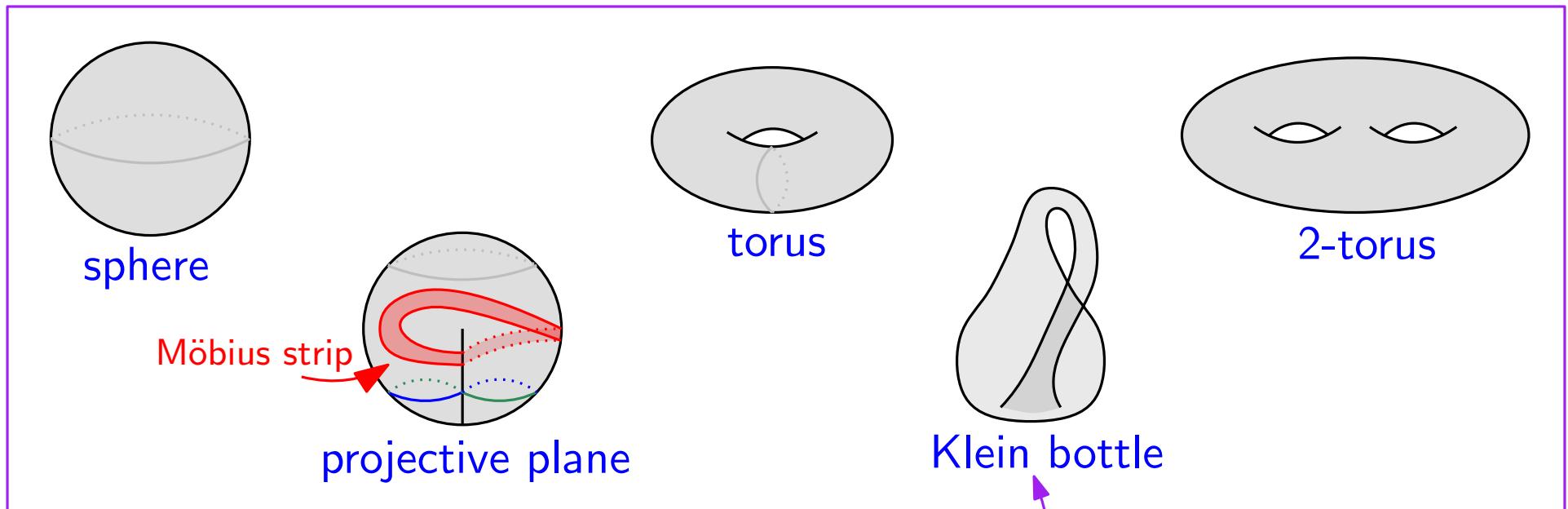
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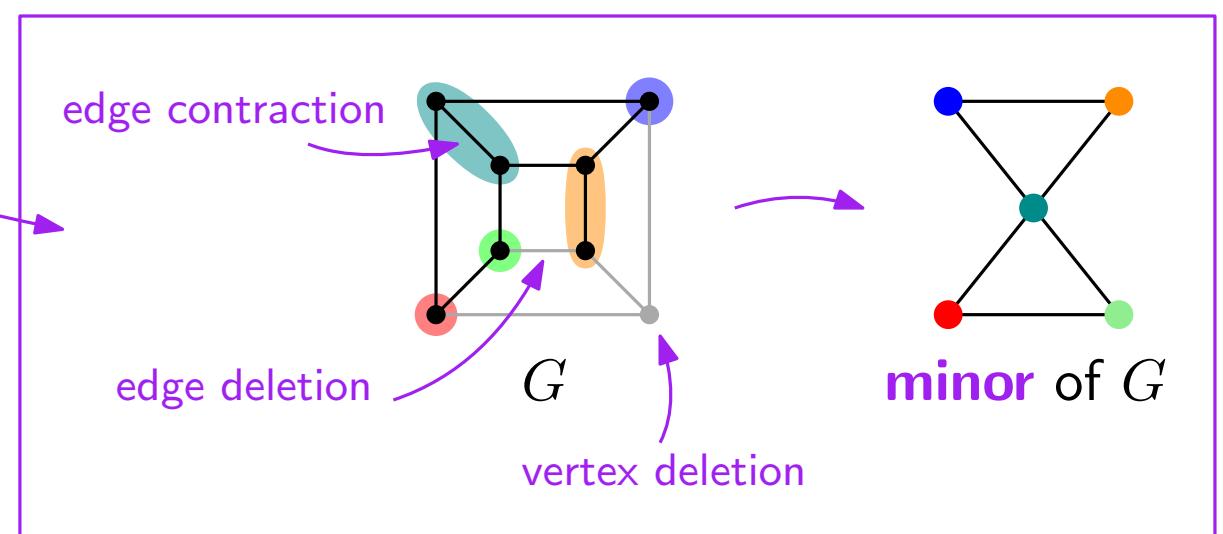
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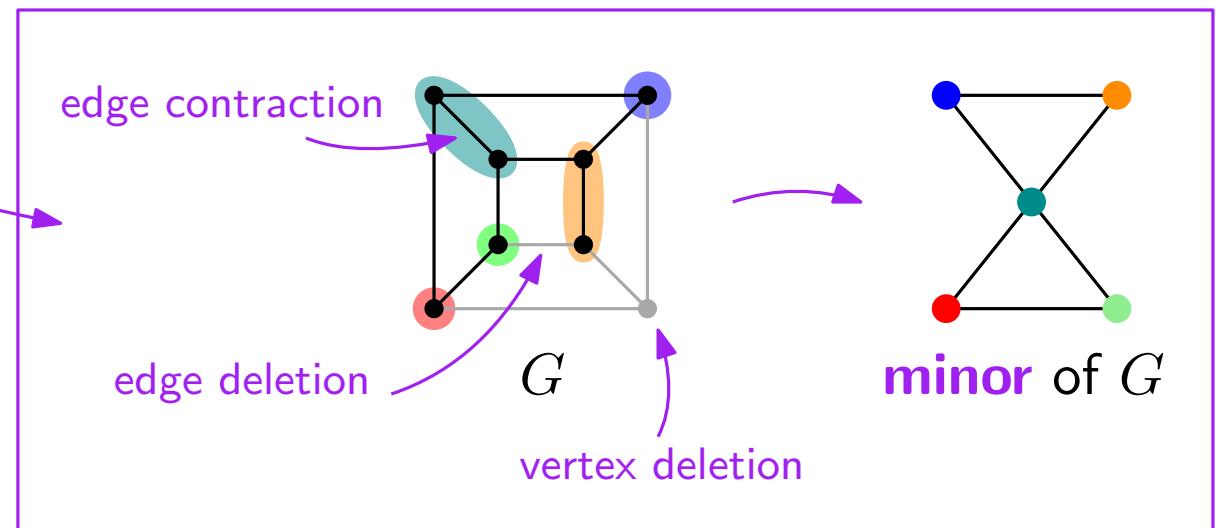
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If $G \in \mathcal{H}$, then minors of G in \mathcal{H} .



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originates from [Robertson, Seymour, '95]

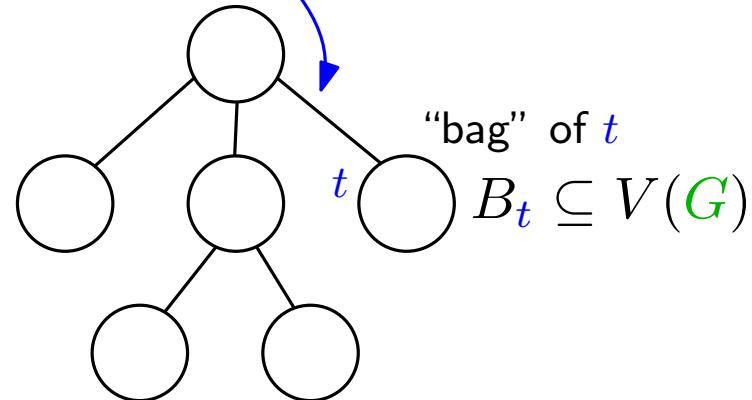
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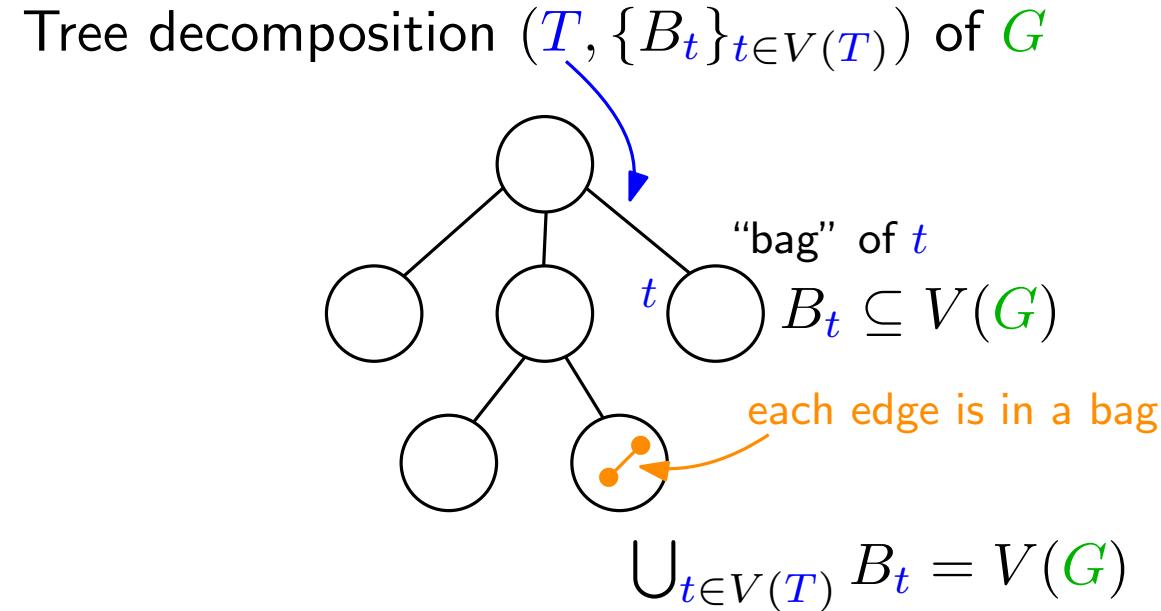
Tree decomposition $(T, \{B_t\}_{t \in V(T)})$ of G



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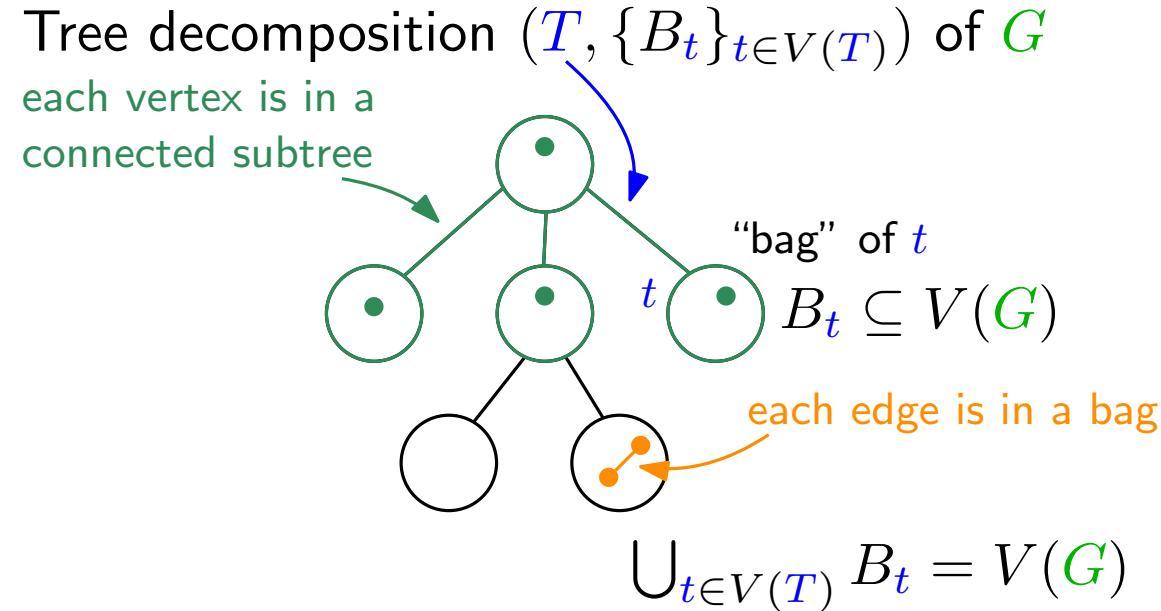
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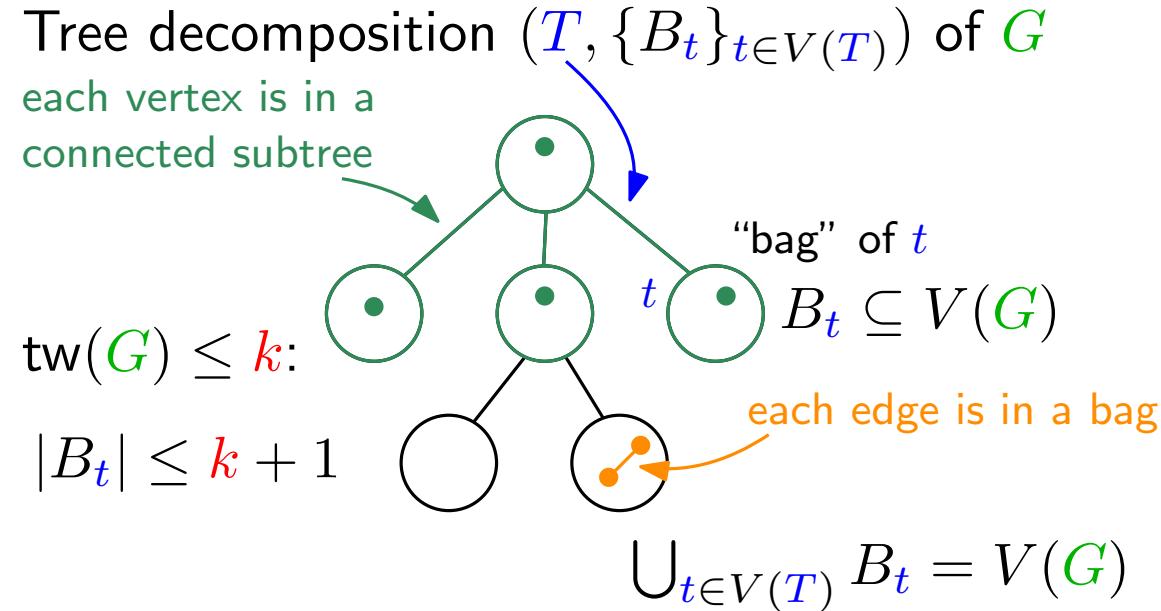
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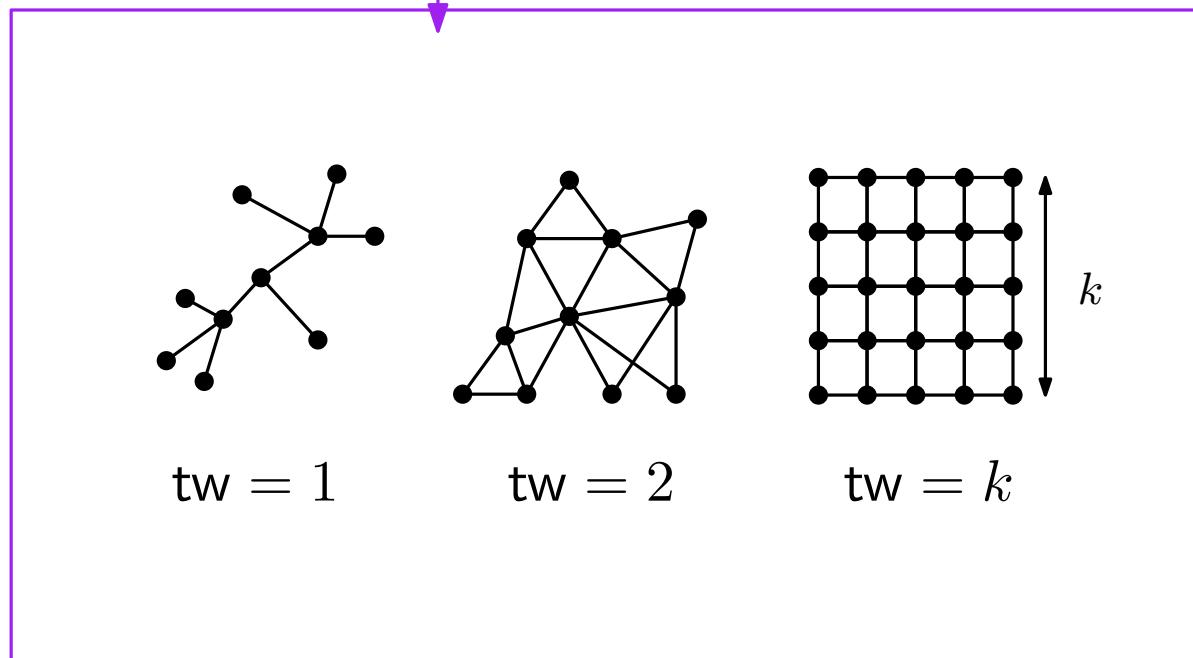
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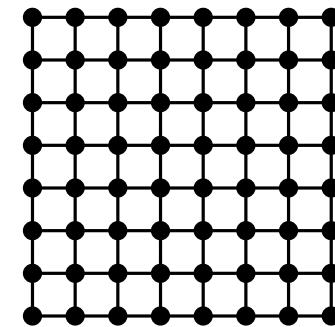
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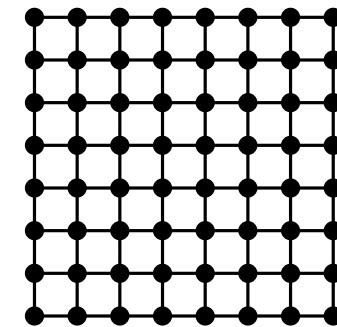
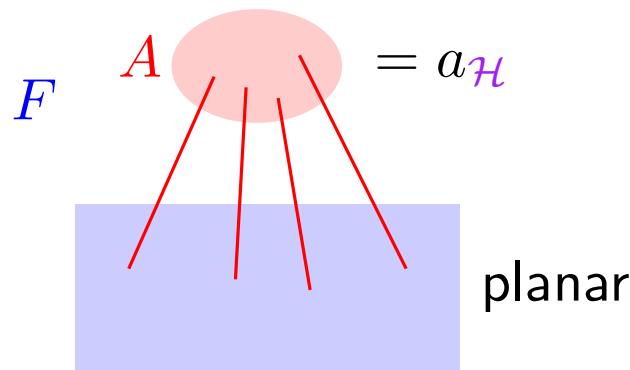
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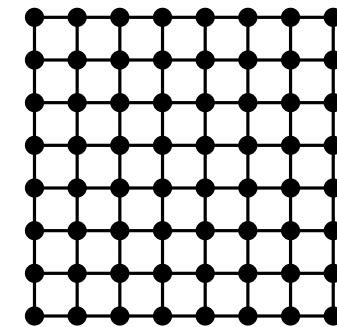
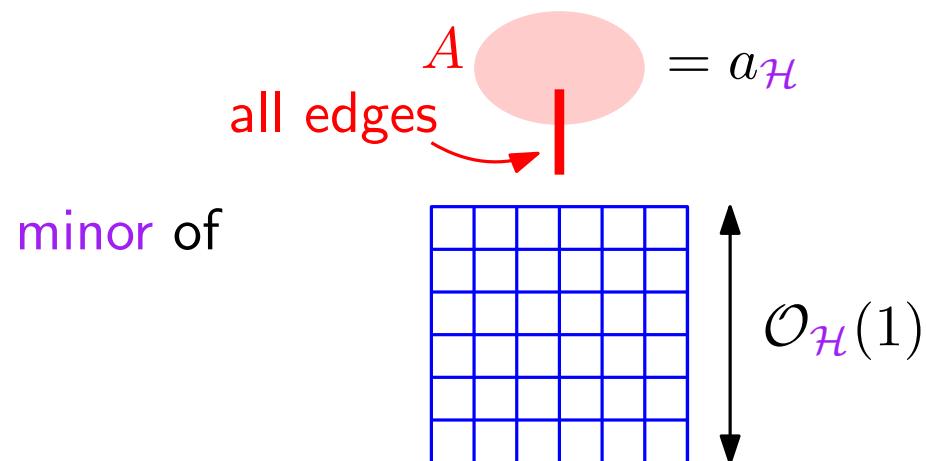
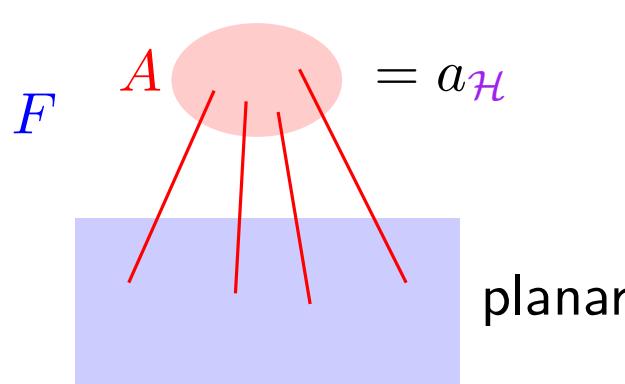
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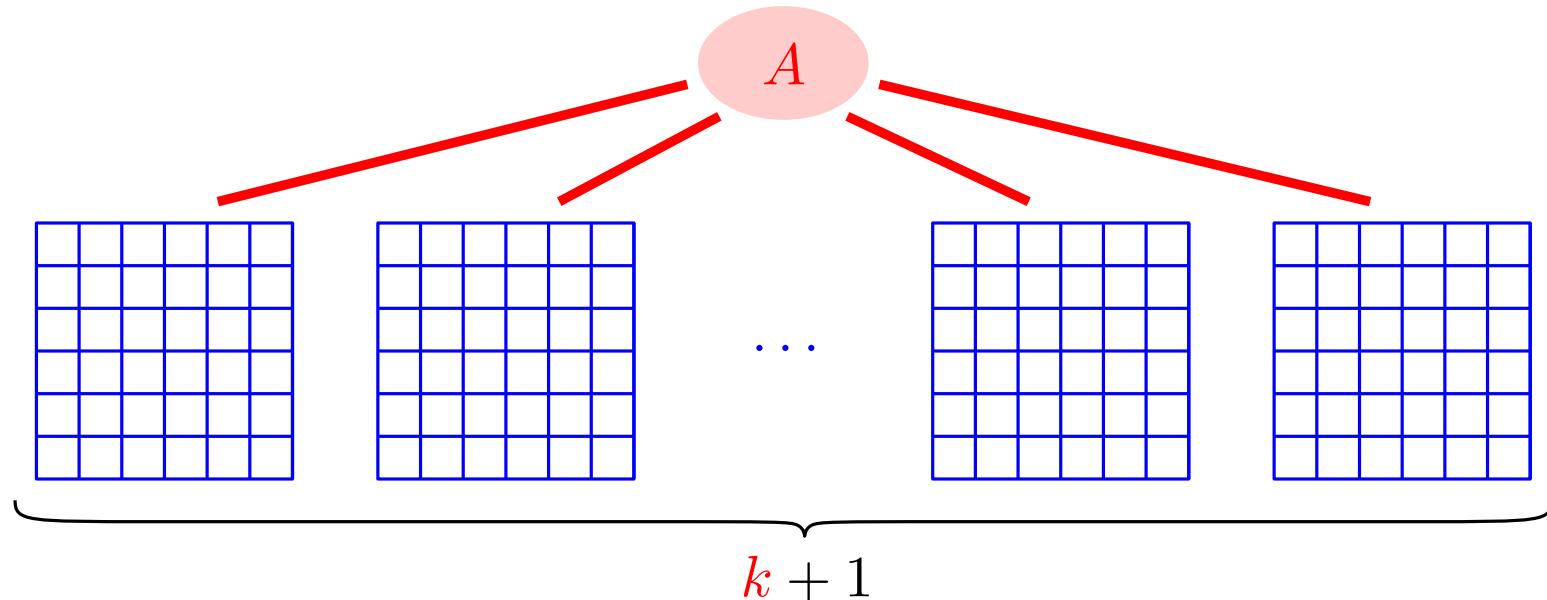
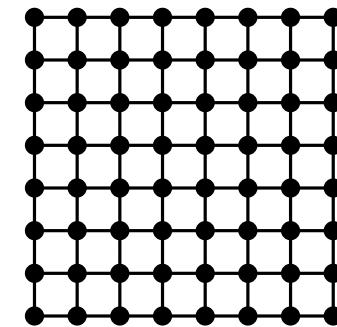
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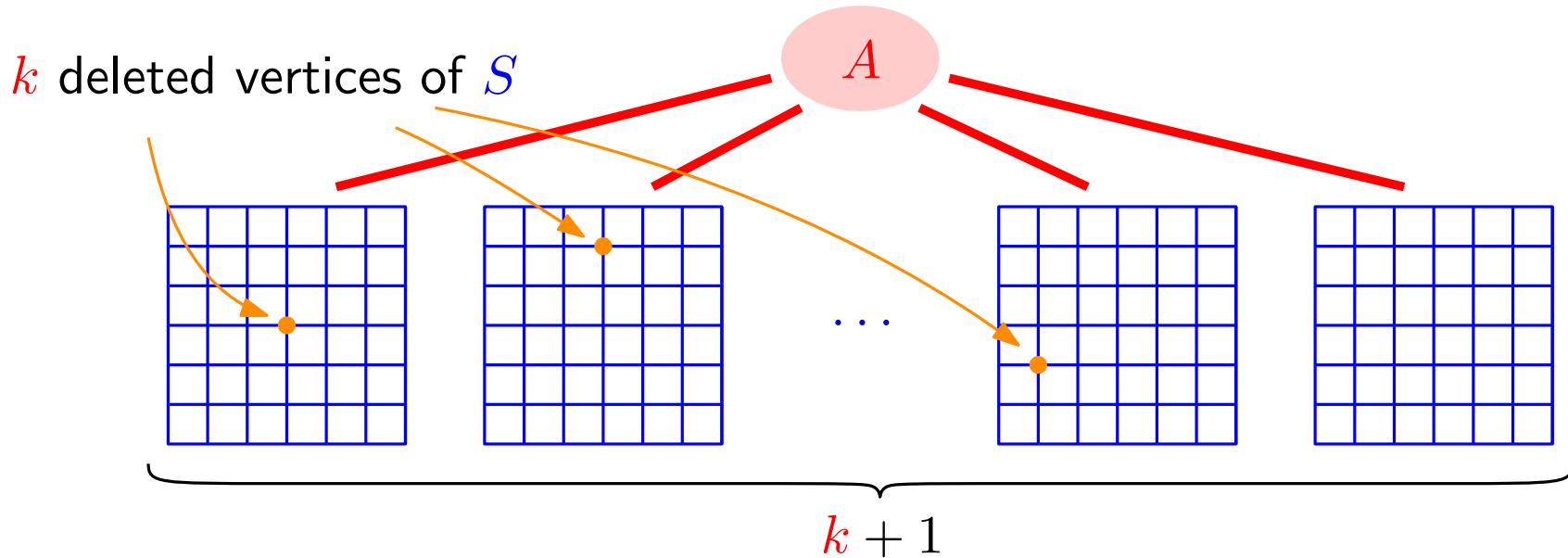
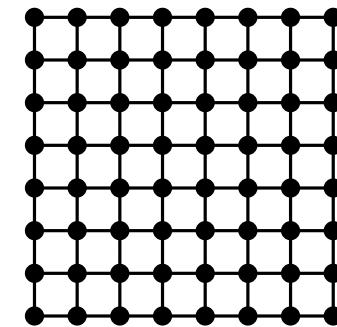
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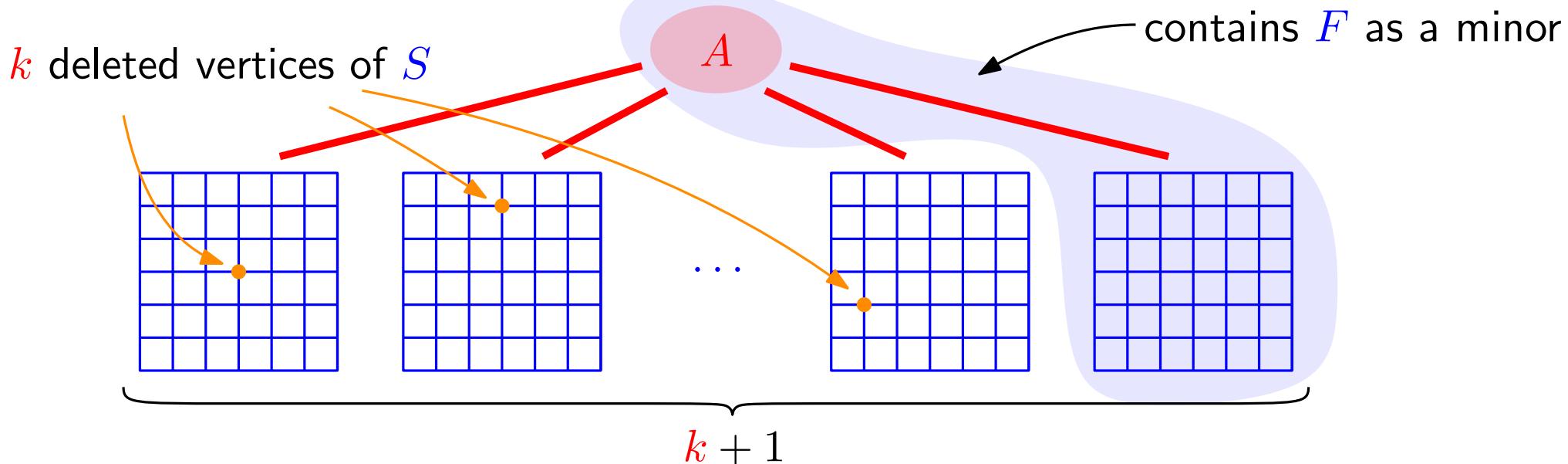
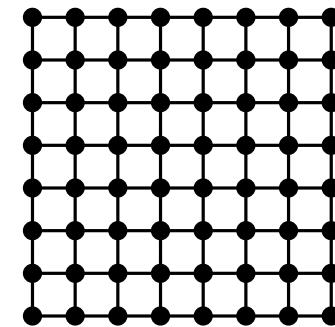
Target graph class \mathcal{H}

Sketch of the proof

Win/Win strategy on the **treewidth** $\text{tw}(G)$ of G :

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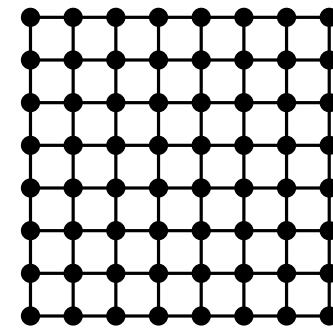
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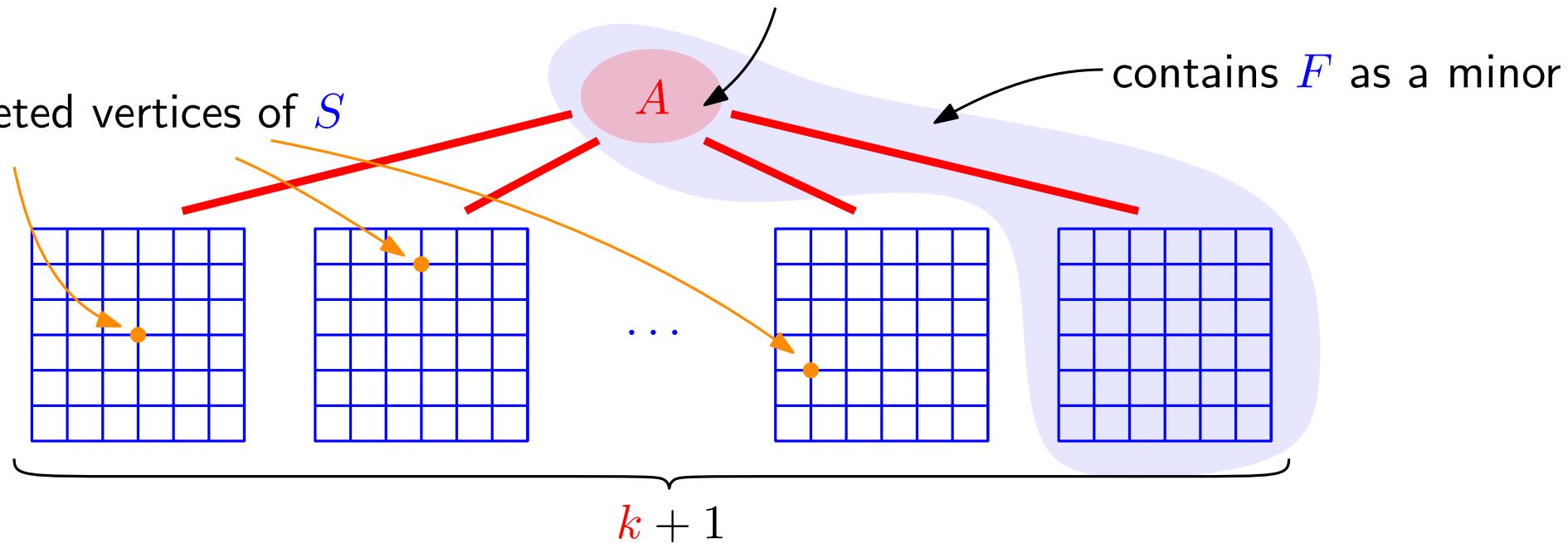
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unless $S \cap A \neq \emptyset$

k deleted vertices of S



Target graph class \mathcal{H}

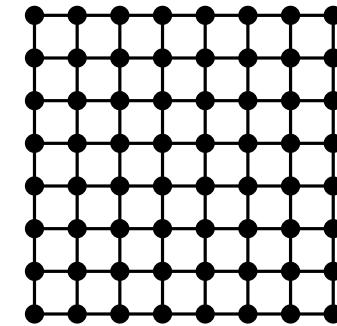
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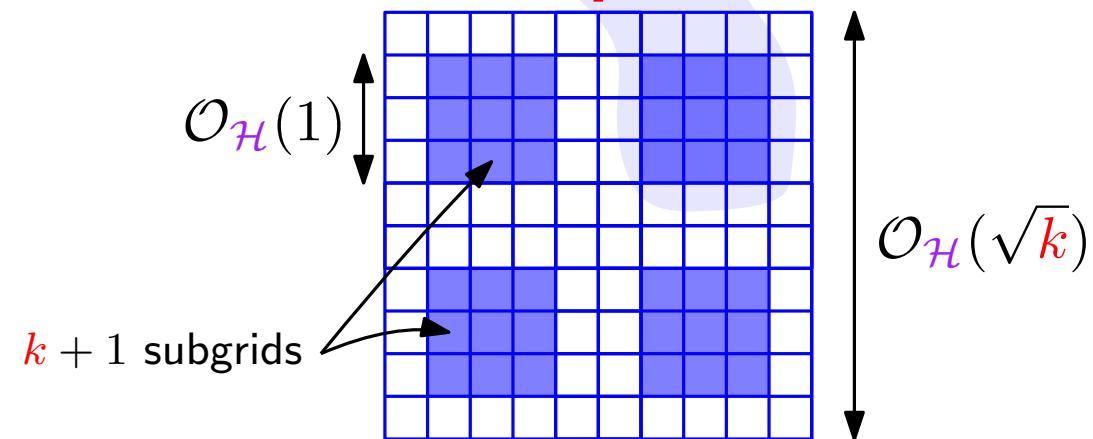
then G contains a **big** grid as a minor.

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A

contains F as a minor



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Sketch of the proof

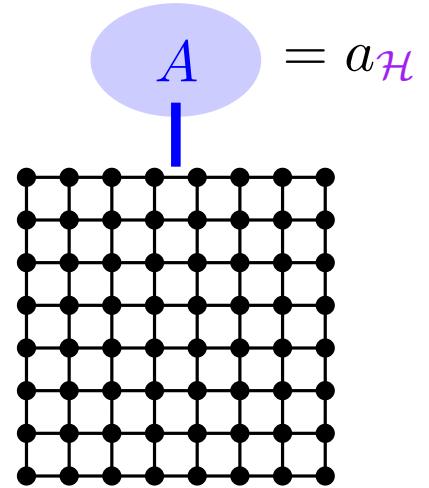
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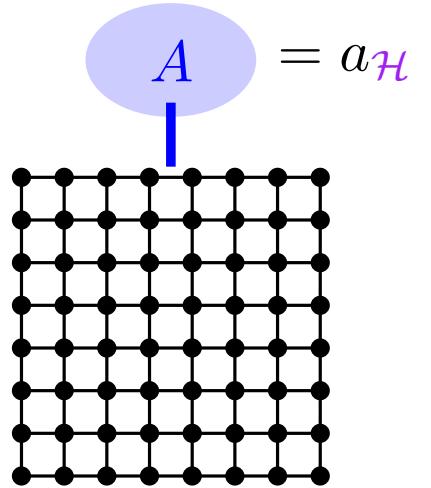
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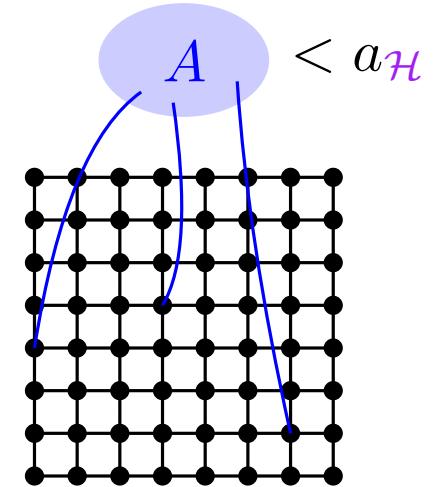
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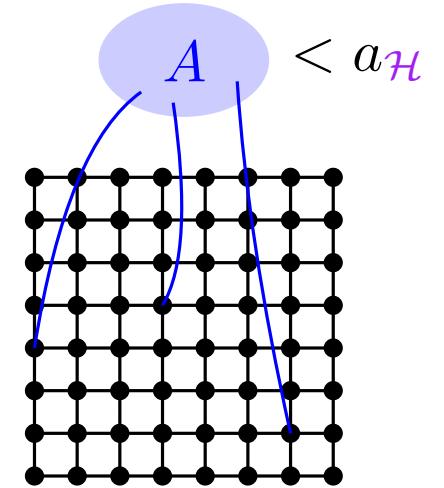
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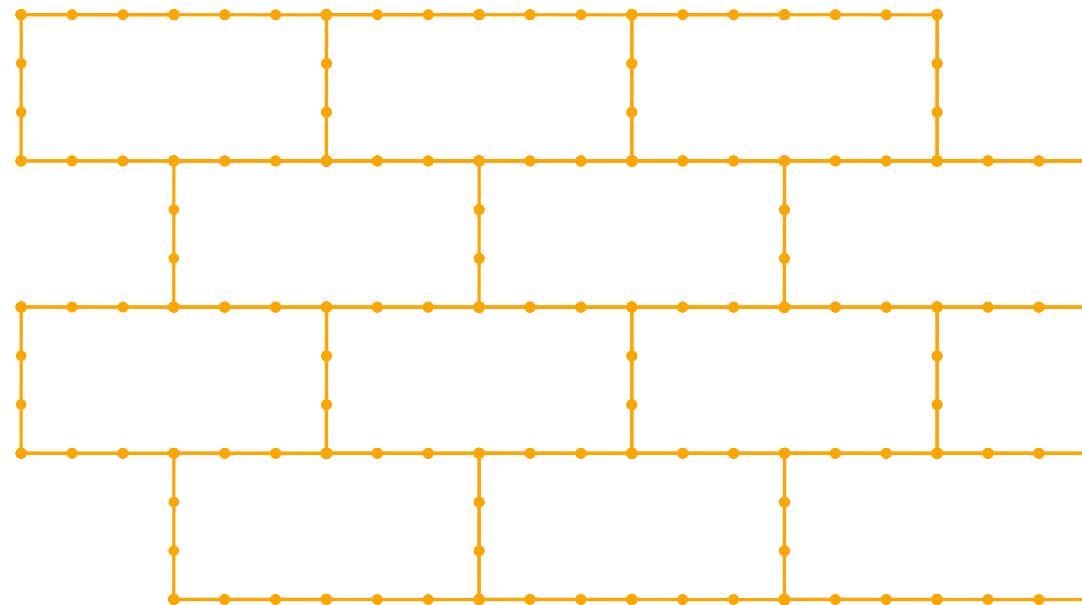
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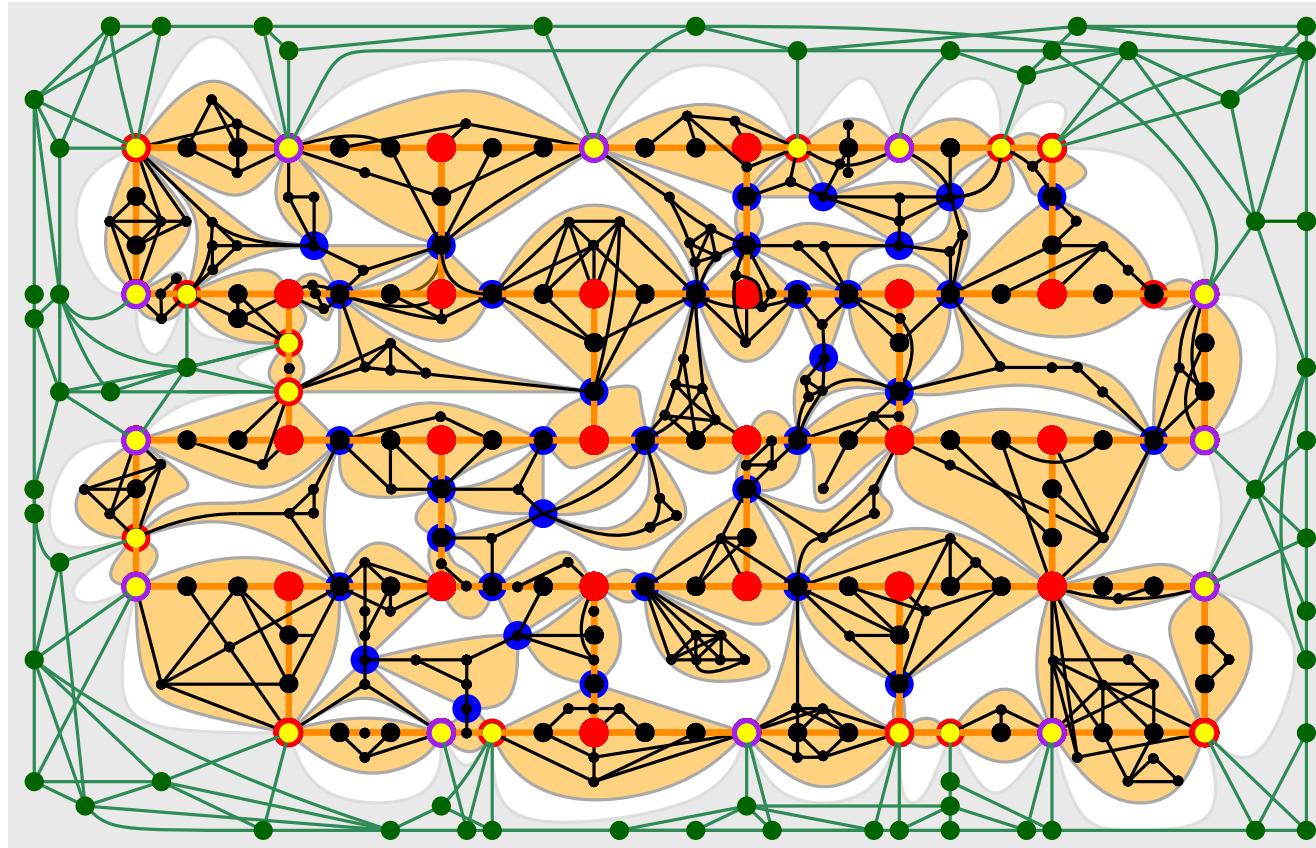
Target graph class \mathcal{H}

A **wall**:



Target graph class \mathcal{H}

A **flat** wall:



[figure by Dimitrios M. Thilikos]

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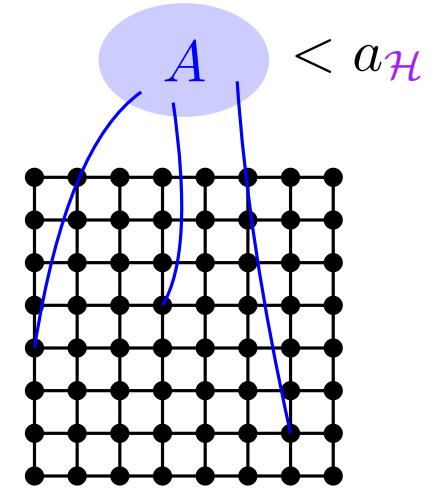
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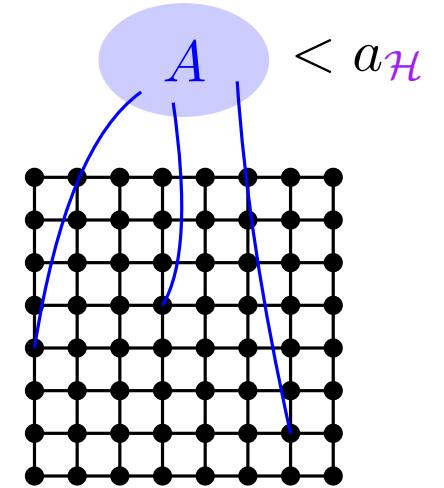
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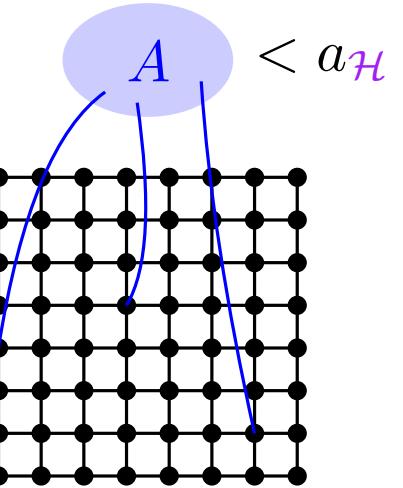
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2. Set of modifications \mathcal{M}

Measure = size of the modulator

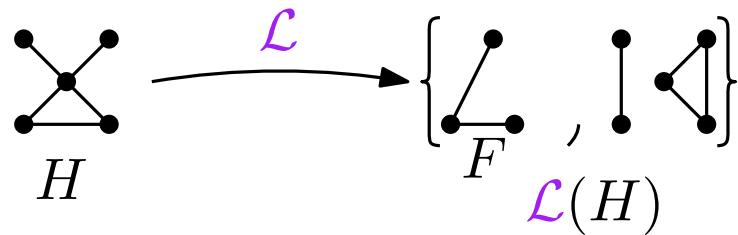
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Model of abstraction to represent many modifications at once?

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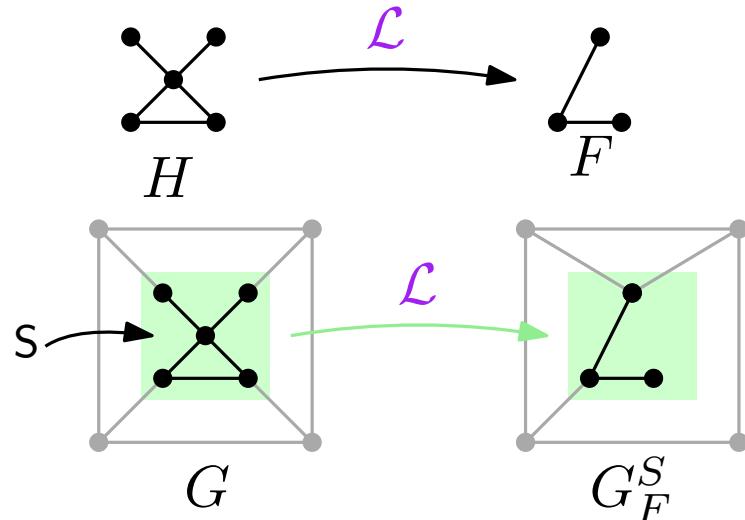
R-action: function \mathcal{L} mapping each graph H to a collection $\mathcal{L}(H)$ of graphs of equal or smaller size. [Fomin, Golovach, Thilikos, '19]



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\mathcal{L} -Replacement to \mathcal{H}

Input: A graph G and an integer k .

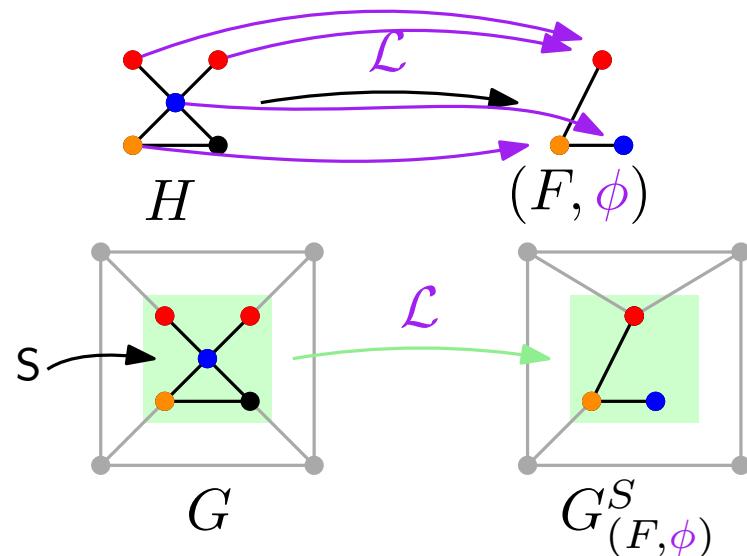
Question: Is there a vertex set S of size at most k and $F \in \mathcal{L}(G[S])$ s.t. $G_F^S \in \mathcal{H}$?

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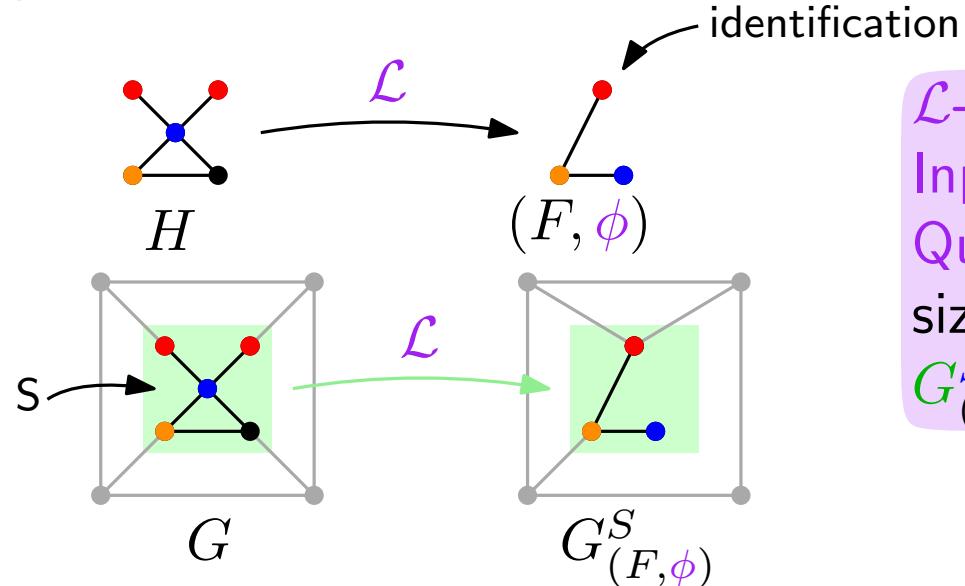
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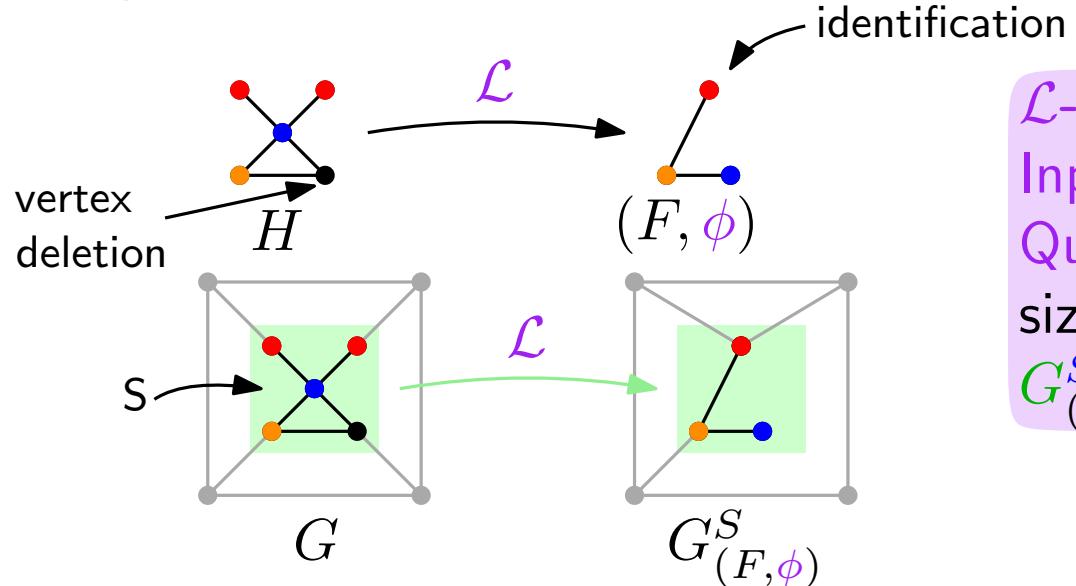
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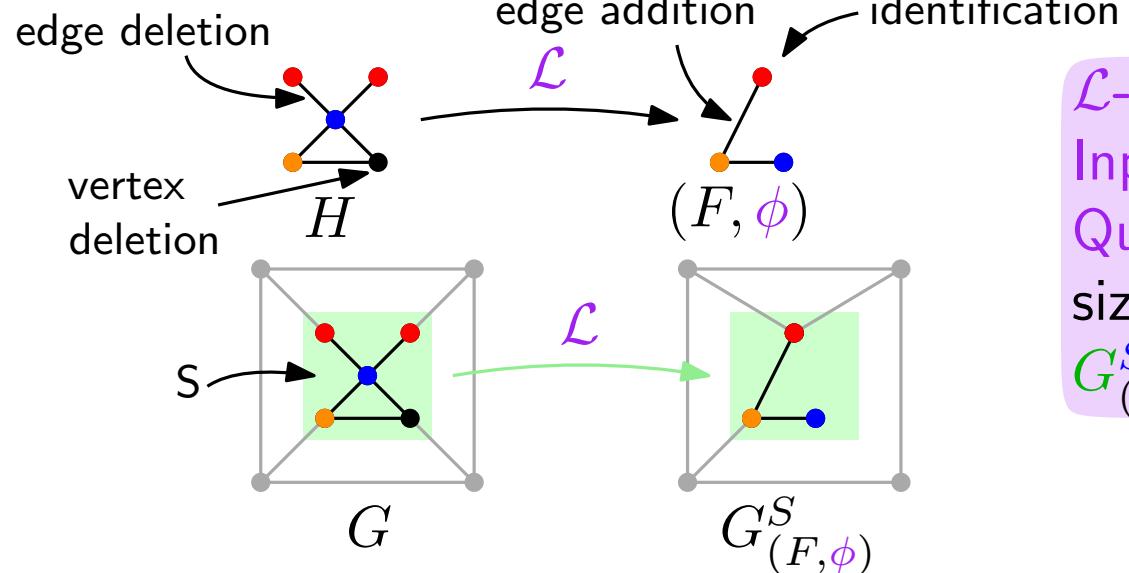
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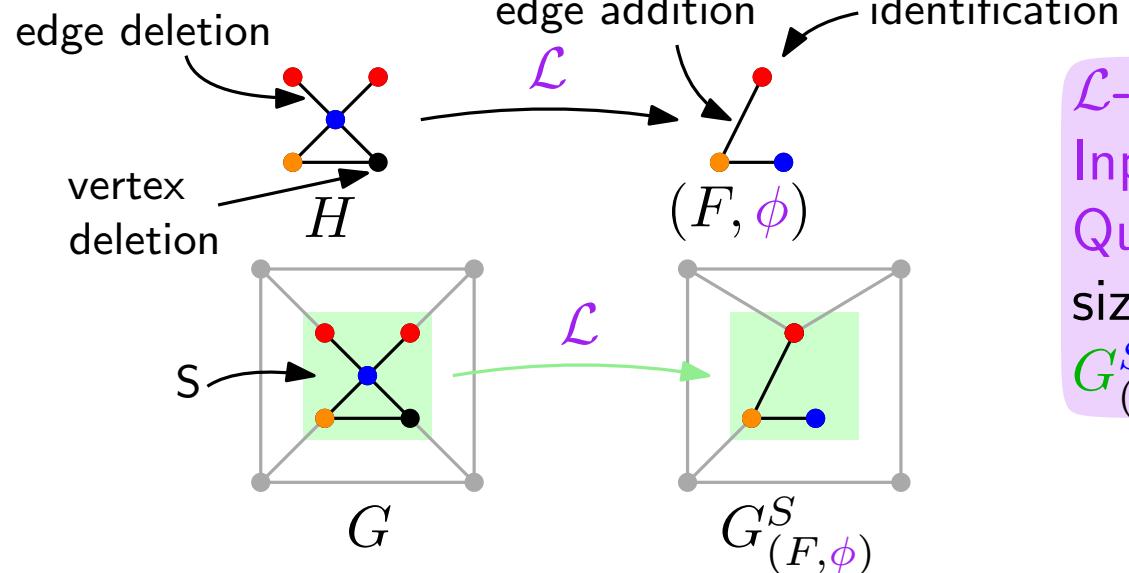
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Model of abstraction to represent many modifications at once?

R-action: function \mathcal{L} mapping each graph H to a collection $\mathcal{L}(H)$ of graphs of **equal or smaller size**.

[Fomin, Golovach, Thilikos, '19]



\mathcal{L} -Replacement to \mathcal{H}

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\mathcal{H} minor-closed

[Morelle, Sau, Thilikos]

\mathcal{L} -REPLACEMENT TO \mathcal{H} is solvable in time $2^{\text{poly}_{\mathcal{H}}(k)} \cdot n^2$ for \mathcal{L} hereditary.

Measure = size of the modulator

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- VERTEX DELETION TO \mathcal{H}
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- EDGE CONTRACTION TO \mathcal{H}
- MATCHING DELETION TO \mathcal{H}
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- etc.

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Sketch of the proof

Sketch of the proof for VERTEX DELETION TO \mathcal{H} :

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If there is a **big flow** from a set A to the grid:

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$2^{\mathcal{O}_{\mathcal{H}}(k^2 + (k + \text{tw}) \log(k + \text{tw}))} \cdot n$

new dynamic programming

Representative-based technique [Baste, Sau, Thilikos , '19]

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[Morelle, Sau, Thilikos]

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\mathcal{H}_Σ = graphs embeddable on a surface Σ

[Morelle, Sau, Thilikos]

\mathcal{L} -REPLACEMENT TO \mathcal{H}_Σ is solvable in time $2^{\mathcal{O}_\Sigma(\mathfrak{k}^9)} \cdot \textcolor{violet}{n}^2$ for \mathcal{L} hereditary.

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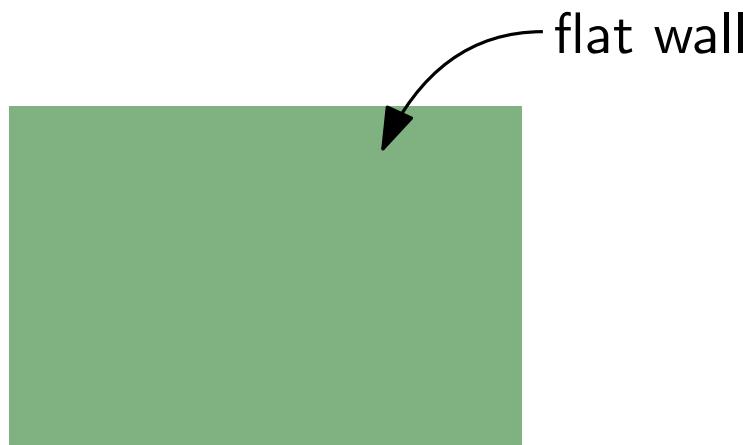
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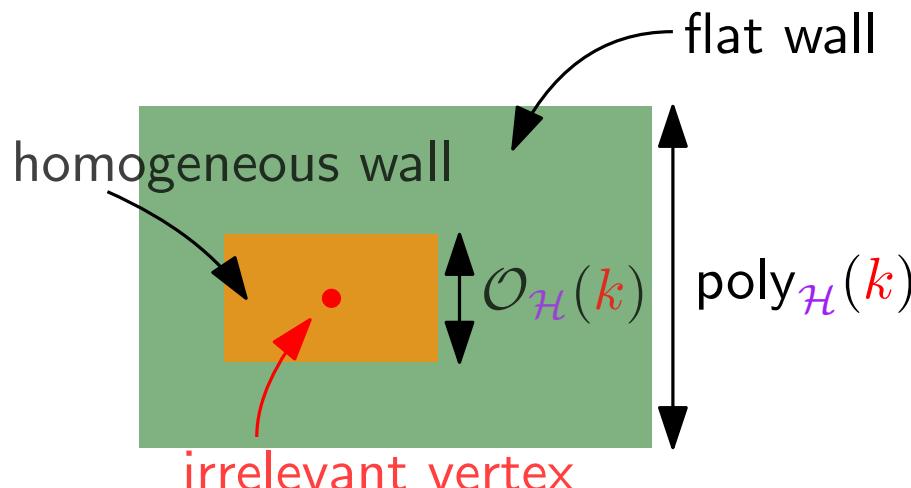
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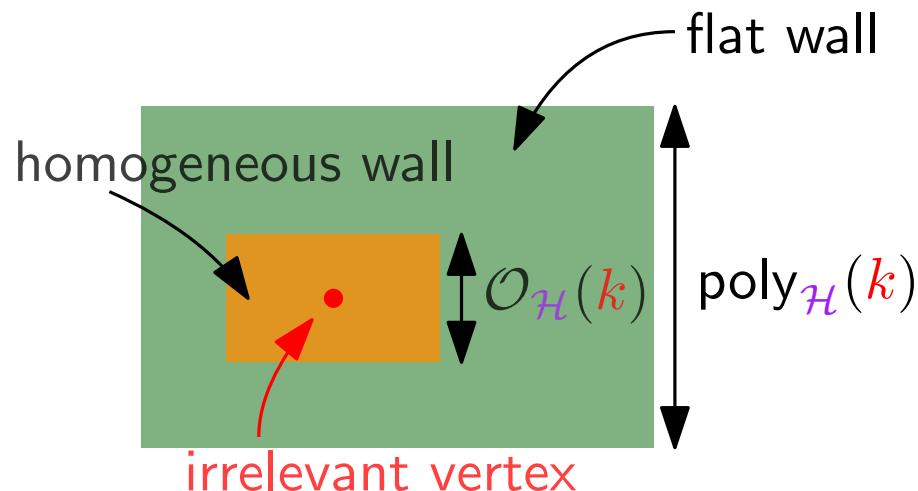
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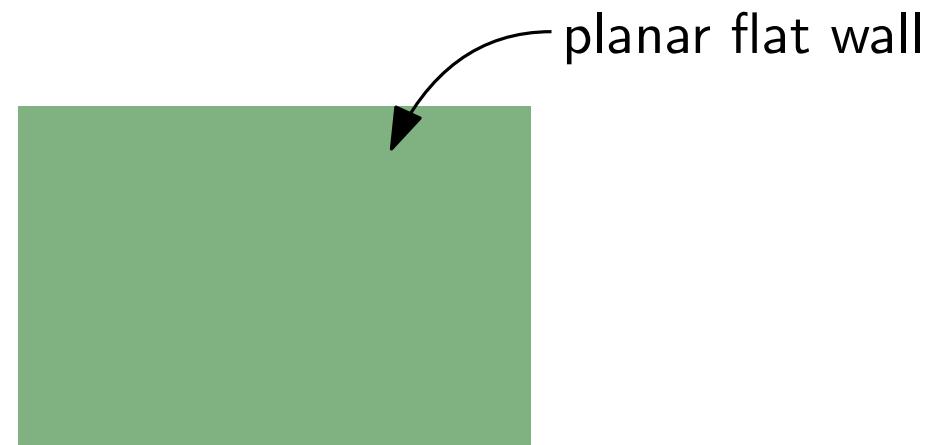
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General case:



Case of surfaces:



\mathcal{H} minor-closed

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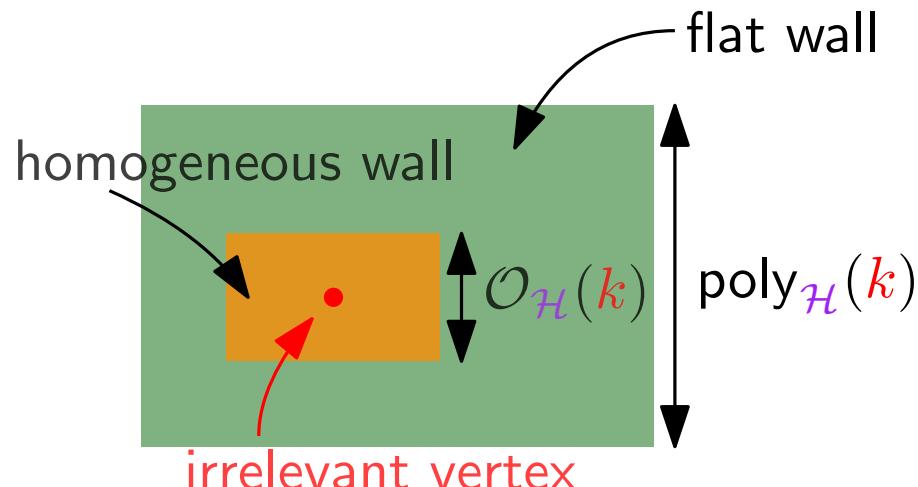
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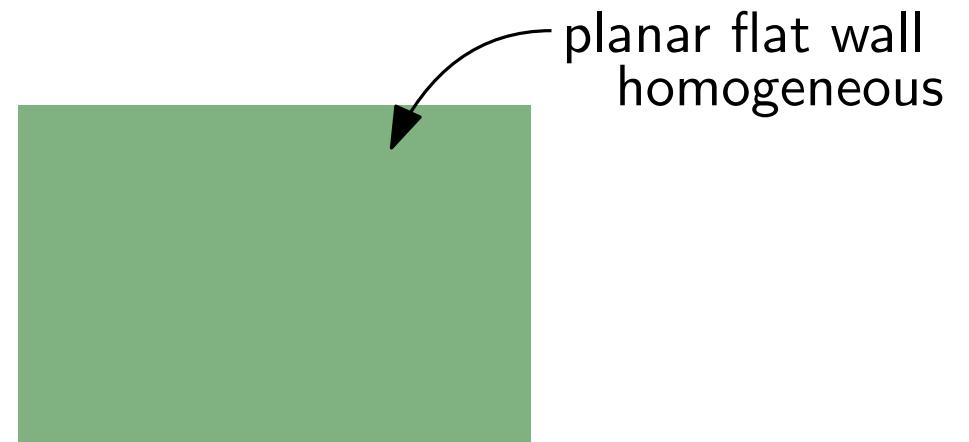
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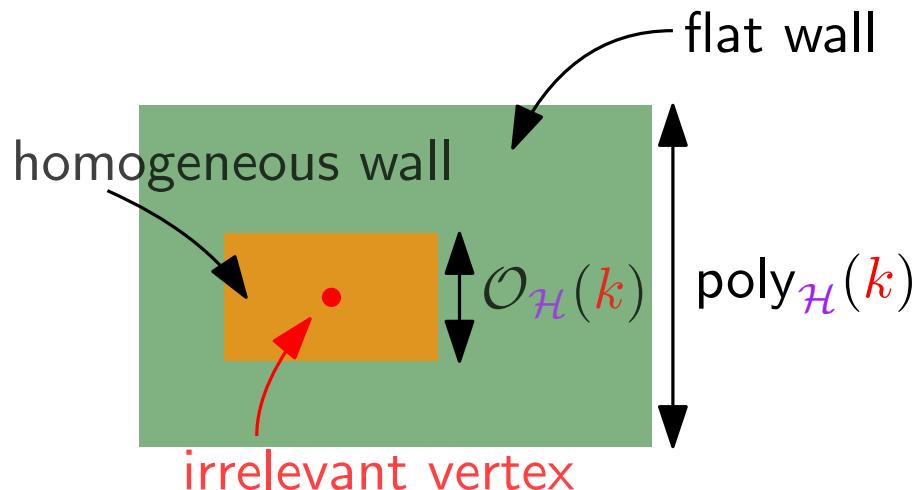
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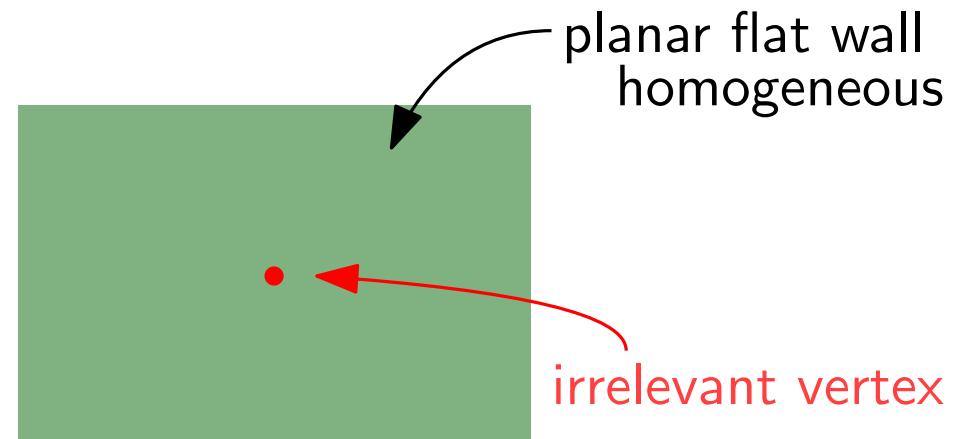
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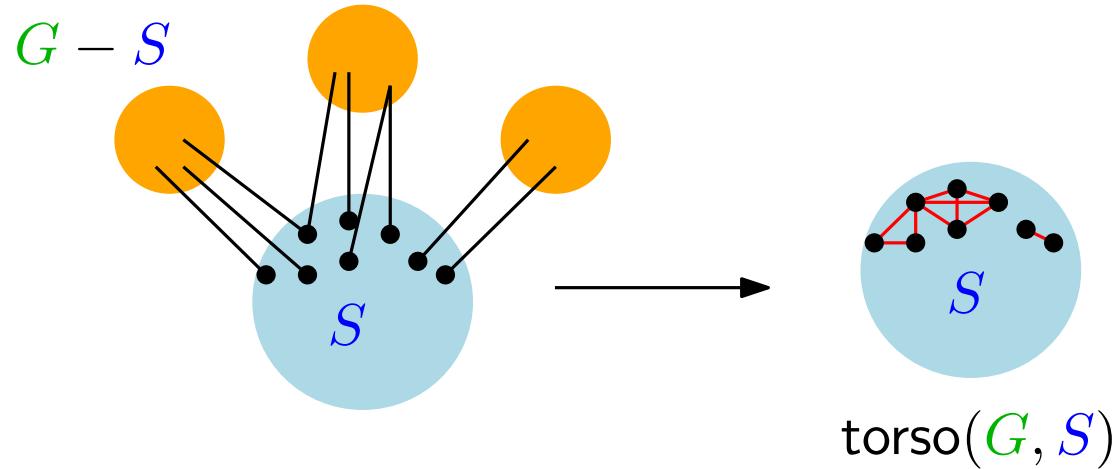


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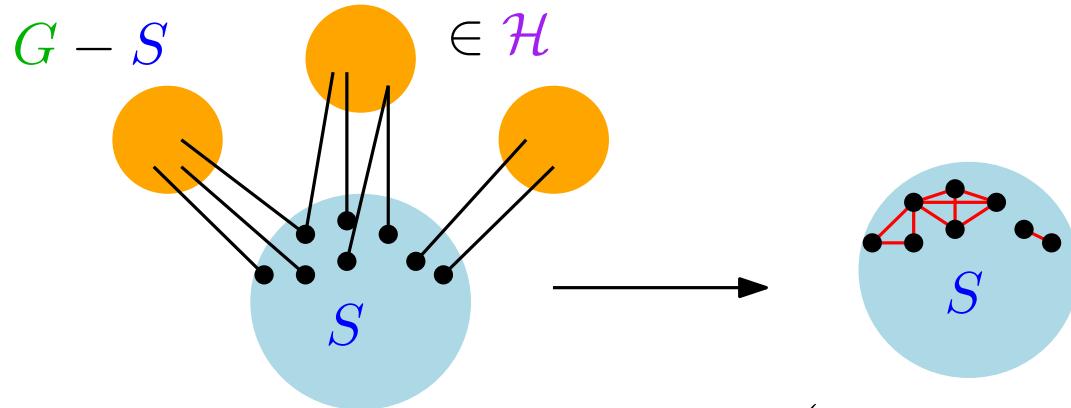


3. Measure p on the modulator

Torso of a vertex set S in a graph G :



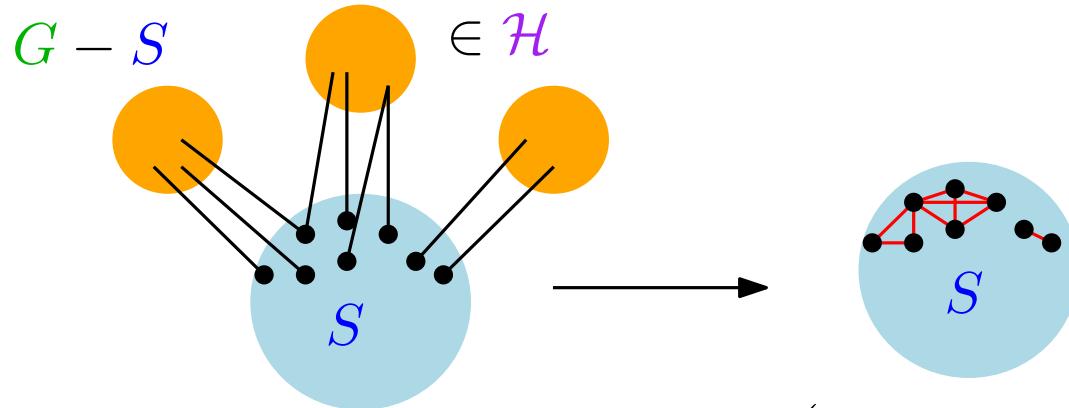
Torso of a vertex set S in a graph G :



Parameter p

$\mathcal{H}\text{-}p(G) = \min\{k \mid \text{there is a vertex set } S \text{ s.t. } p(\text{torso}(G, S)) \leq k \text{ and the components of } G - S \text{ are in } \mathcal{H}\}$

Torso of a vertex set S in a graph G :



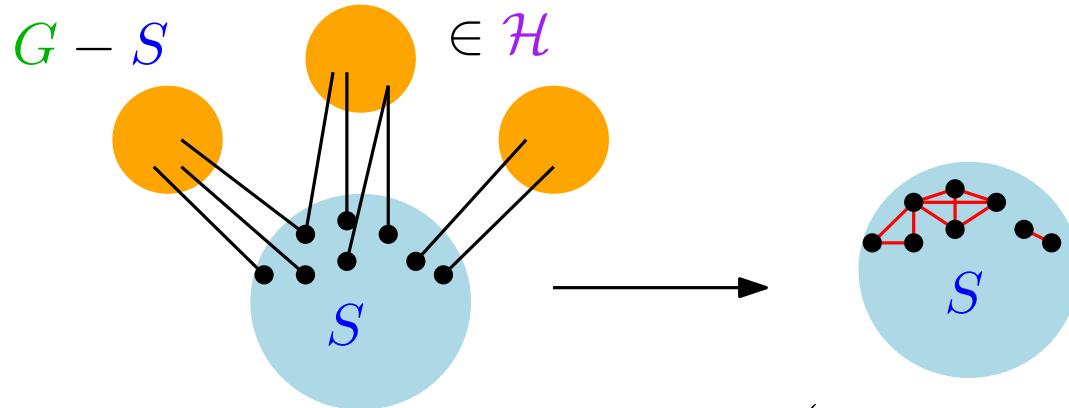
Parameter p

$\mathcal{H}\text{-}p(G) = \min\{k \mid \text{there is a vertex set } S \text{ s.t. } p(\text{torso}(G, S)) \leq k \text{ and the components of } G - S \text{ are in } \mathcal{H}\}$

Graph modification problem: **Input:** A graph G and an integer k .

Output: Is $\mathcal{H}\text{-}p(G) \leq k$?

Torso of a vertex set S in a graph G :

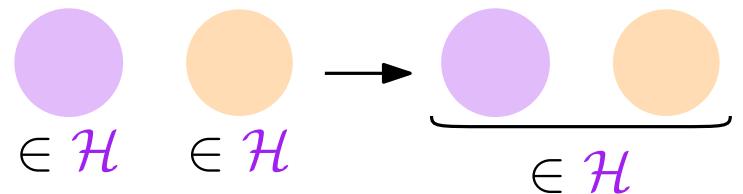


Parameter p

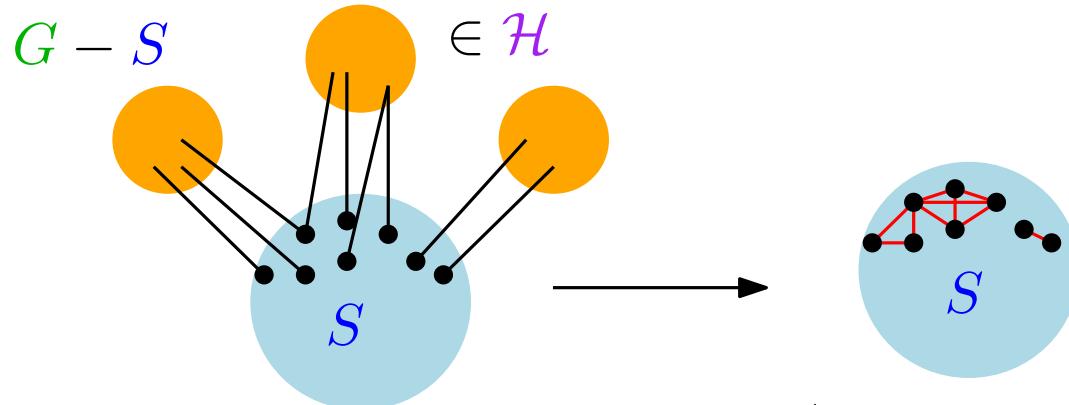
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\mathcal{H} -size \rightarrow VERTEX DELETION TO \mathcal{H} if \mathcal{H} is closed under disjoint union



Torso of a vertex set S in a graph G :



$$p(\text{torso}(G, S)) \leq k$$

Parameter p

\mathcal{H} - $p(G) = \min\{k \mid \text{there is a vertex set } S \text{ s.t. } p(\text{torso}(G, S)) \leq k$
and the components of $G - S$ are in $\mathcal{H}\}$

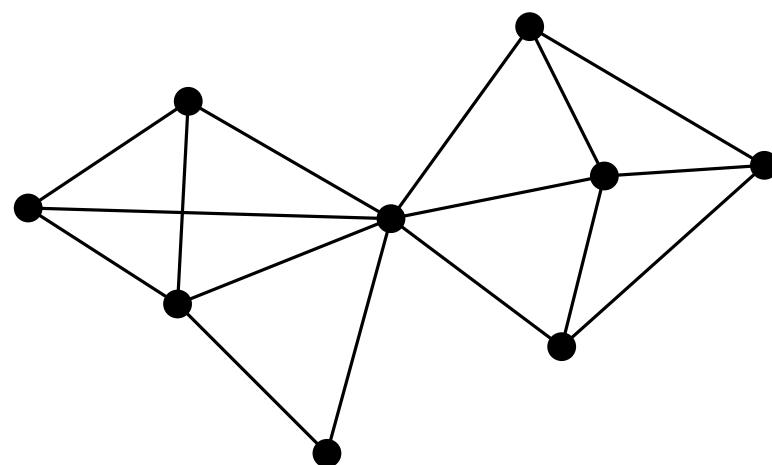
Graph modification problem: Input: A graph G and an integer k .
Output: Is \mathcal{H} - $p(G) \leq k$?

\mathcal{H} -size \rightarrow VERTEX DELETION TO \mathcal{H}

\mathcal{H} -td \rightarrow ELIMINATION DISTANCE TO \mathcal{H} [Bulian, Dawar, '16]

Torso of a vertex set S in a graph G :

treedepth $\text{td}(G)$:



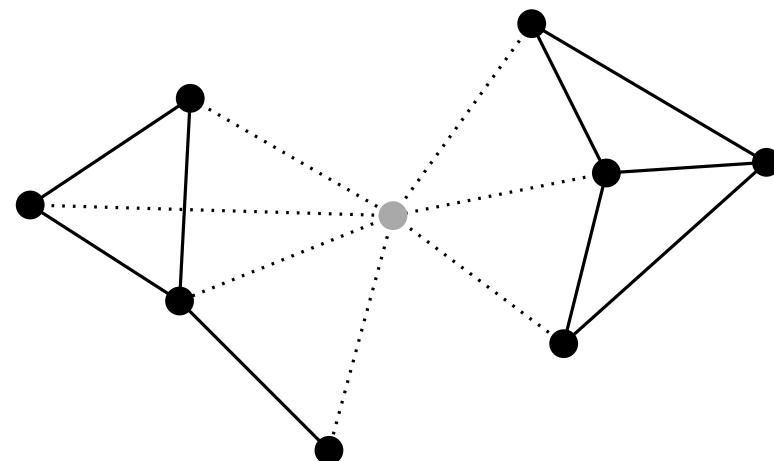
Step 0

At each step, remove 1 vertex
from each component

\mathcal{H} -td \rightarrow ELIMINATION DISTANCE TO \mathcal{H} [Bulian, Dawar, '16]

Torso of a vertex set S in a graph G :

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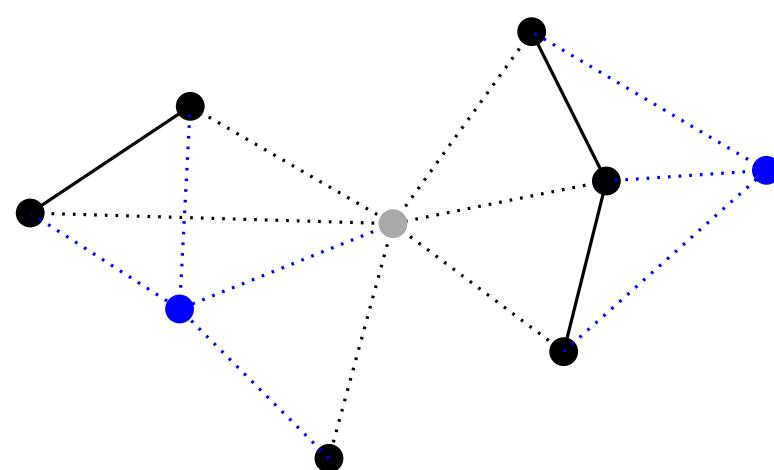
Step 1

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Torso of a vertex set S in a graph G :

treedepth $\text{td}(G)$:



Step 2

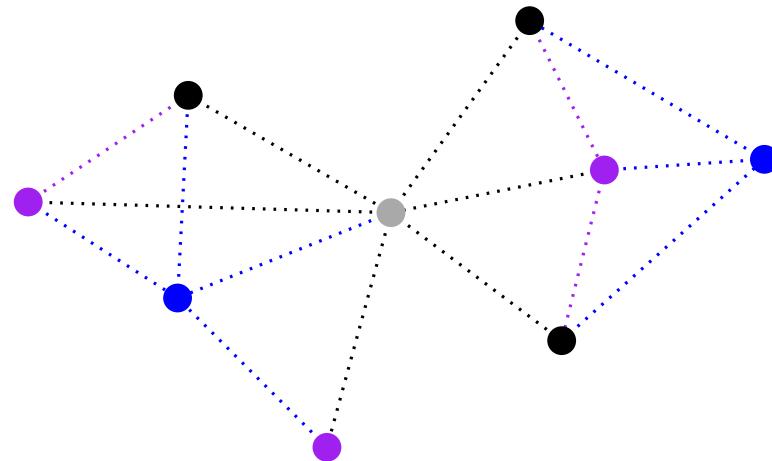
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Torso of a vertex set S in a graph G :

treedepth $\text{td}(G)$:

Step 3



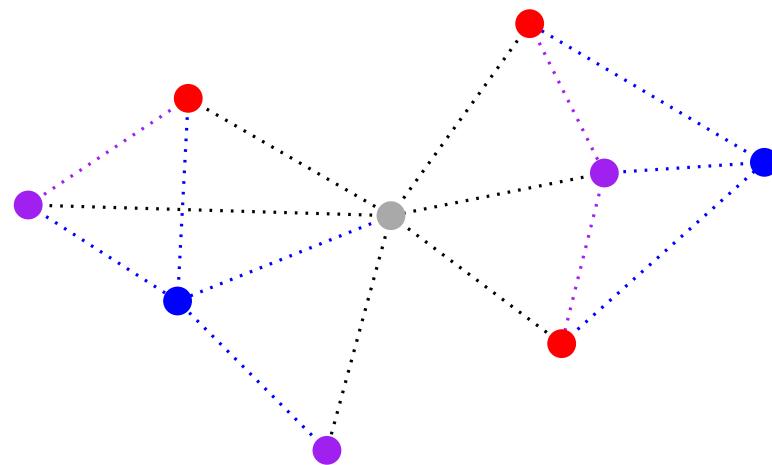
At each step, remove 1 vertex from each component

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Torso of a vertex set S in a graph G :

treedepth $\text{td}(G)$:

Step 4



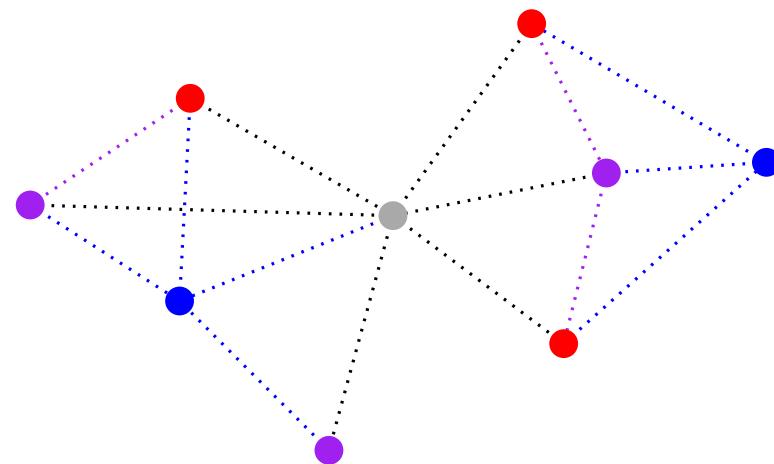
At each step, remove 1 vertex
from each component

\mathcal{H} -td \rightarrow ELIMINATION DISTANCE TO \mathcal{H} [Bulian, Dawar, '16]

Torso of a vertex set S in a graph G :

treedepth $\text{td}(G)$: min number of steps to remove all vertices

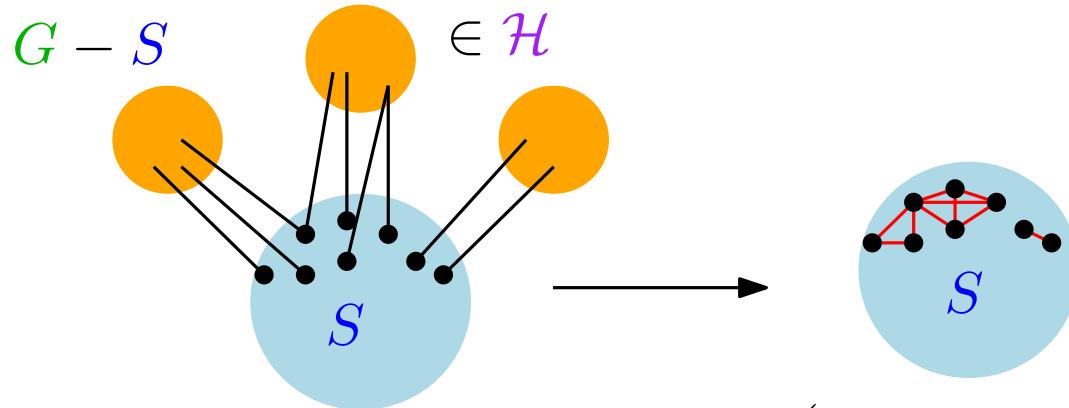
Step 4



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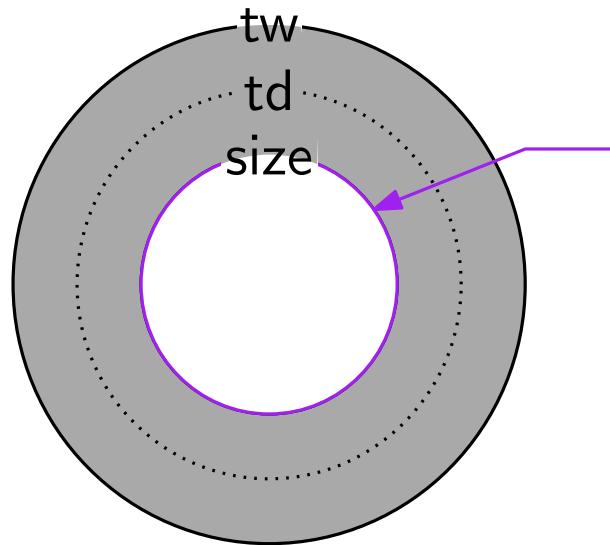
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\mathcal{H} -td \rightarrow ELIMINATION DISTANCE TO \mathcal{H} [Bulian, Dawar, '16]

\mathcal{H} -tw \rightarrow \mathcal{H} -TREEDWIDTH [Eiben, Ganian, Hamm, Kwon, '21]

for each G , $\text{tw}(G) \leq \text{td}(G) \leq \text{size}(G)$

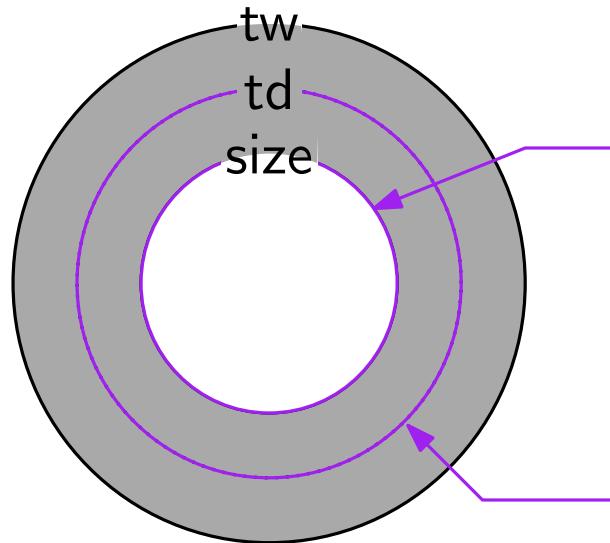


VERTEX DELETION TO \mathcal{H}

[Morelle, Sau, Stamoulis, Thilikos]

$2^{\text{poly}_{\mathcal{H}}(k)} \cdot n^2$ \leftarrow \mathcal{H} minor-closed

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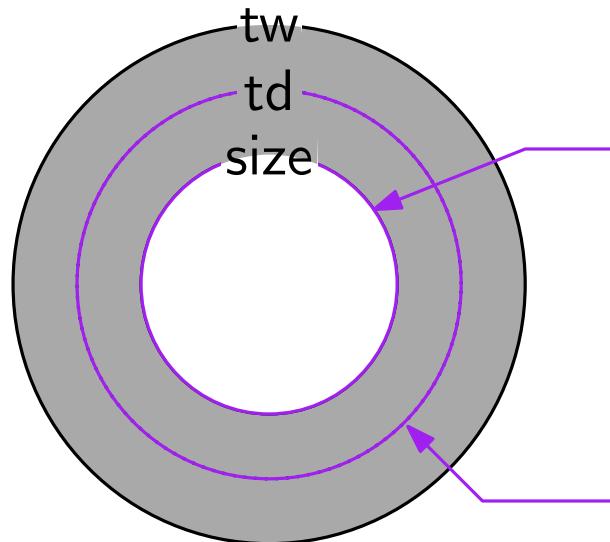
[Robertson, Seymour, '04] + [Bulian, Dawar, '17] +

[Kawarabayashi, Kobayashi, Reed, '12]

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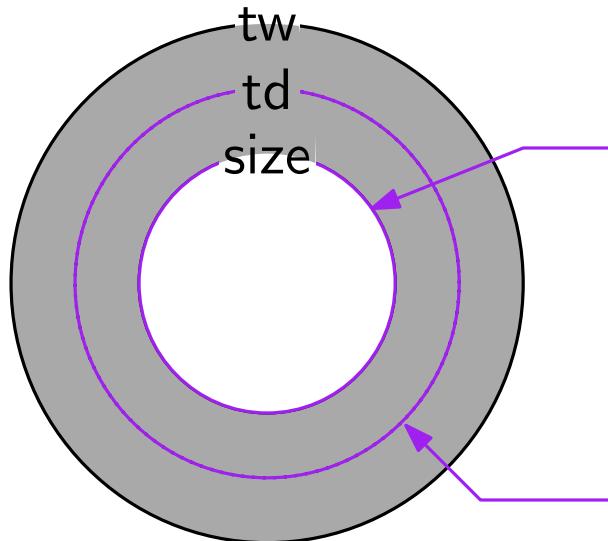
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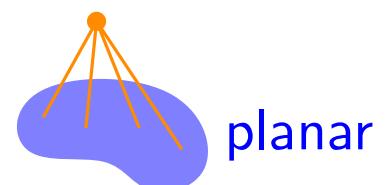
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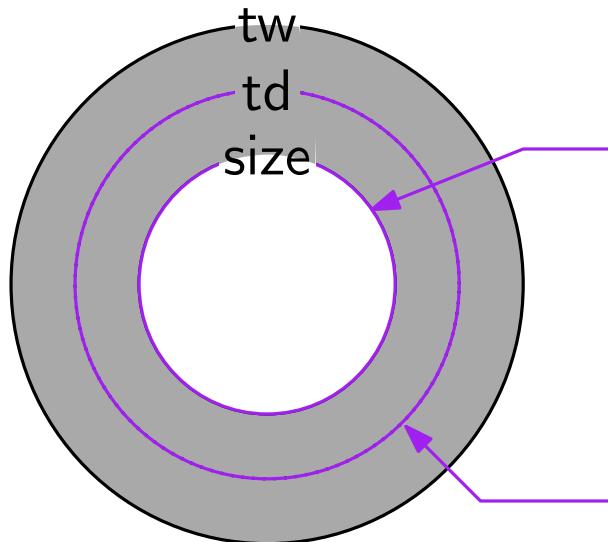
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as a minor



for each G , $\text{tw}(G) \leq \text{td}(G) \leq \text{size}(G)$



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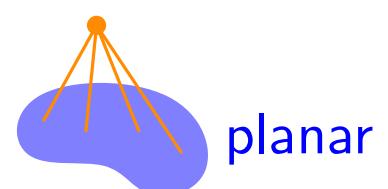
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Sketch of the proof for VERTEX DELETION TO \mathcal{H} :

Win/Win strategy on the **treewidth** $\text{tw}(G)$ of G :

If G has **big** treewidth:

then G contains a **big grid** as a minor.

If there is a **big flow** from a set A to the grid:

then $A \cap S \neq \emptyset$ “obligatory set”

Branching step: guess $v \in A$ s.t. $v \in S$ and recurse on $(G - v, k - 1)$.

Otherwise there is a **small flow** to the grid:

then G contains a **“flat wall”**

Irrelevant vertex technique: there is a vertex v in the wall s.t. (G, k) and $(G - v, k)$ are equivalent instances. “irrelevant vertex”

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→ new dynamic programming $2^{\mathcal{O}(k \cdot \text{tw} + \text{tw} \log \text{tw})} \cdot n$

Representative-based technique [Baste, Sau, Thilikos , '19]

17 - 3 DP for treedepth [Reidl, Roszmanith, Villaamil, Sikdar, '14]

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Is there a vertex set S s.t. $\text{td}(\text{torso}(G, S)) \leq k$ and the components of $G - S$ are in \mathcal{H} ?

Sketch of the proof

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17 - 5 DP for treedepth [Reidl, Roszmanith, Villaamil, Sikdar, '14]

Sketch of the proof

$$2^{2^{2^{\text{poly}} \mathcal{H}(k)}} \cdot n^2$$

Win/Win strategy on the **treewidth** $\text{tw}(G)$ of G :

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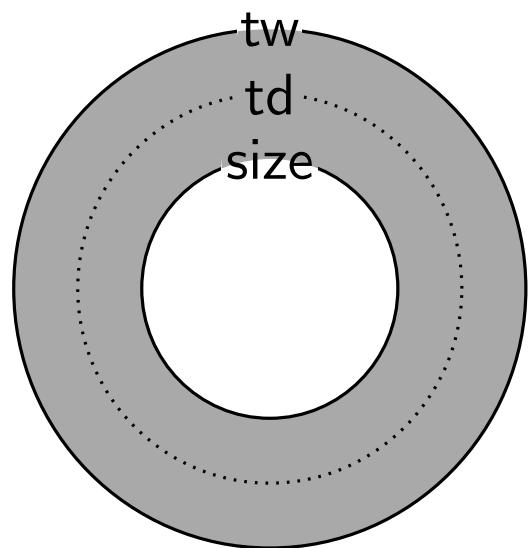
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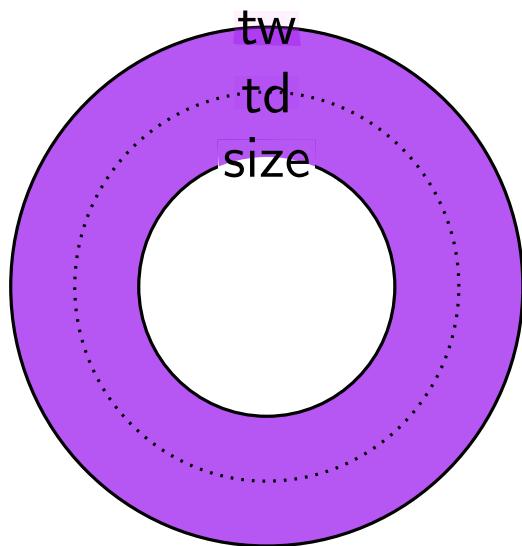
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Limit of the irrelevant vertex technique



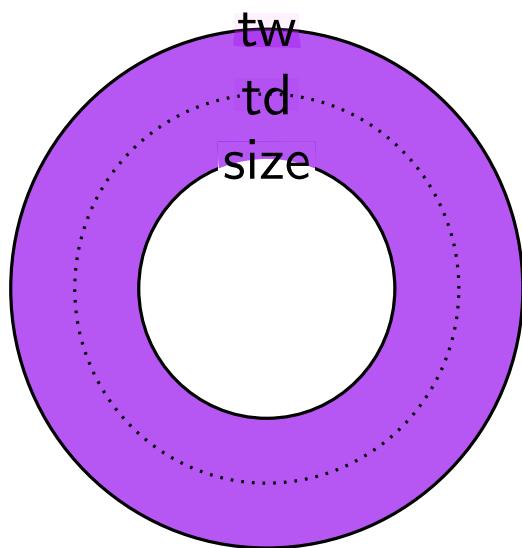
Limit of the irrelevant vertex technique



[Fomin, Golovach, Sau, Stamoulis, Thilikos, '23]

For \mathcal{H} minor-closed, the irrelevant vertex technique works for any parameter $\mathcal{H}\text{-}p$ such that $\text{size} \geq p \geq \text{tw}$.

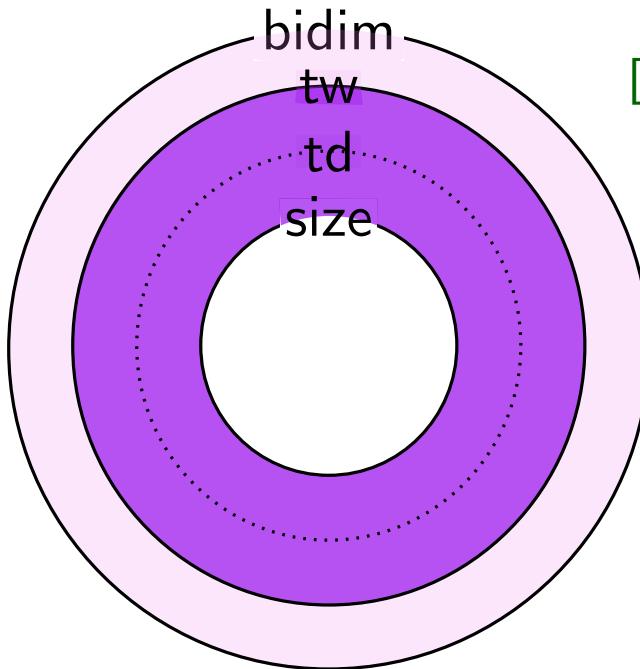
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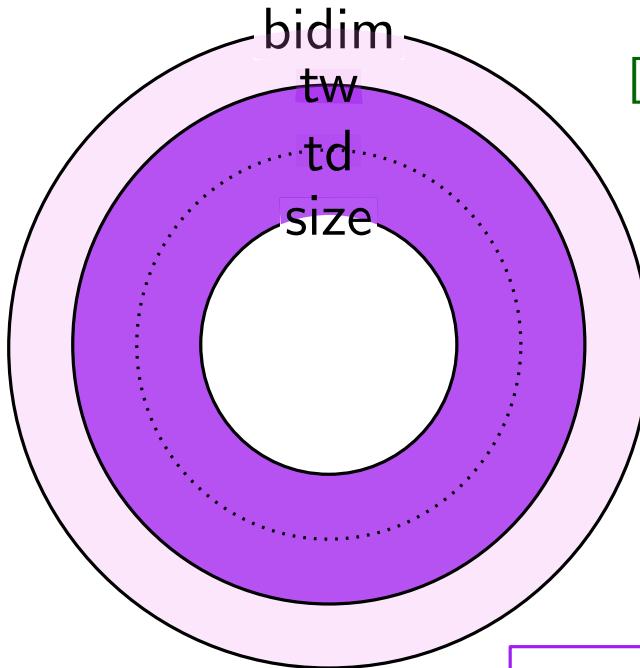
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For \mathcal{H} minor-closed, the irrelevant vertex technique works up to modulators of bounded **bidimensionality**.

Limit of the irrelevant vertex technique



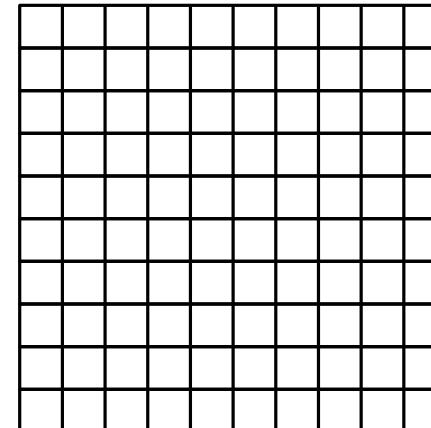
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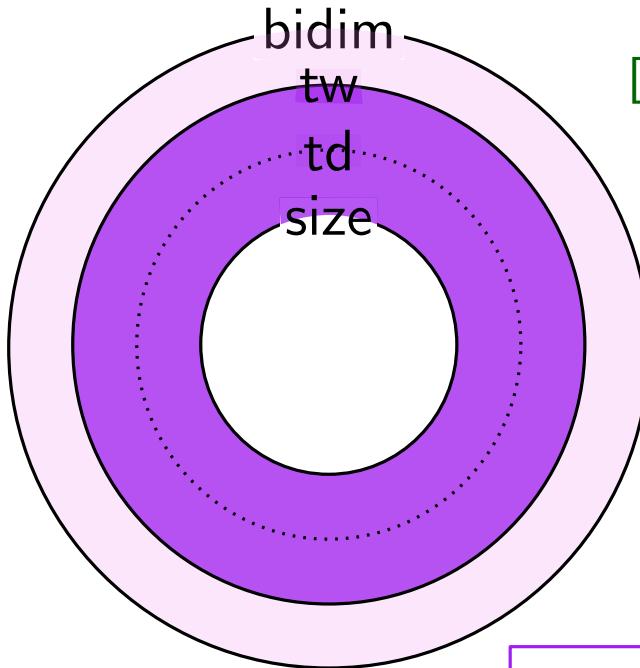
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$\text{bidim}(G, S) =$
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Limit of the irrelevant vertex technique



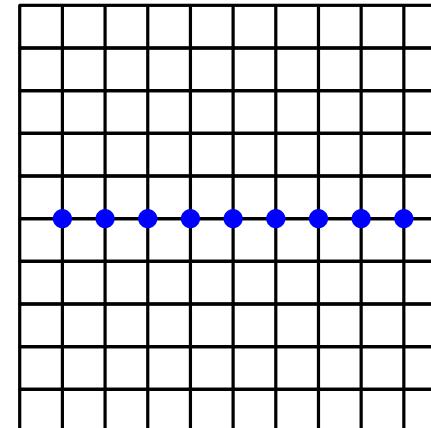
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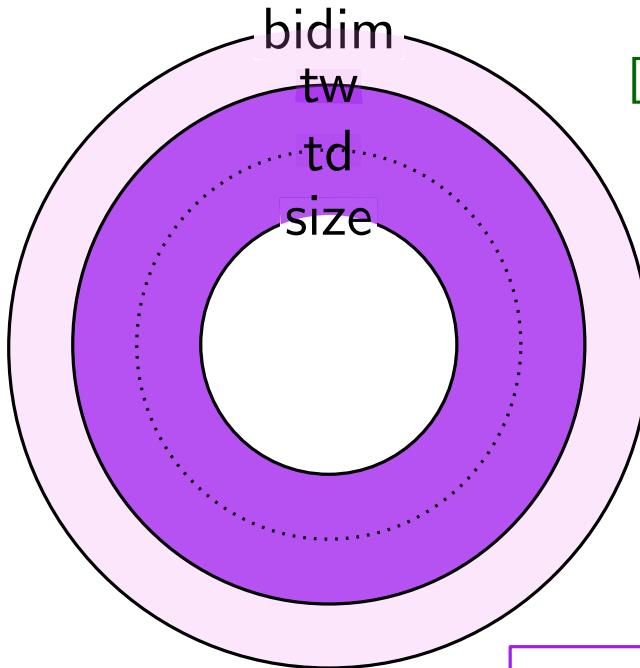
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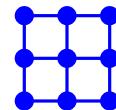
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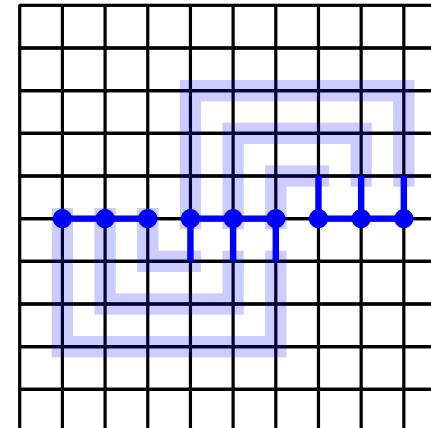
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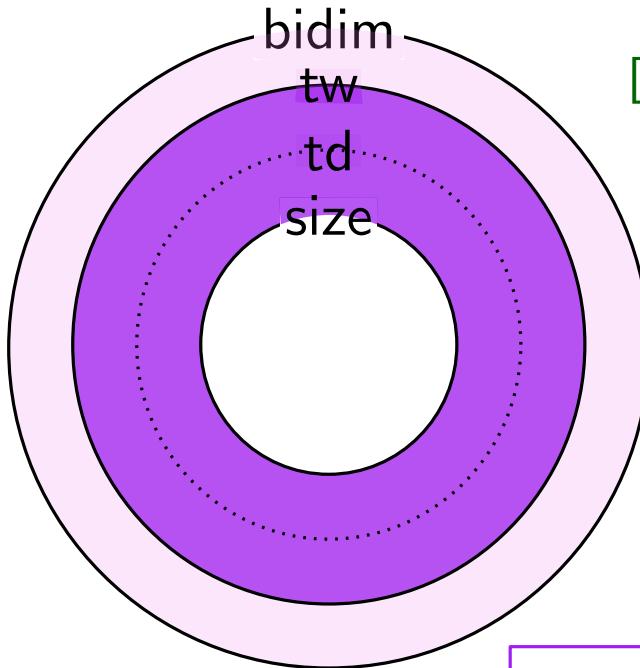
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$\text{bidim}(G, S) = k$



Limit of the irrelevant vertex technique



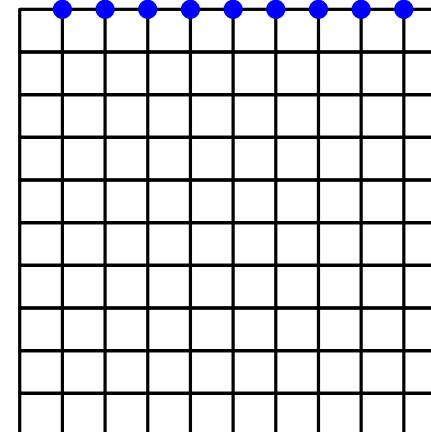
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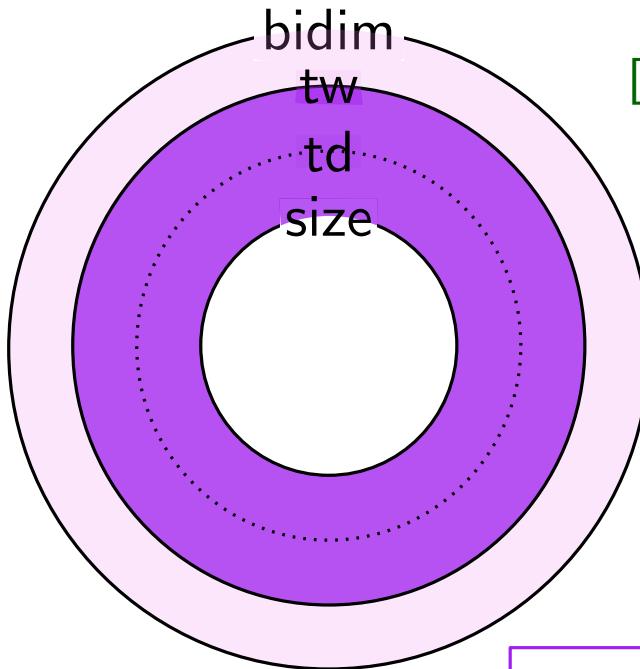
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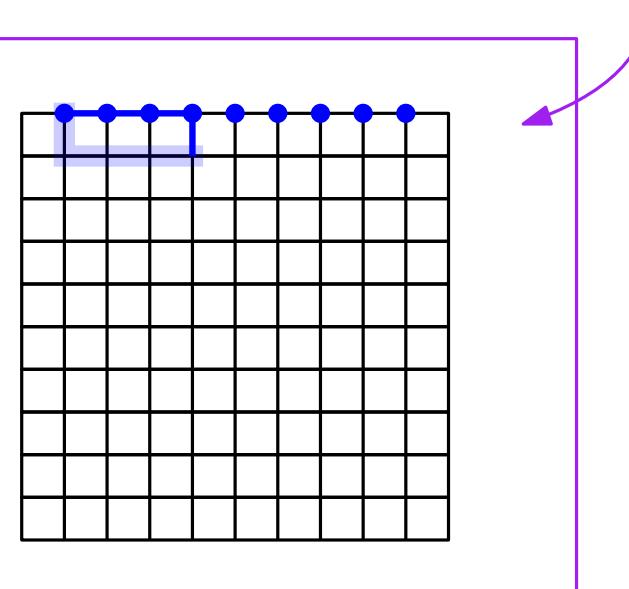
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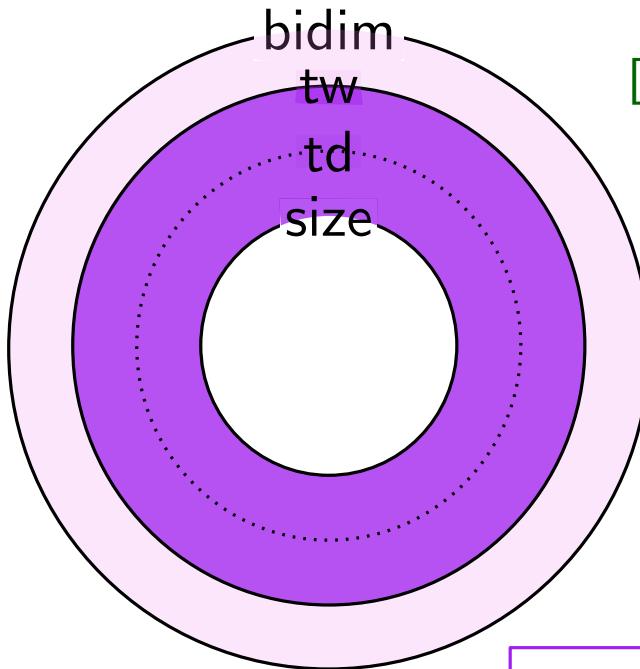
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$\text{bidim}(G, S) =$
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$\text{bidim}(G, S) = 2$



Limit of the irrelevant vertex technique



[Fomin, Golovach, Sau, Stamoulis, Thilikos, '23]

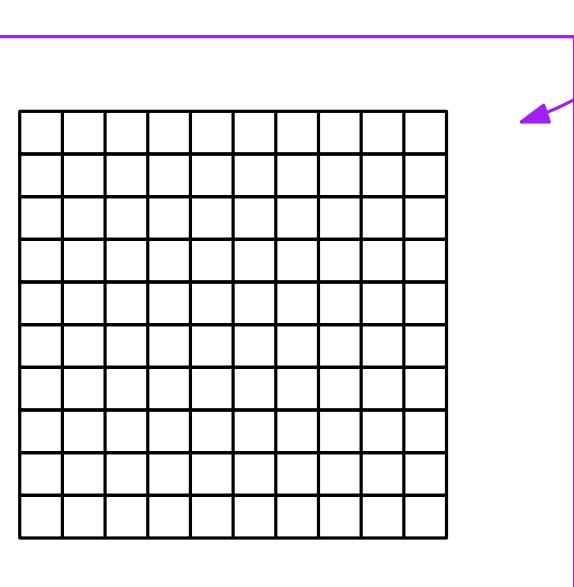
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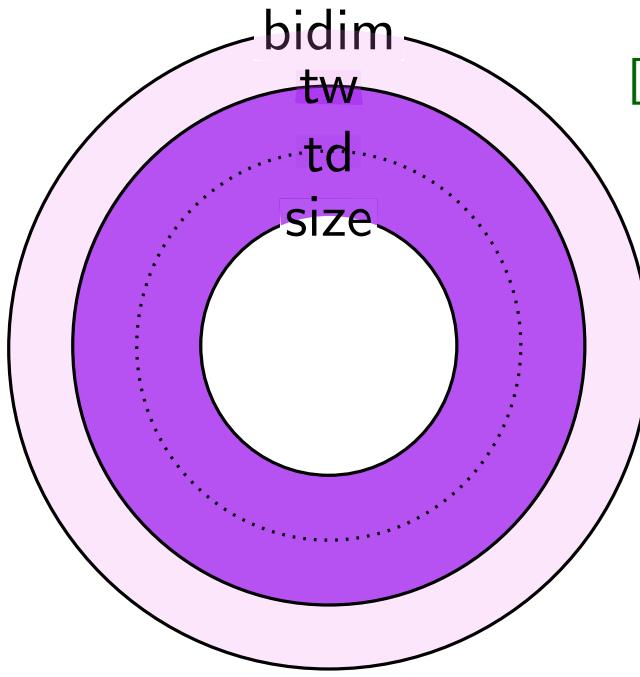
For \mathcal{H} minor-closed, the irrelevant vertex technique works up to modulators of bounded bidimensionality.

$\text{bidim}(G, S) =$
max treewidth of an
 S -minor of G .

“max size of a grid
grasped by S ”



Limit of the irrelevant vertex technique



[Fomin, Golovach, Sau, Stamoulis, Thilikos, '23]

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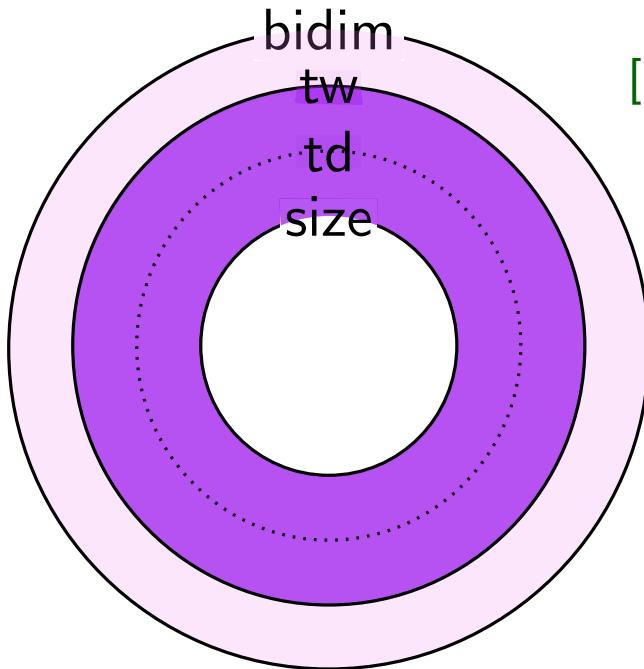


Any **graph modification problem** where:

- the **modulator** has bounded bidimensionality
- the **target class** is minor-closed
- the set of allowed **modifications** is expressible in CMSO logic

can be solved in time $f(k) \cdot n^2$, for some computable f .

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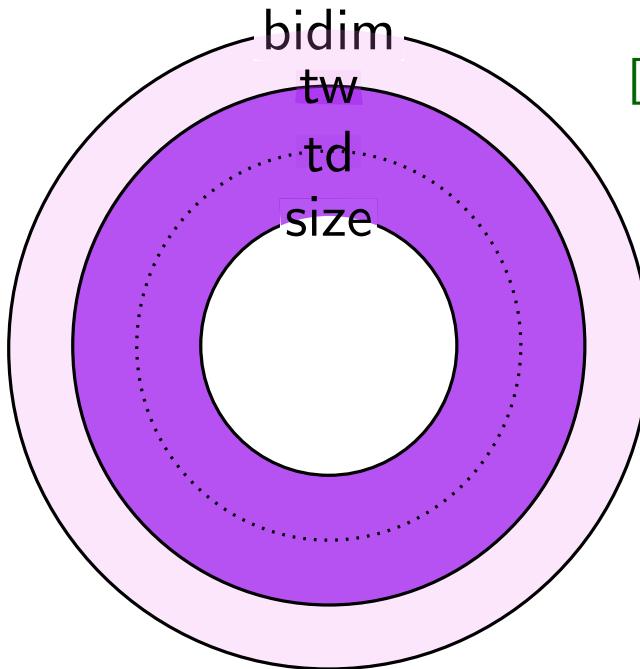
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variables v, e, V, E
quantifiers \forall, \exists
connectives $\wedge, \vee, \Rightarrow, \neg, \in$
relations $\text{inc}(\cdot), |\cdot| = q \pmod r$

Limit of the irrelevant vertex technique



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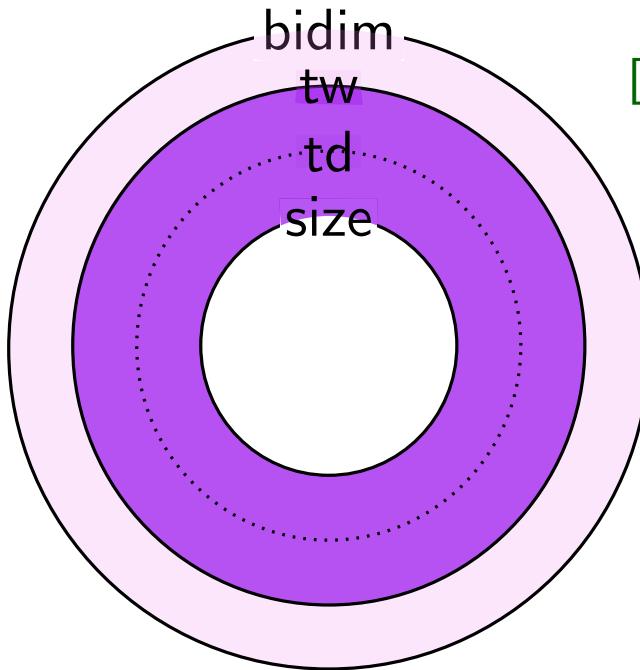
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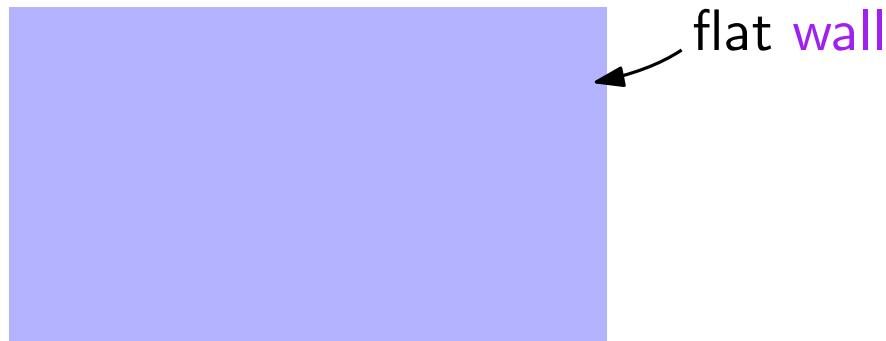
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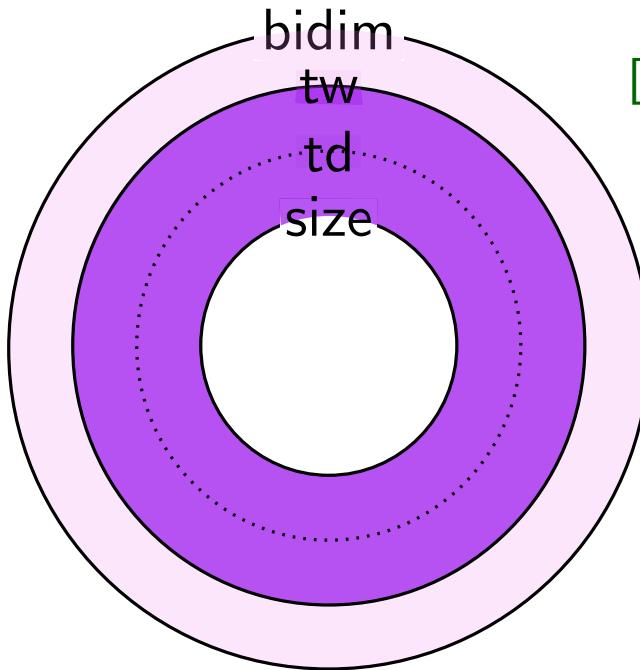
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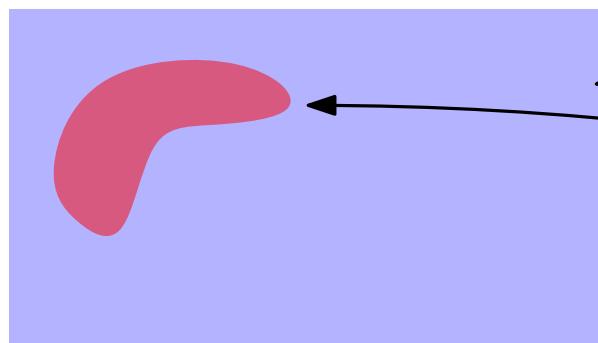
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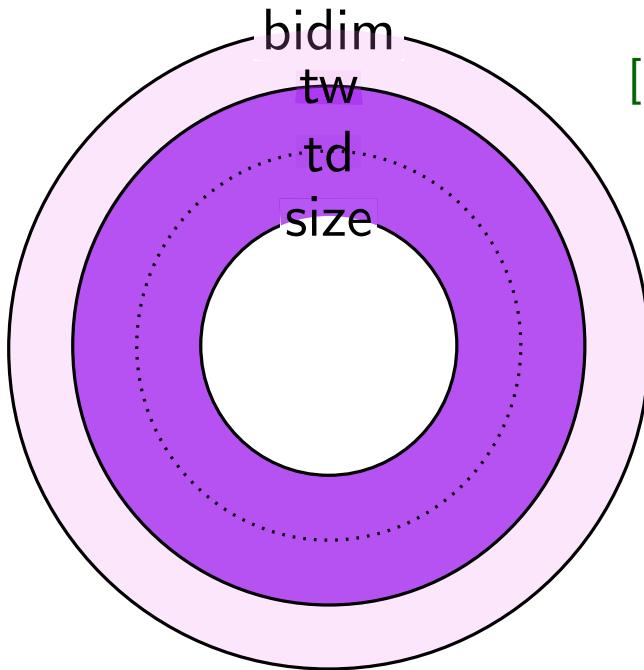
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flat wall

no matter how we delete/modify the modulator

Limit of the irrelevant vertex technique



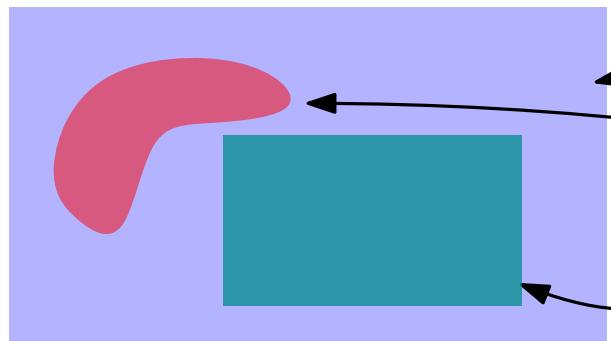
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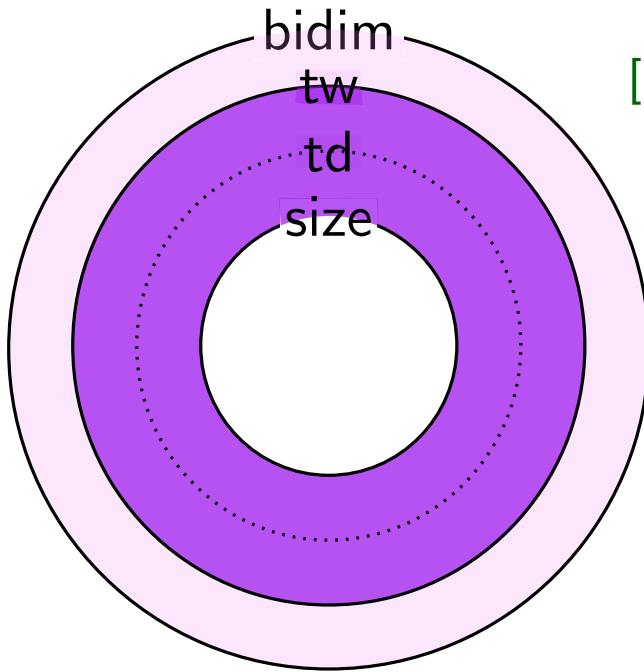


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Limit of the irrelevant vertex technique



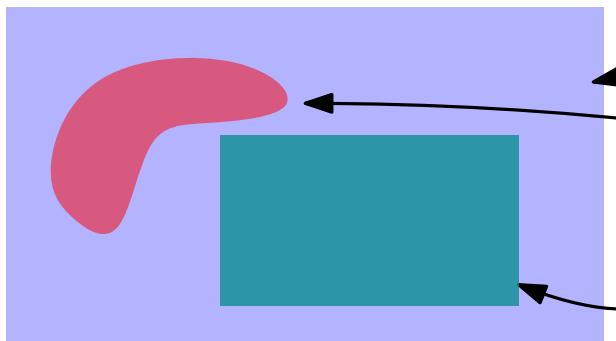
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Breaking the limit

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How to solve a graph modification problem where the modulator has unbounded bidimensionality?

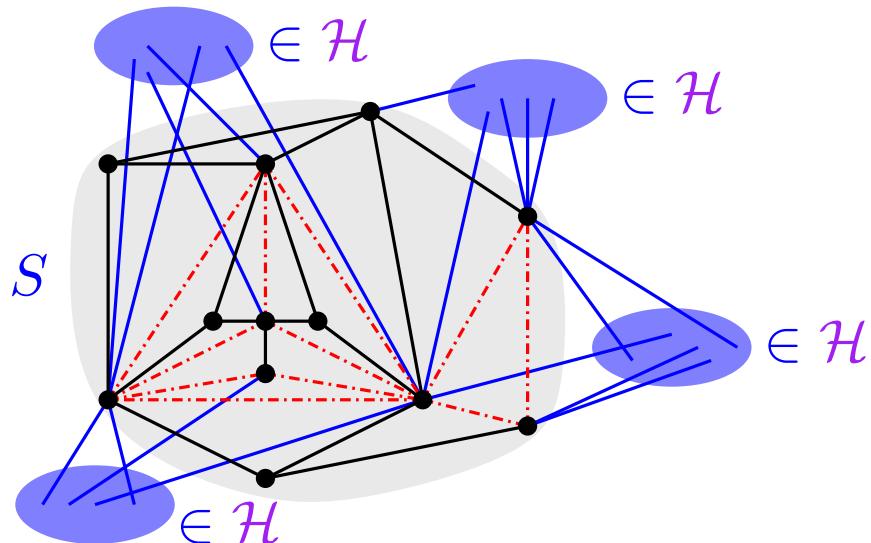
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\mathcal{H} -PLANARITY

Input: A graph G .

Output: Is there a vertex set S whose torso is **planar** and s.t. the connected components of $G - S$ are in \mathcal{H} ?



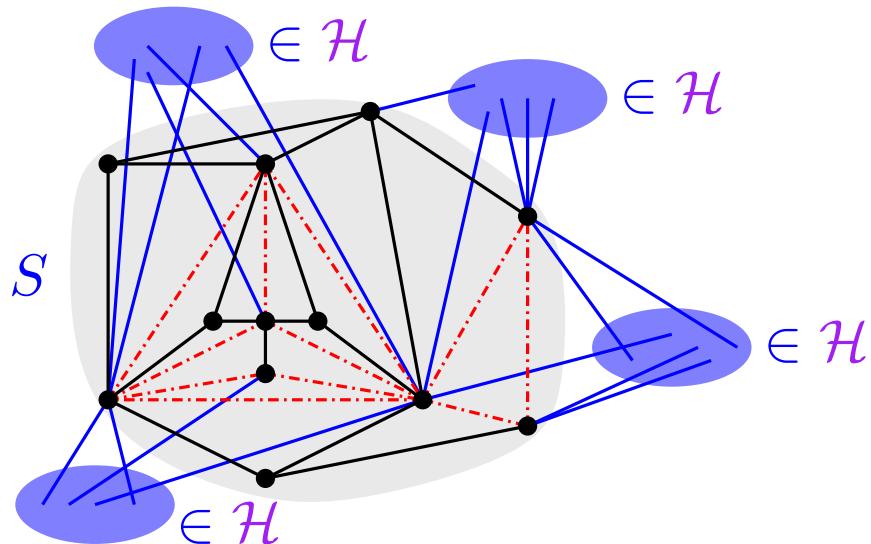
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If \mathcal{H} is hereditary, CMSO-definable, and decidable in time $\mathcal{O}(n^c)$, then \mathcal{H} -PLANARITY is solvable in time $\mathcal{O}(n^4 + n^c \log n)$.

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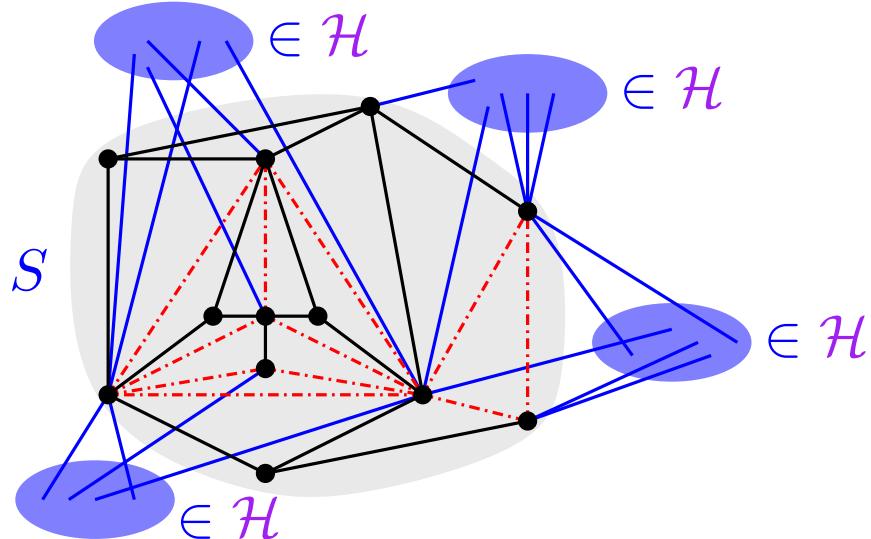
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if $G \in \mathcal{H}$, then $G - v \in \mathcal{H}$



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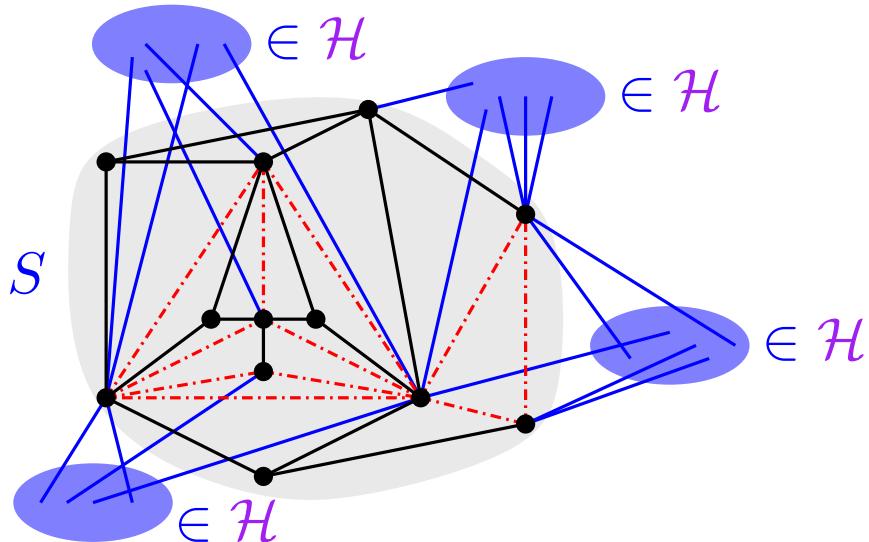
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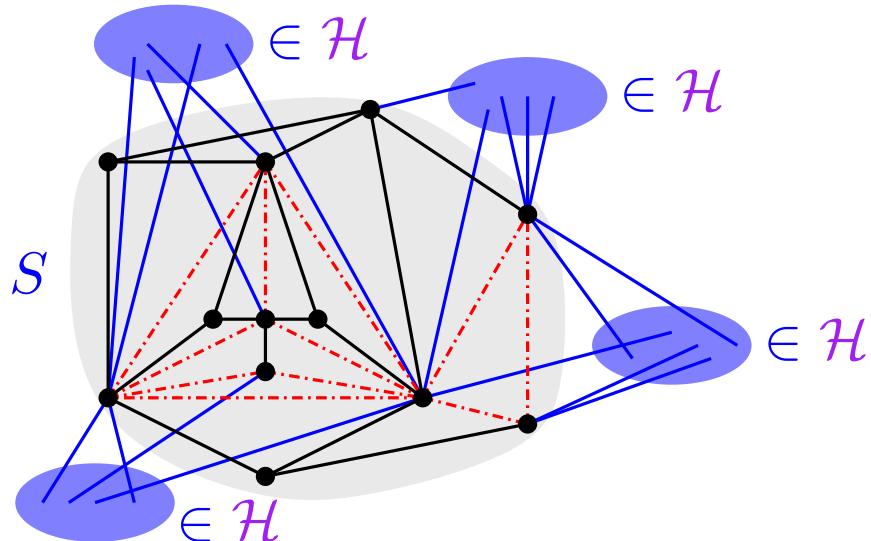
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→ new irrelevant vertex technique

Sketch of the proof

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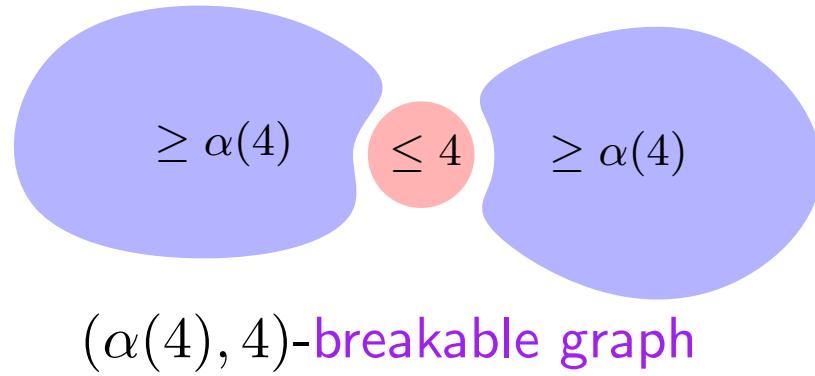
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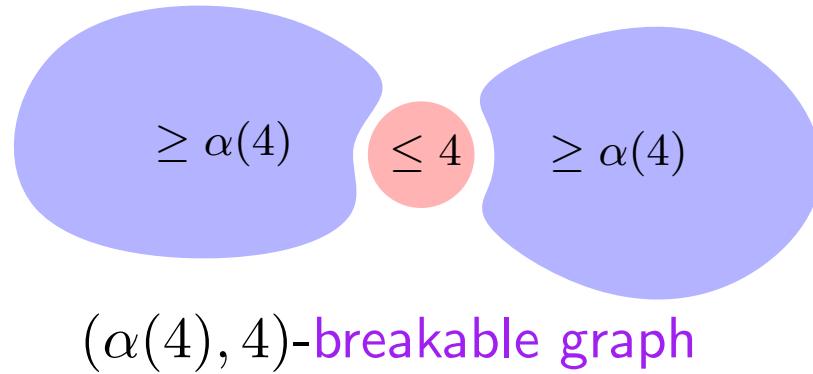
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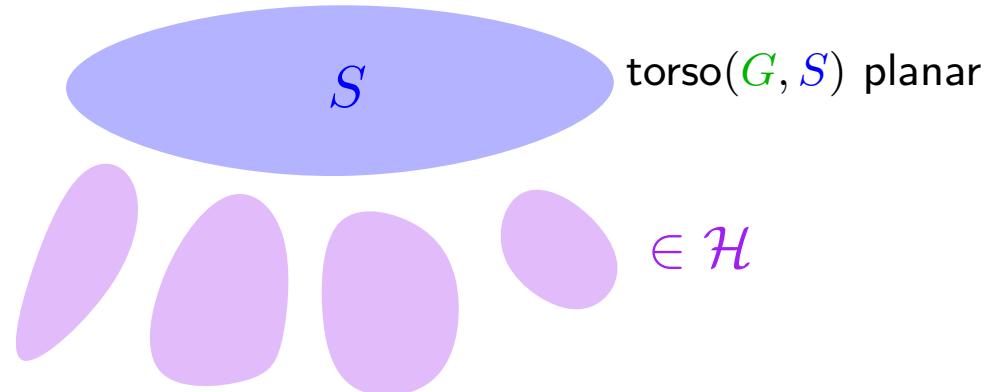
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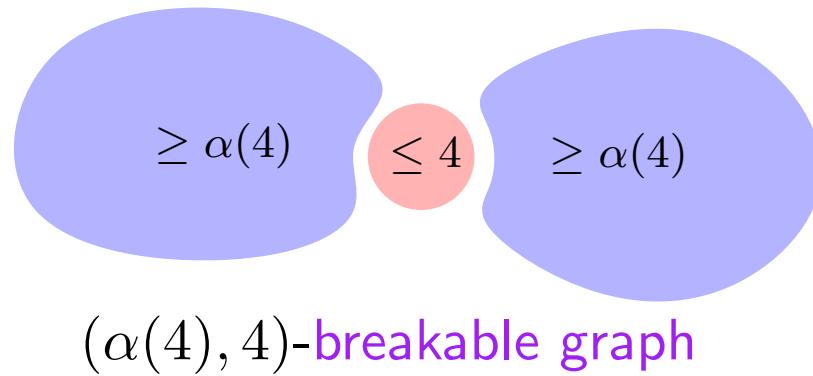
\mathcal{H} -planar graph



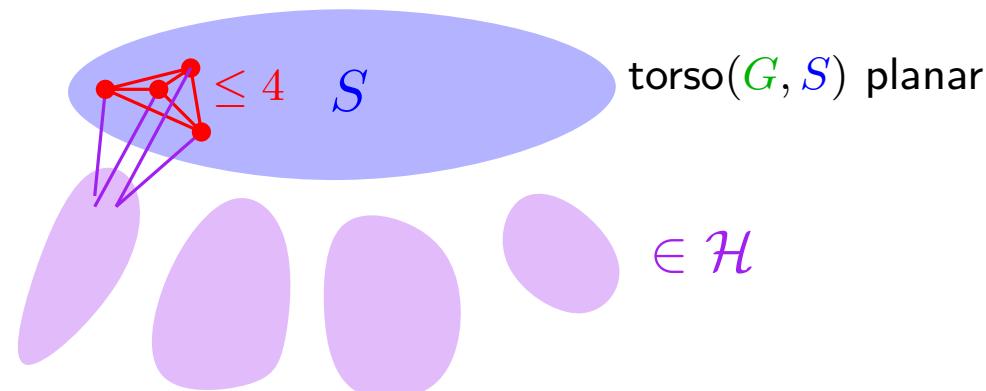
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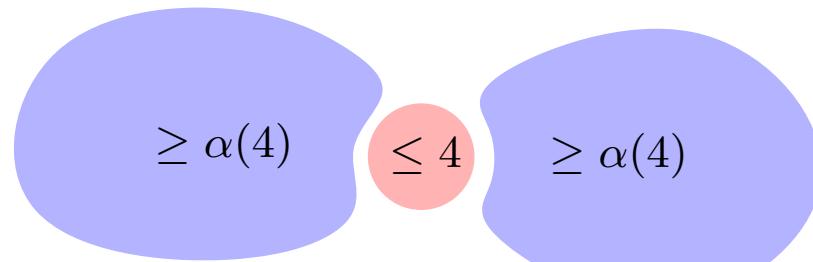
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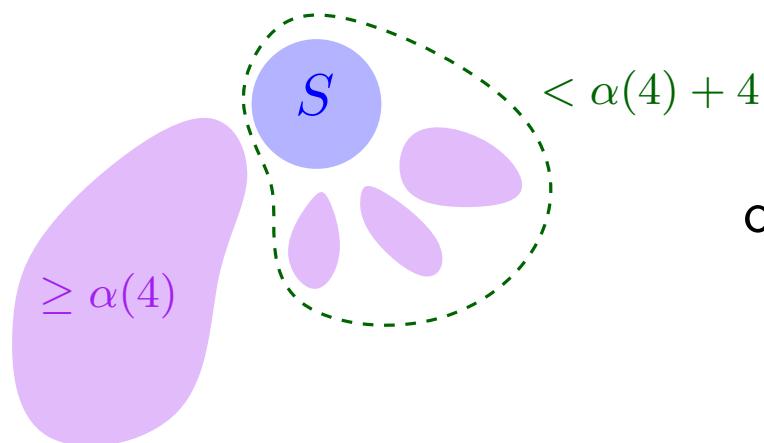
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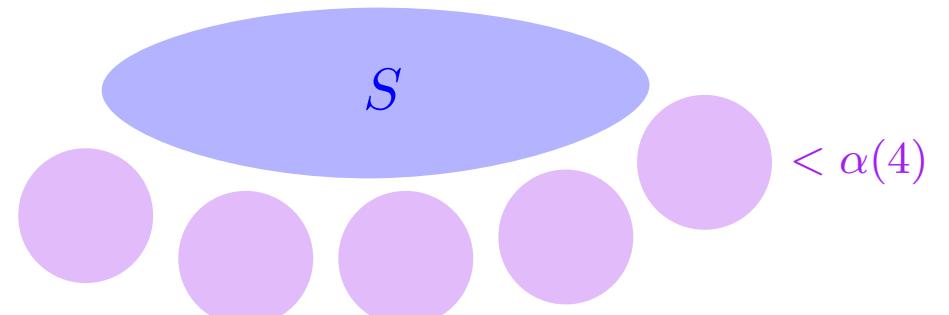
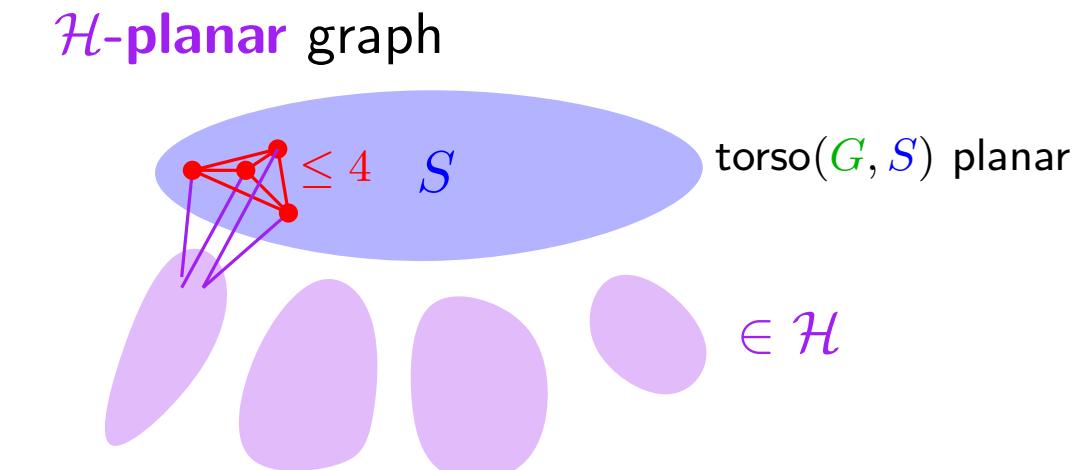
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$(\alpha(4), 4)$ -breakable graph



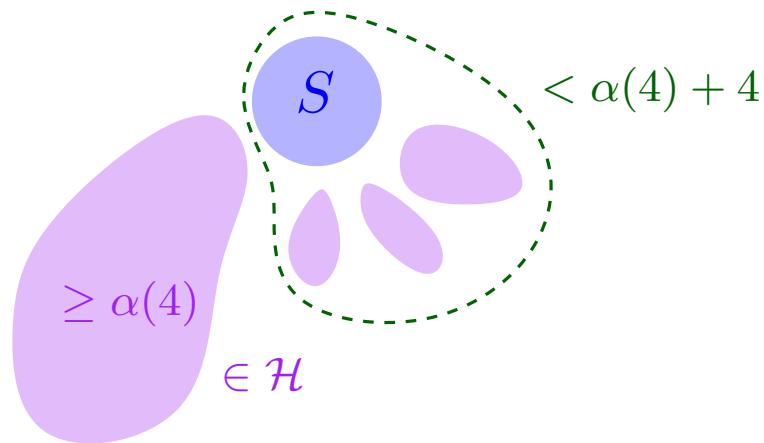
or



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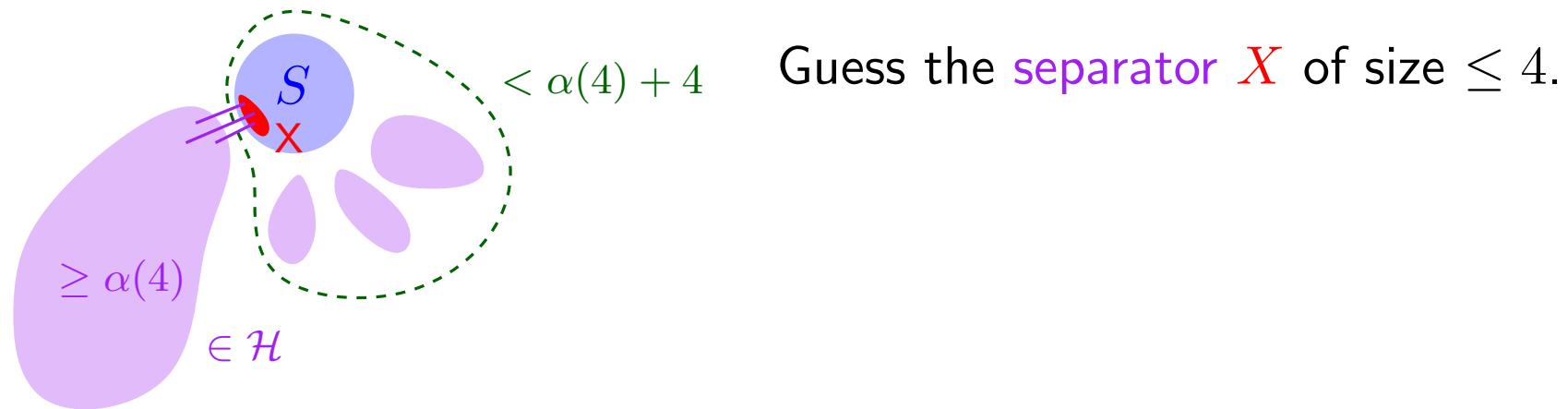
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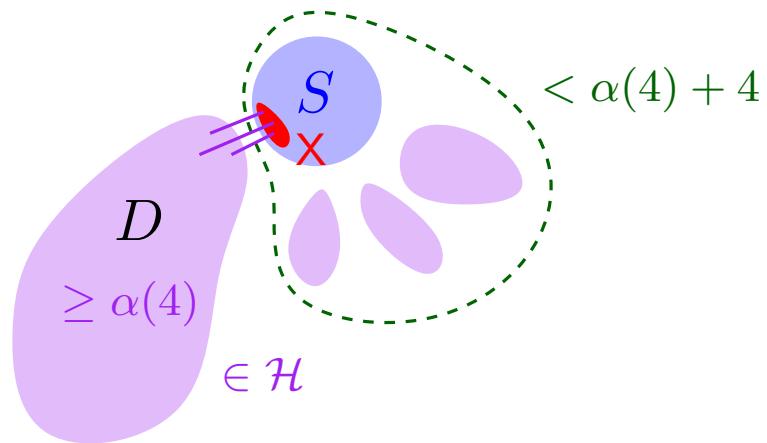
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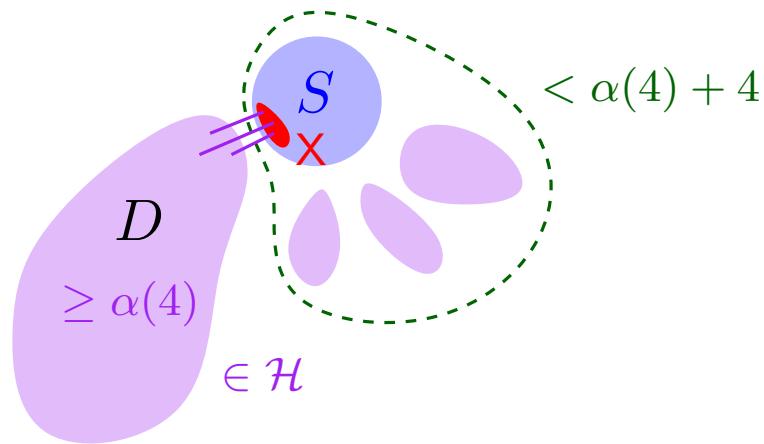
Guess the separator X of size ≤ 4 .

Check if there is a unique component D in $G - X$ of size $\geq \alpha(4)$.

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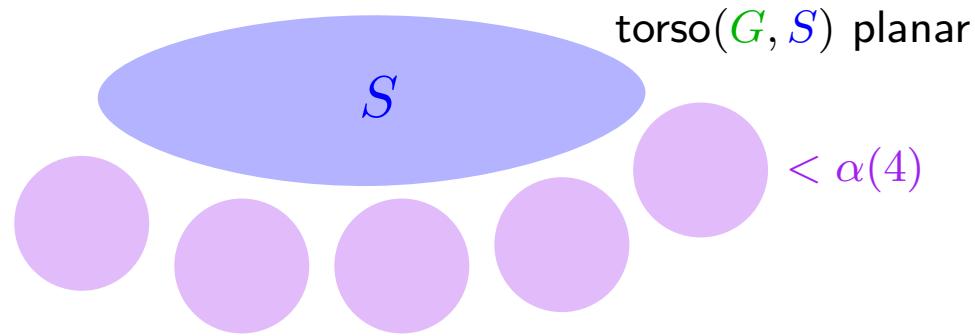


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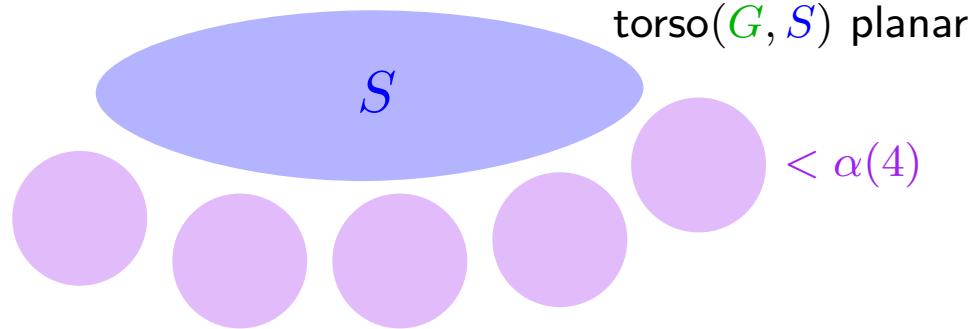
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Guess the set $S \supseteq X$ in $G - D$ and check if the torso of S is planar and if the components of $G - S$ are in \mathcal{H} .

Sketch of the proof

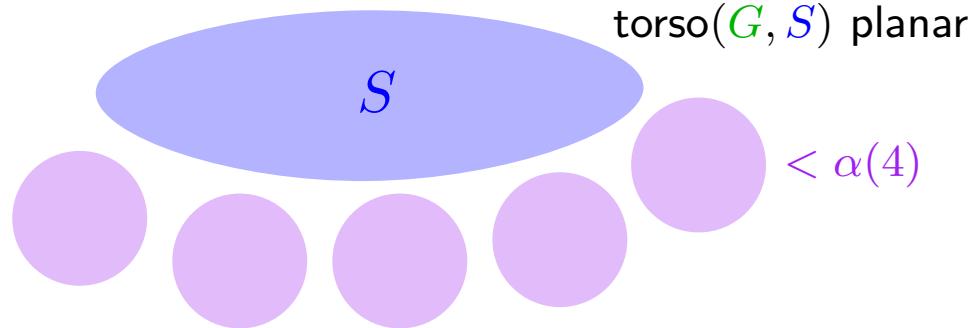


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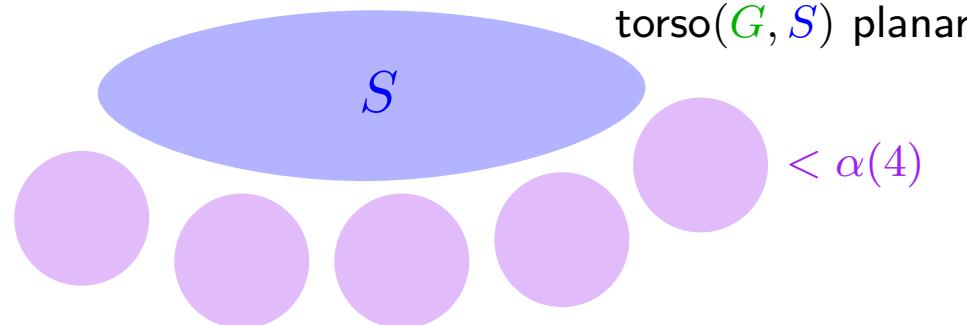
SMALL-LEAVES \mathcal{H} -PLANARITY

Sketch of the proof



SMALL-LEAVES \mathcal{H} -PLANARITY
Restate the problem

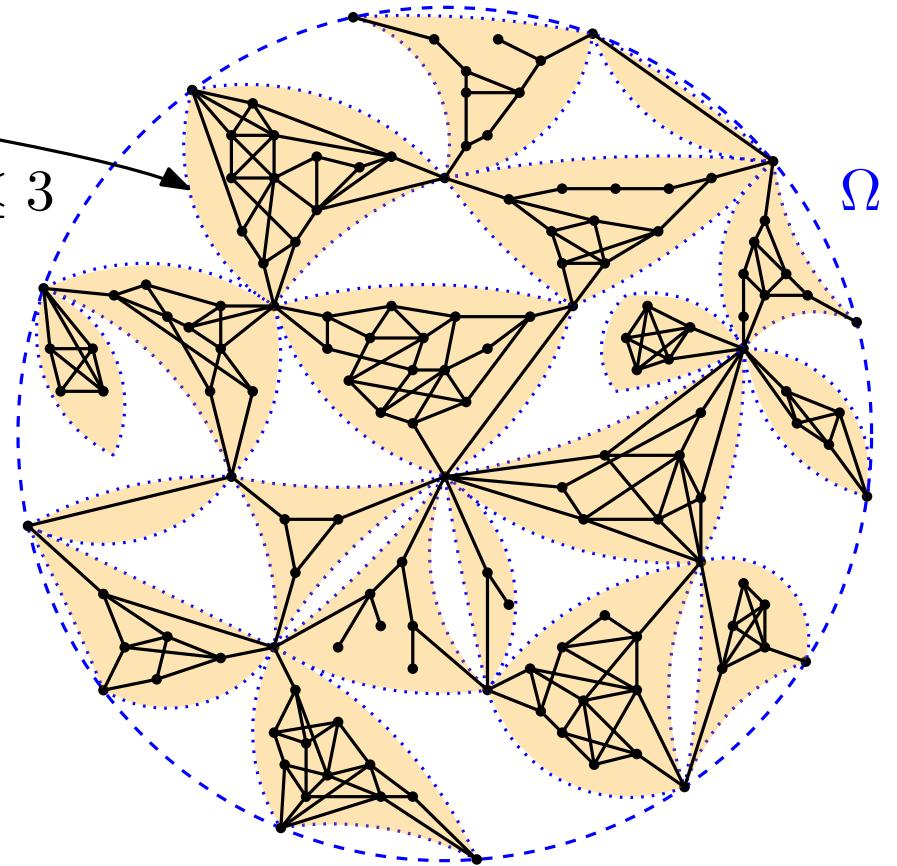
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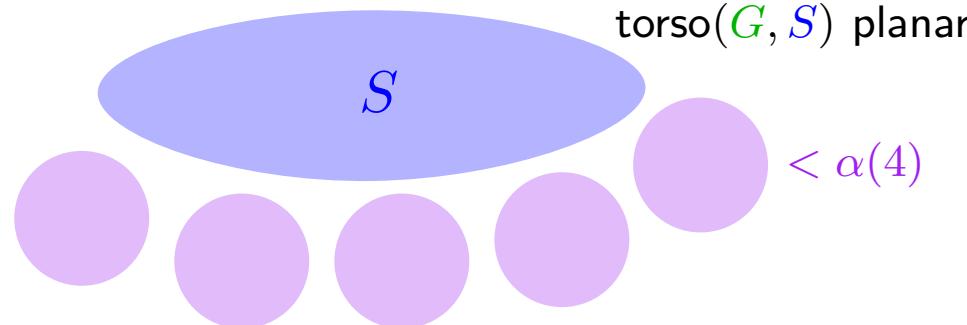
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Restate the problem

Rendition of (G, Ω)

cell
boundary ≤ 3



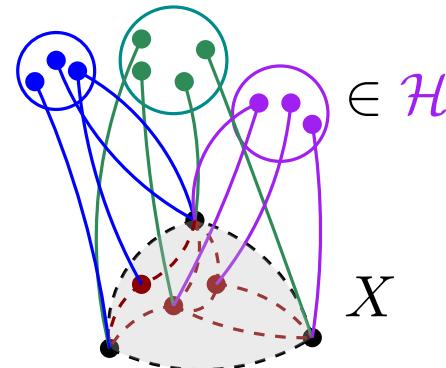
Sketch of the proof



G is a yes-instance

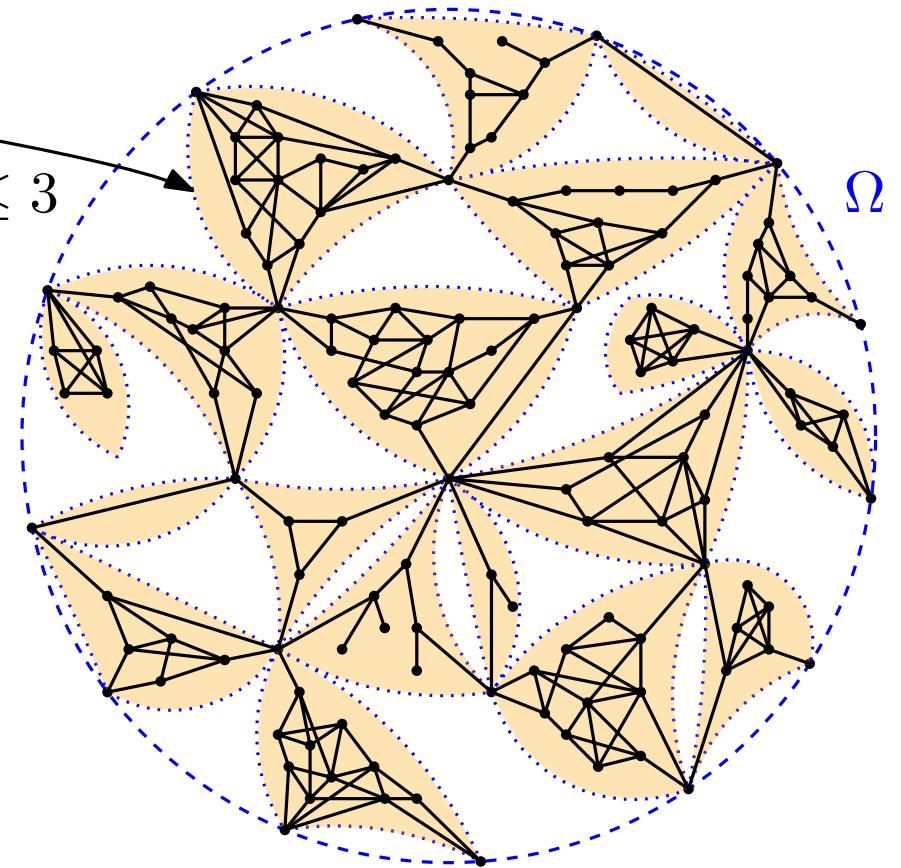
\Leftrightarrow

G has a rendition whose cells are **\mathcal{H} -compatible**.

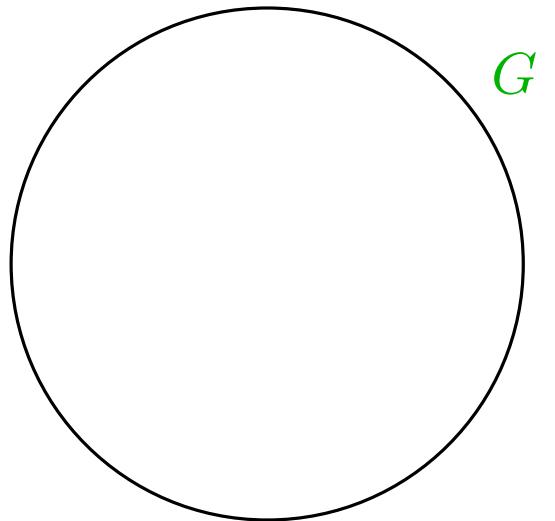


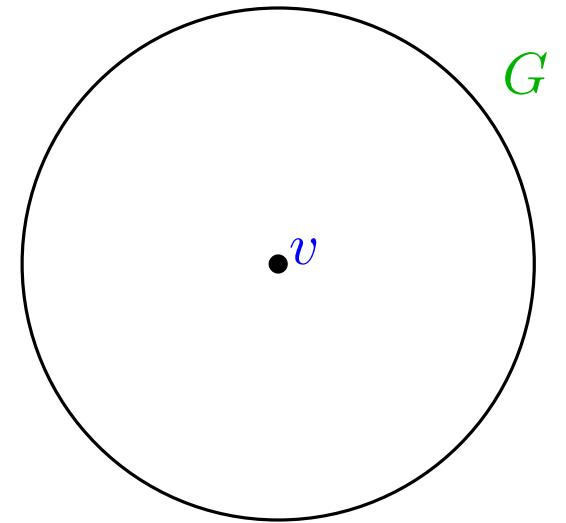
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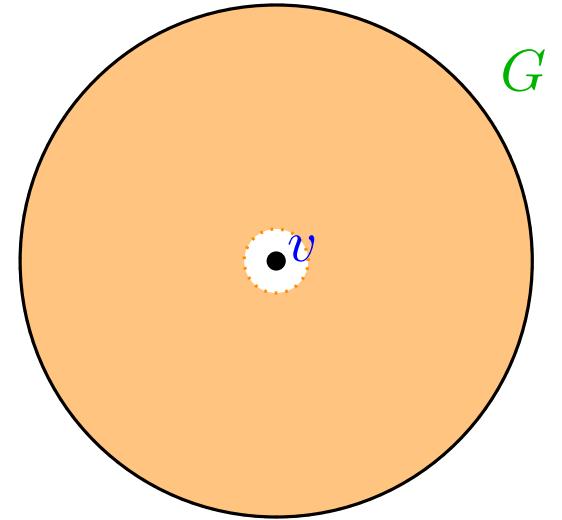
Idea:





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Pick a vertex v .

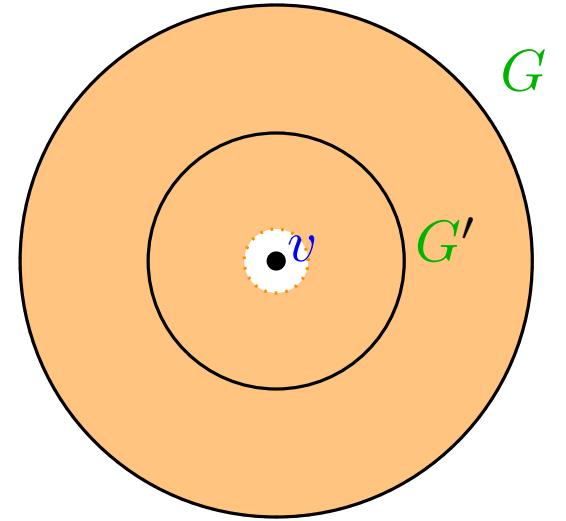


Idea:

Pick a vertex v .

Solve recursively on $G - v$.

Rendition ρ_1 of $G - v$ whose cells are \mathcal{H} -compatible.



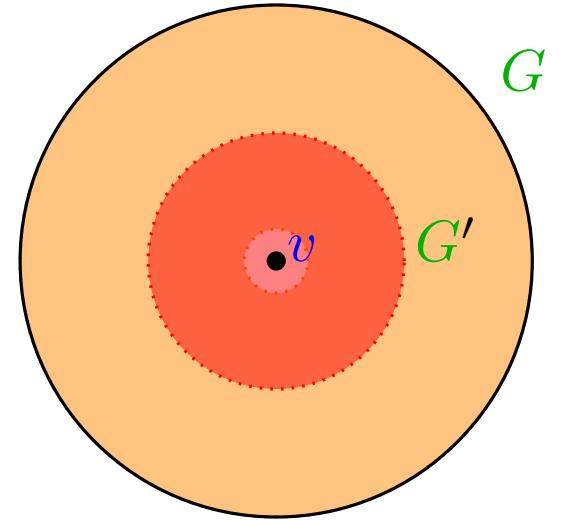
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Take a region G' around v of small treewidth.



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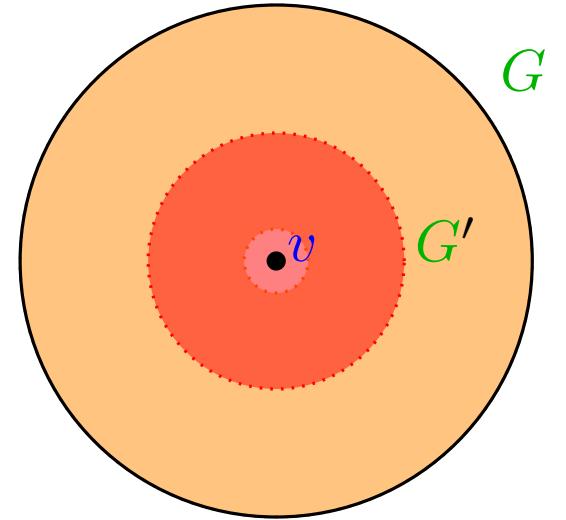
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Solve on G' . [Courcelle, '90]

Rendition ρ_2 of G' whose cells are \mathcal{H} -compatible.



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Solve recursively on $G - v$.

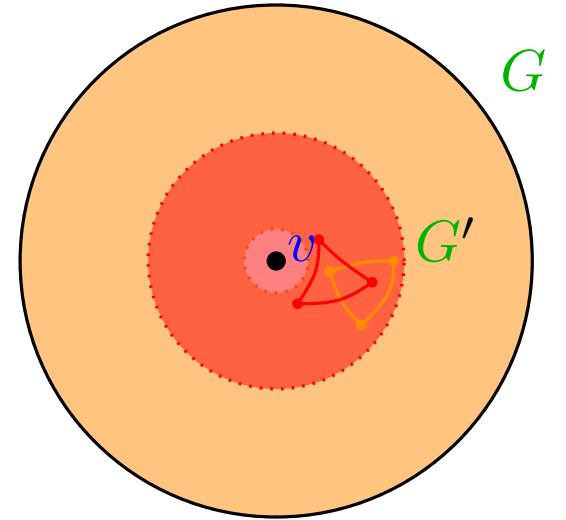
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Rendition ρ_2 of G' whose cells are \mathcal{H} -compatible.

→ want to combine ρ_1 and ρ_2 into a rendition of G whose cells are \mathcal{H} -compatible.



Idea:

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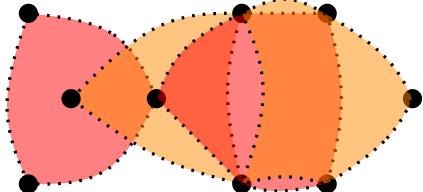
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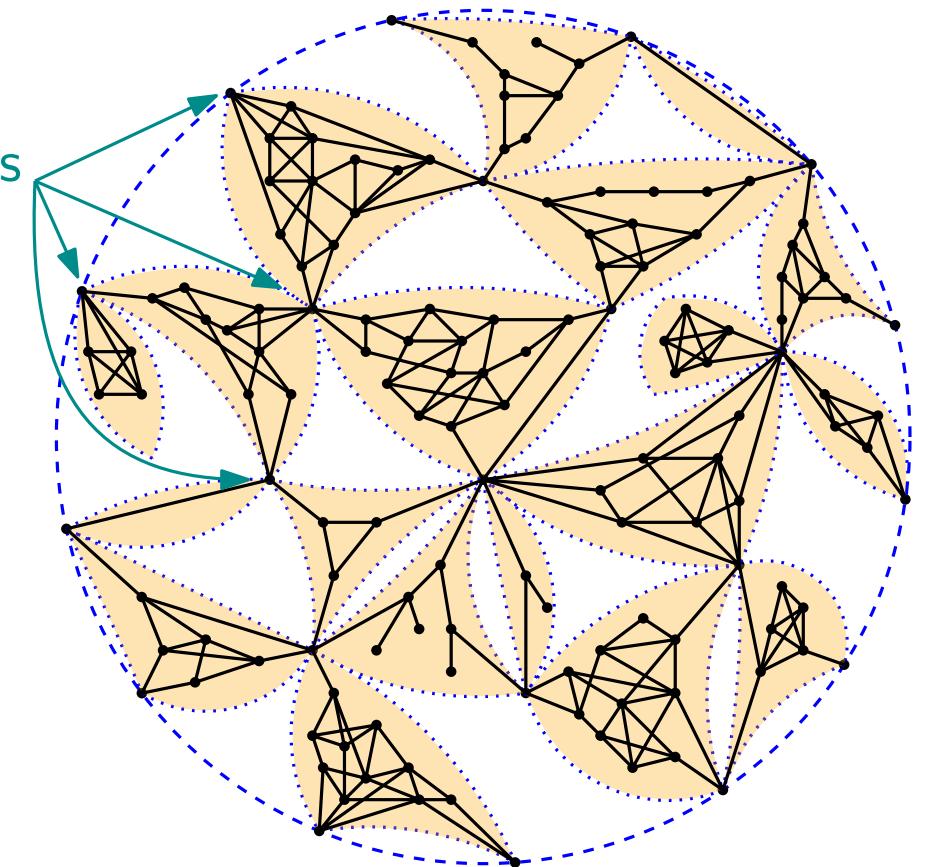
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Problem: How to glue correctly?

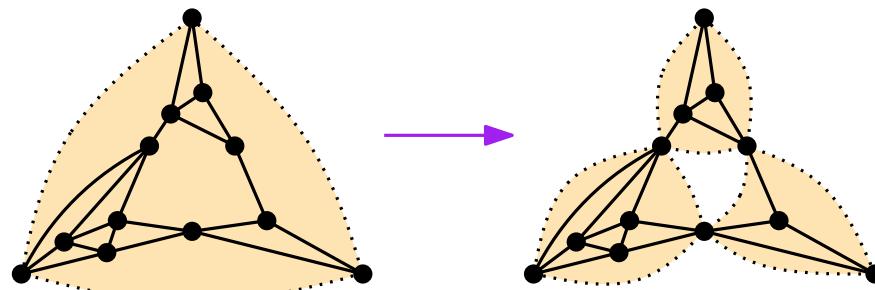


no “canonical rendition” of a graph

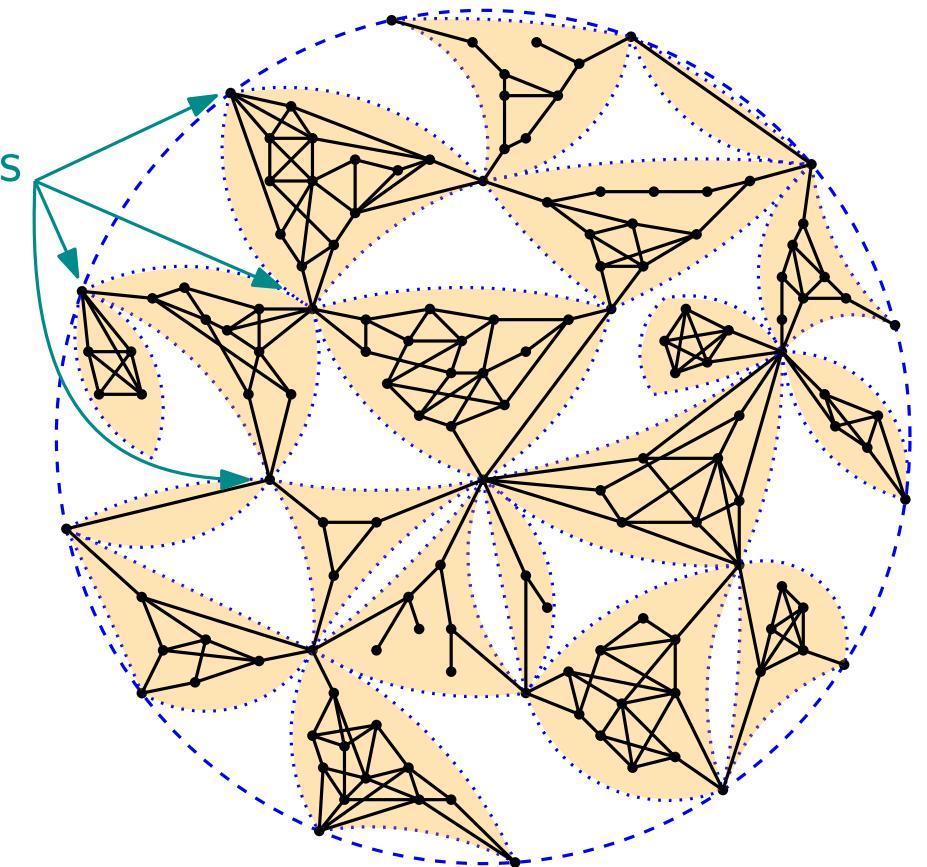
ground vertices



ground-maximal rendition:
cannot add more vertices to the ground

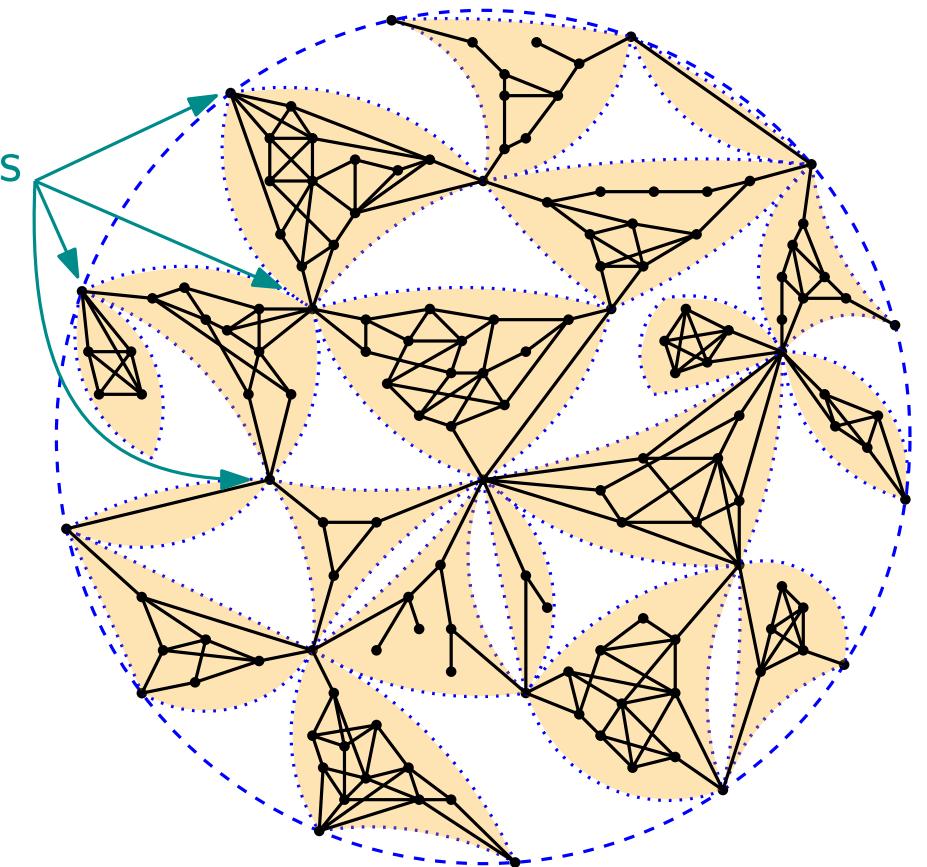
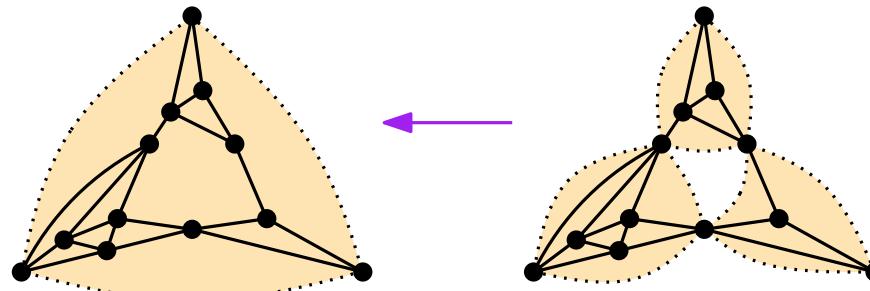


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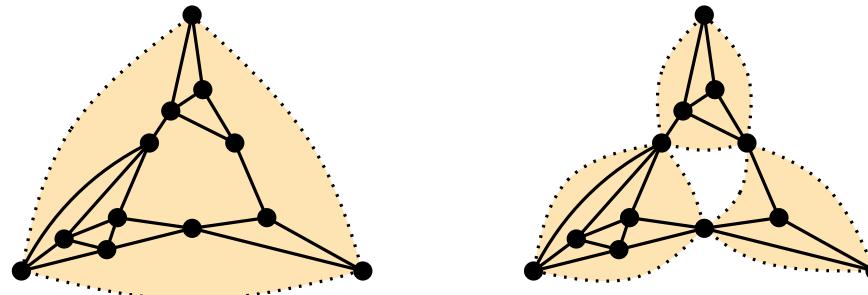
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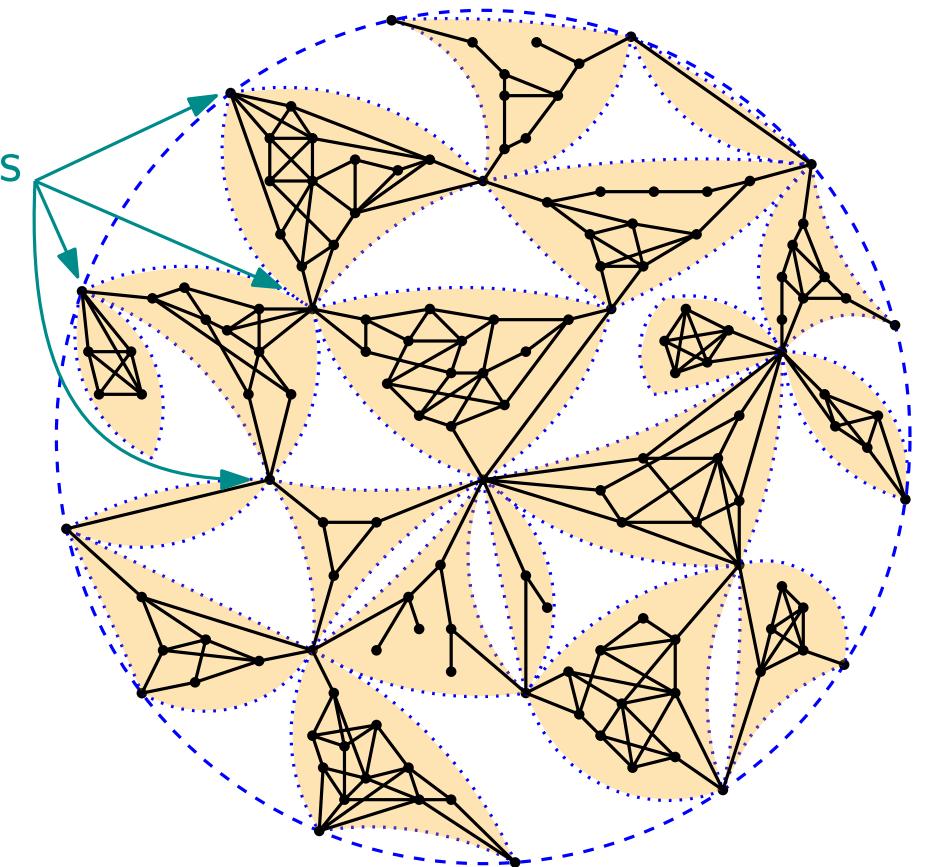


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ground-maximal rendition:
cannot add more vertices to the ground

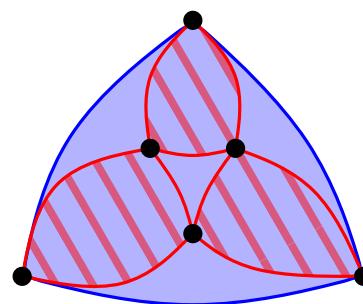


ground vertices



ground-minimal rendition:
cannot remove more vertices from the ground

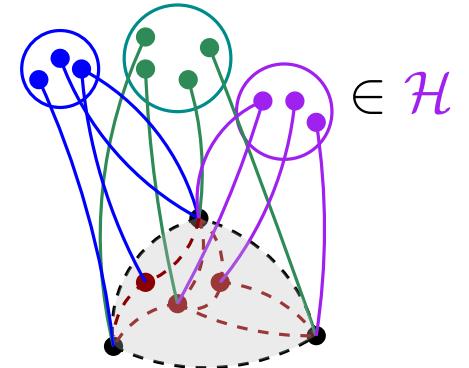
Every cell of **ground-maximal** rendition is **contained** in a cell of a **ground-minimal** rendition.



G is a **yes**-instance of SMALL-LEAVES \mathcal{H} -PLANARITY

\Leftrightarrow

G has a **rendition** whose cells are \mathcal{H} -**compatible**.



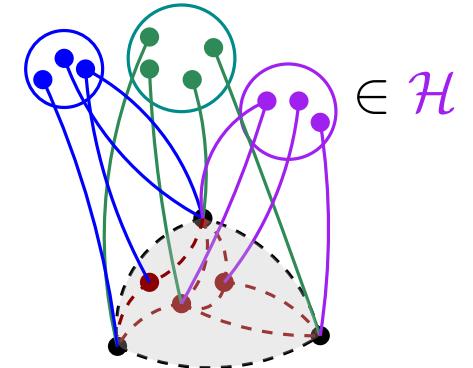
G is a yes-instance of SMALL-LEAVES \mathcal{H} -PLANARITY

\Leftrightarrow

G has a rendition whose cells are \mathcal{H} -compatible.

\Leftrightarrow

G has a ground-maximal rendition whose cells are \mathcal{H} -compatible.



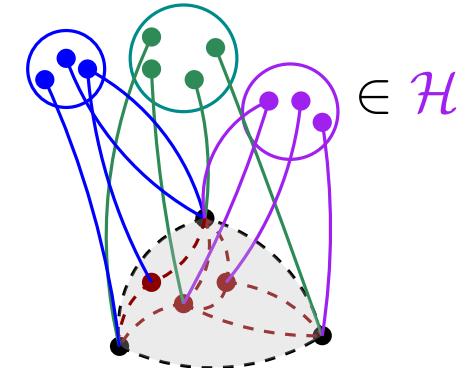
G is a **yes**-instance of SMALL-LEAVES \mathcal{H} -PLANARITY

\Leftrightarrow

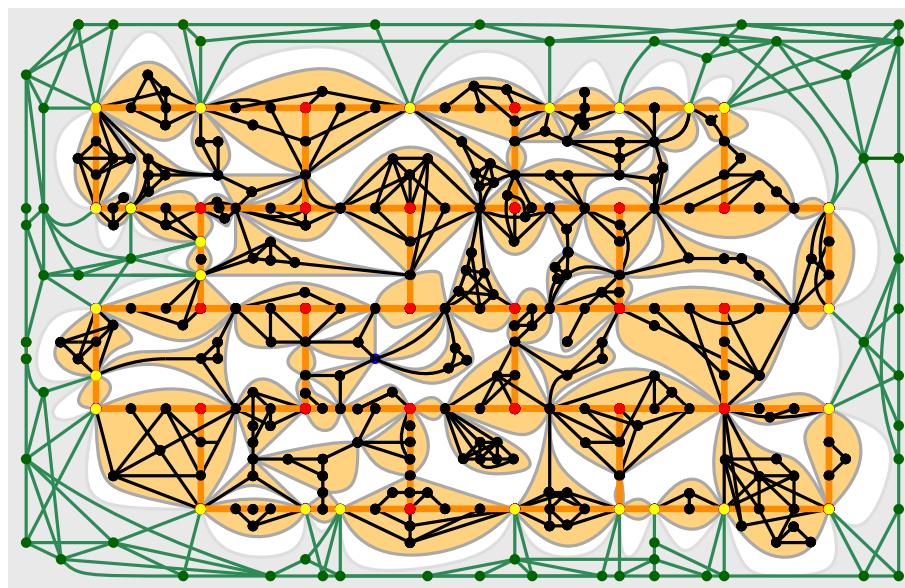
G has a **rendition** whose cells are \mathcal{H} -**compatible**.

\Leftrightarrow

G has a **ground-maximal rendition** whose cells are \mathcal{H} -**compatible**.



flat wall



[figure by Dimitrios M. Thilikos]

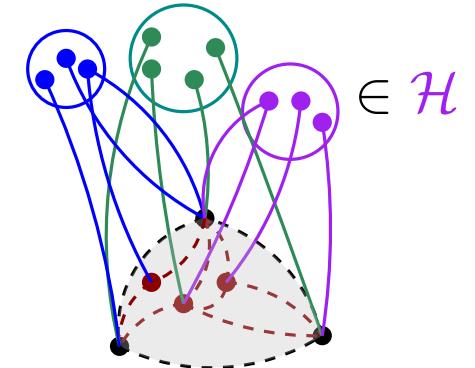
G is a **yes**-instance of SMALL-LEAVES \mathcal{H} -PLANARITY

\Leftrightarrow

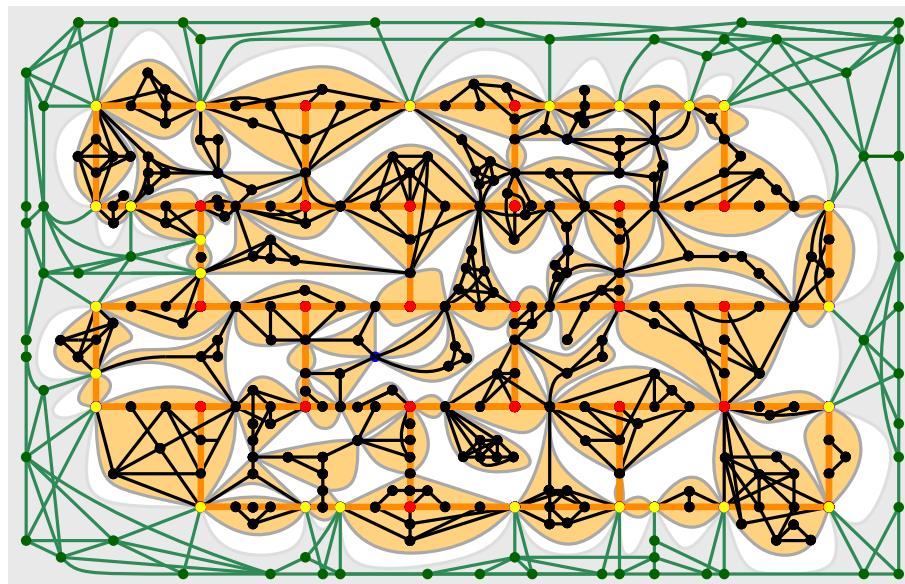
G has a **rendition** whose cells are \mathcal{H} -**compatible**.

\Leftrightarrow

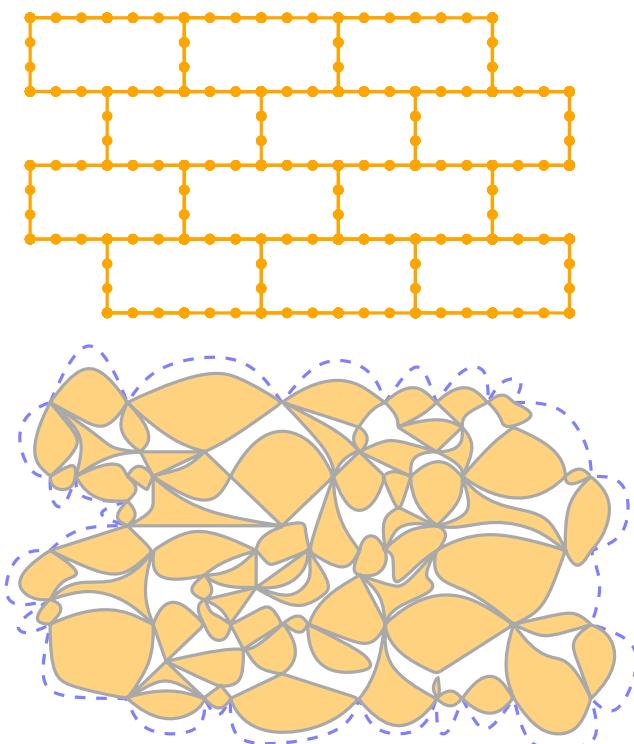
G has a **ground-maximal rendition** whose cells are \mathcal{H} -**compatible**.



flat wall = wall + rendition



[figure by Dimitrios M. Thilikos]



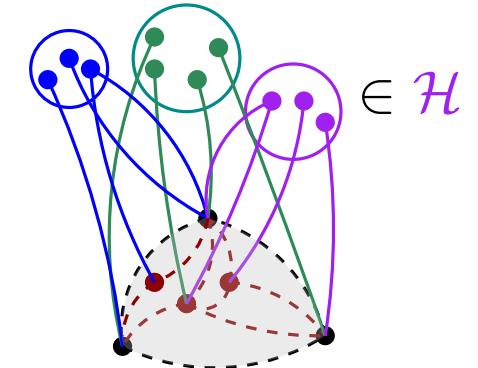
G is a **yes**-instance of SMALL-LEAVES \mathcal{H} -PLANARITY

\Leftrightarrow

G has a **rendition** whose cells are \mathcal{H} -**compatible**.

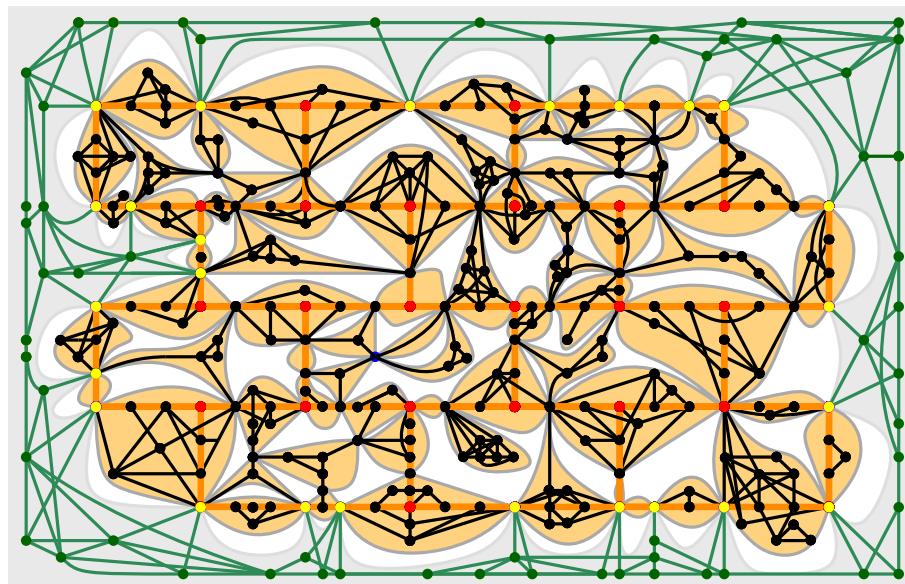
\Leftrightarrow

G has a **ground-maximal rendition** whose cells are \mathcal{H} -**compatible**.

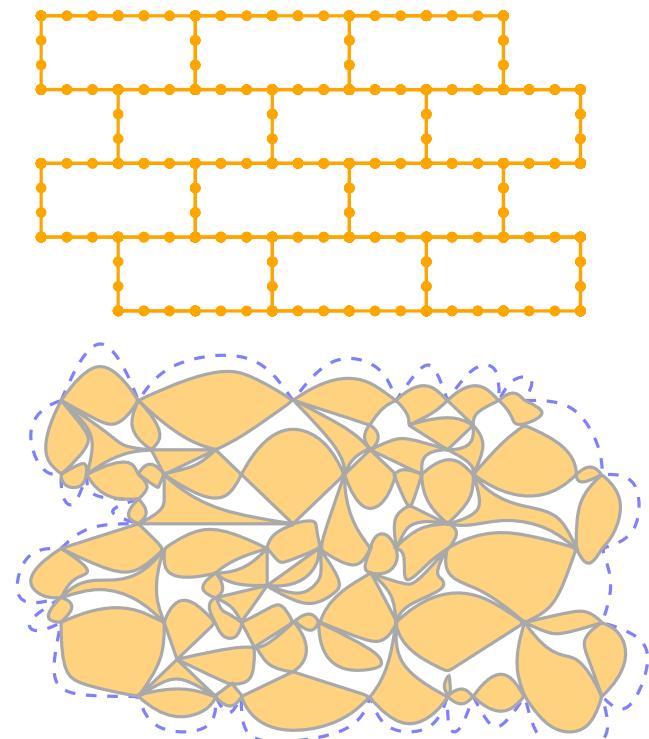


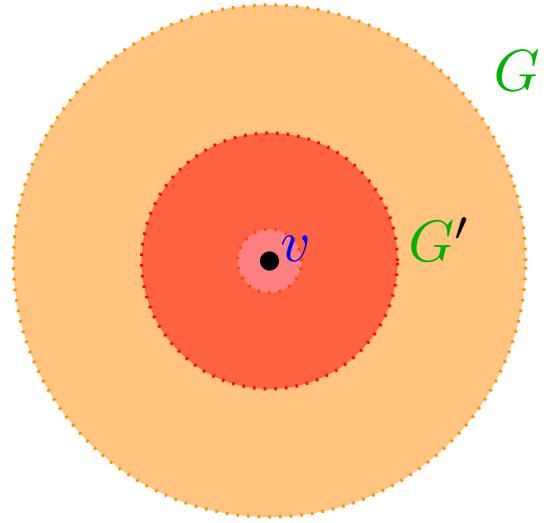
flat wall = wall + rendition

can choose ground-minimal



[figure by Dimitrios M. Thilikos]





Pick a vertex v

Solve recursively on $G - v$.

Ground-maximal rendition ρ_1 of $G - v$ whose cells are \mathcal{H} -compatible.

Take a region G' around v of small treewidth.

Solve on G' . [Courcelle, '90]

Ground-maximal rendition ρ_2 of G' whose cells are \mathcal{H} -compatible.

Find a flat wall W in G whose interior G' has bounded treewidth (or conclude).

Ground-minimal rendition ρ' in G' .

Pick a vertex v

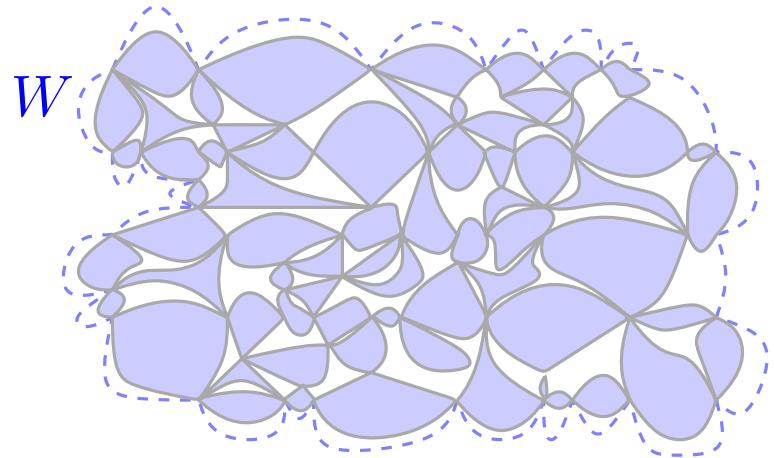
Solve recursively on $G - v$.

Ground-maximal rendition ρ_1 of $G - v$ whose cells are \mathcal{H} -compatible.

Take a region G' around v of small treewidth.

Solve on G' . [Courcelle, '90]

Ground-maximal rendition ρ_2 of G' whose cells are \mathcal{H} -compatible.



Find a flat wall W in G whose interior G' has bounded treewidth (or conclude).

Ground-minimal rendition ρ' in G' .

Pick a vertex v in the center of W .

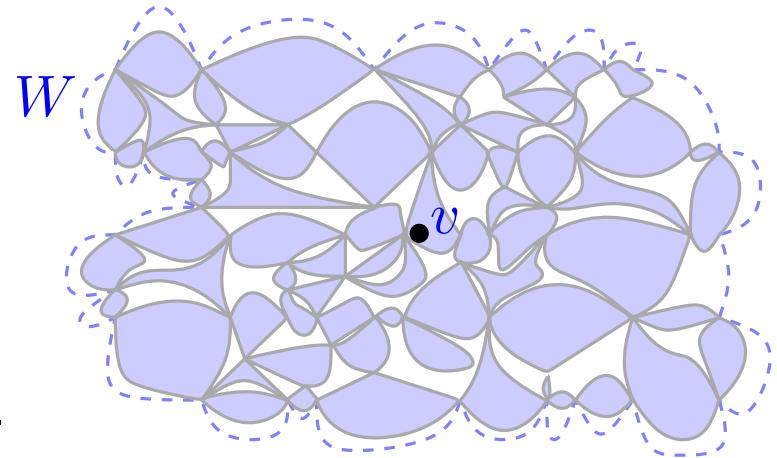
Solve recursively on $G - v$.

Ground-maximal rendition ρ_1 of $G - v$ whose cells are \mathcal{H} -compatible.

Take a region G' around v of small treewidth.

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Pick a vertex v in the center of W .

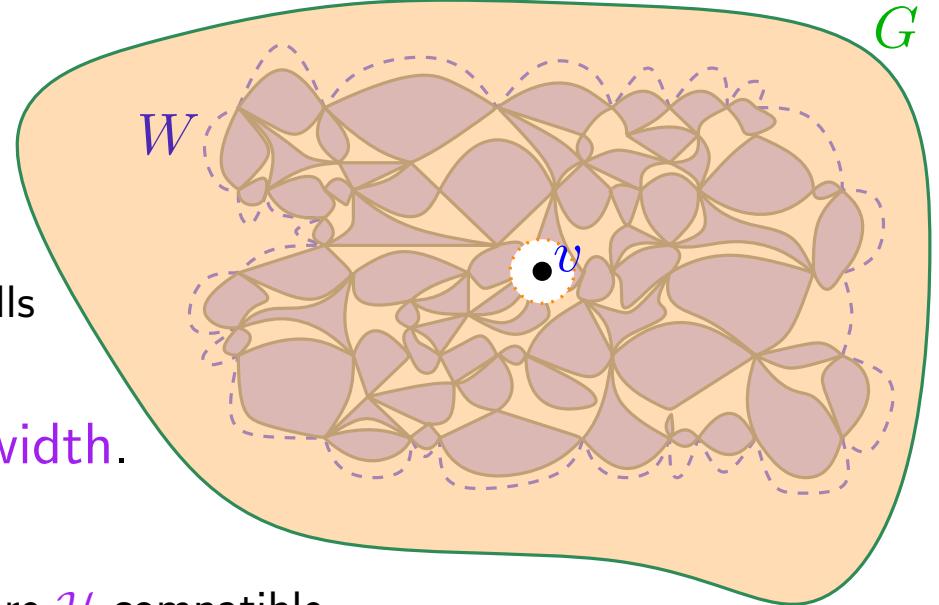
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Ground-minimal rendition ρ' in G' .

Pick a vertex v in the center of W .

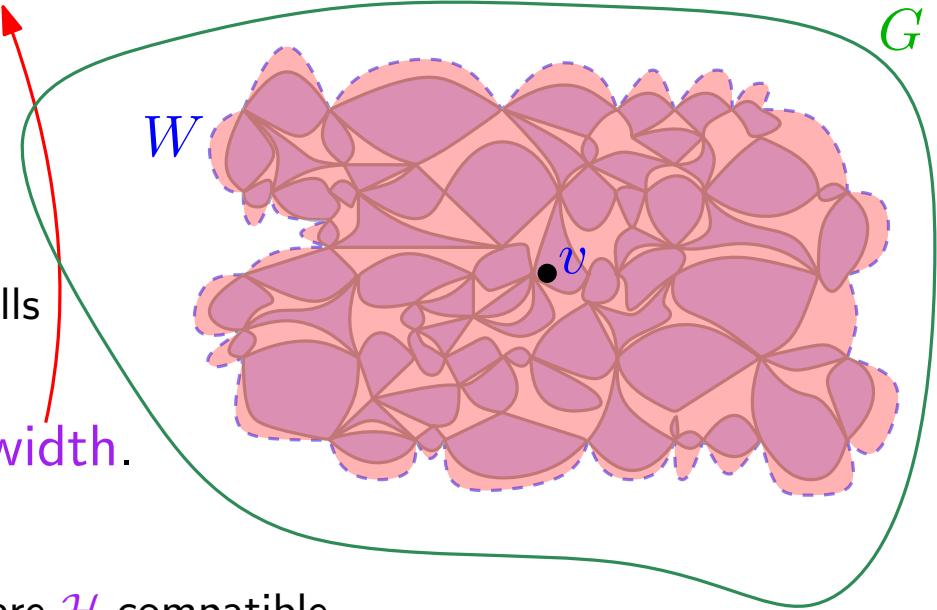
Solve recursively on $G - v$.

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Find a flat wall W in G whose interior G' has bounded treewidth (or conclude).

Ground-minimal rendition ρ' in G' .

Pick a vertex v in the center of W .

Solve recursively on $G - v$.

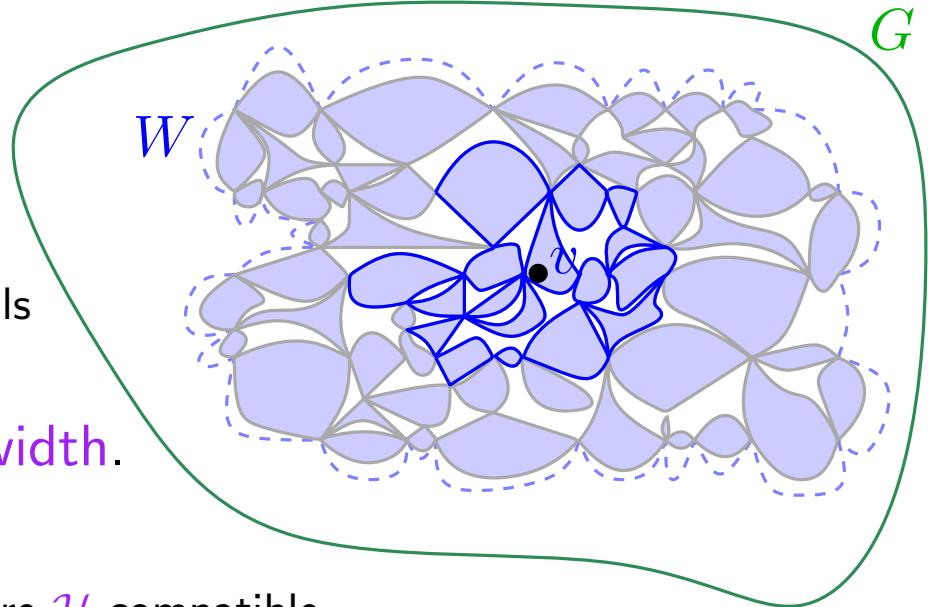
Ground-maximal rendition ρ_1 of $G - v$ whose cells are \mathcal{H} -compatible.

Take a region G' around v of small treewidth.

Solve on G' . [Courcelle, '90]

Ground-maximal rendition ρ_2 of G' whose cells are \mathcal{H} -compatible.

Take a region R of cells of ρ' around v in W .



Find a flat wall W in G whose interior G' has bounded treewidth (or conclude).

Ground-minimal rendition ρ' in G' .

Pick a vertex v in the center of W .

Solve recursively on $G - v$.

Ground-maximal rendition ρ_1 of $G - v$ whose cells are \mathcal{H} -compatible.

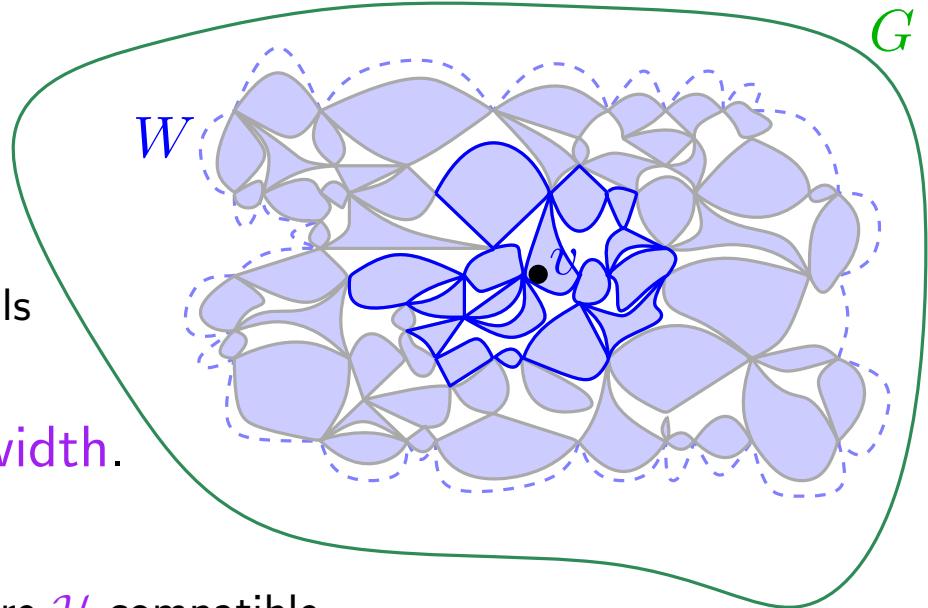
Take a region G' around v of small treewidth.

Solve on G' . [Courcelle, '90]

Ground-maximal rendition ρ_2 of G' whose cells are \mathcal{H} -compatible.

Take a region R of cells of ρ' around v in W .

Each cell of ρ_1 and ρ_2 is contained in a cell of ρ' . \rightarrow can glue ρ_1 and ρ_2 at the boundary of R



Find a flat wall W in G whose interior G' has bounded treewidth (or conclude).

Ground-minimal rendition ρ' in G' .

Pick a vertex v in the center of W .

Solve recursively on $G - v$.

Ground-maximal rendition ρ_1 of $G - v$ whose cells are \mathcal{H} -compatible.

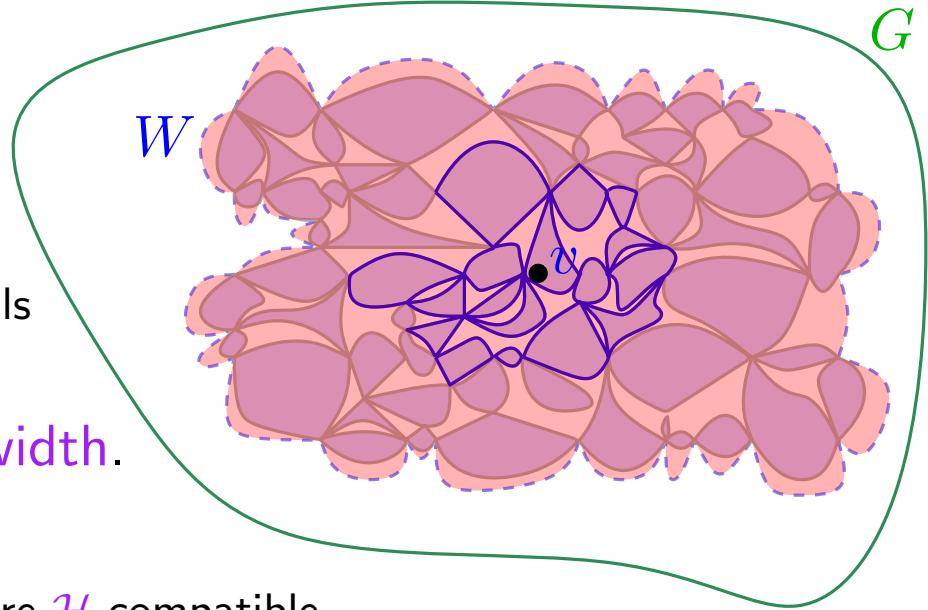
Take a region G' around v of small treewidth.

Solve on G' . [Courcelle, '90]

Ground-maximal rendition ρ_2 of G' whose cells are \mathcal{H} -compatible.

Take a region R of cells of ρ' around v in W .

Each cell of ρ_1 and ρ_2 is contained in a cell of ρ' . \rightarrow can glue ρ_1 and ρ_2 at the boundary of R



Find a flat wall W in G whose interior G' has bounded treewidth (or conclude).

Ground-minimal rendition ρ' in G' .

Pick a vertex v in the center of W .

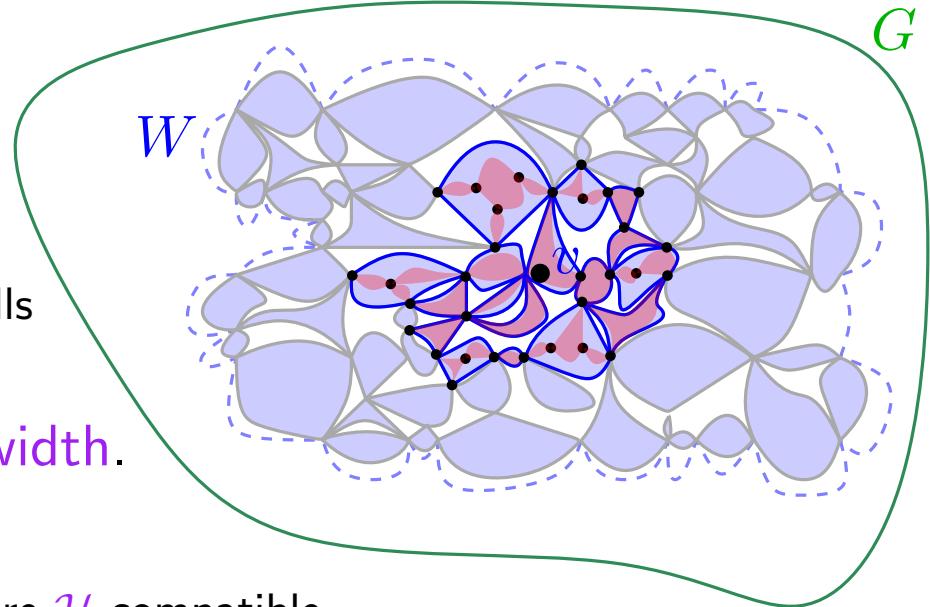
Solve recursively on $G - v$.

Ground-maximal rendition ρ_1 of $G - v$ whose cells are \mathcal{H} -compatible.

Take a region G' around v of small treewidth.

Solve on G' . [Courcelle, '90]

Ground-maximal rendition ρ_2 of G' whose cells are \mathcal{H} -compatible.



Take a region R of cells of ρ' around v in W .

Each cell of ρ_1 and ρ_2 is contained in a cell of ρ' . \rightarrow can glue ρ_1 and ρ_2 at the boundary of R
 \rightarrow replace the cells of ρ' in R with cells of ρ_2

Find a flat wall W in G whose interior G' has bounded treewidth (or conclude).

Ground-minimal rendition ρ' in G' .

Pick a vertex v in the center of W .

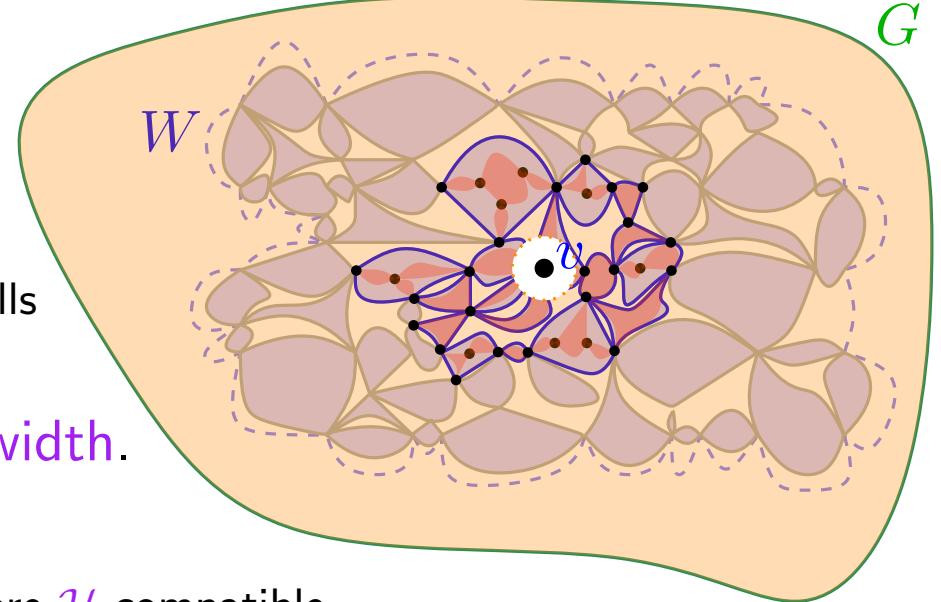
Solve recursively on $G - v$.

Ground-maximal rendition ρ_1 of $G - v$ whose cells are \mathcal{H} -compatible.

Take a region G' around v of small treewidth.

Solve on G' . [Courcelle, '90]

Ground-maximal rendition ρ_2 of G' whose cells are \mathcal{H} -compatible.



Take a region R of cells of ρ' around v in W .

Each cell of ρ_1 and ρ_2 is contained in a cell of ρ' . \rightarrow can glue ρ_1 and ρ_2 at the boundary of R
 \rightarrow replace the cells of ρ' in R with cells of ρ_2

Find a flat wall W in G whose interior G' has bounded treewidth (or conclude).

Ground-minimal rendition ρ' in G' .

Pick a vertex v in the center of W .

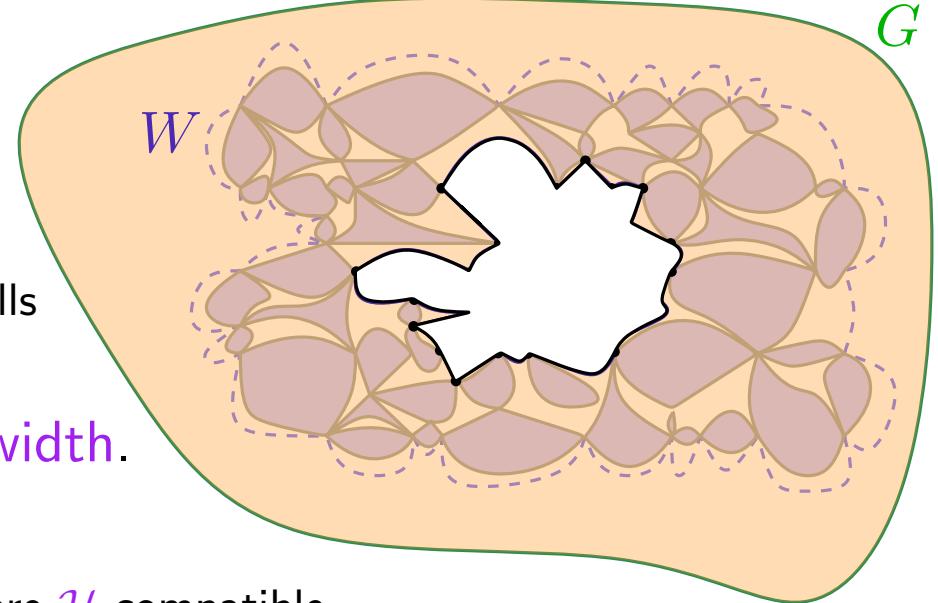
Solve recursively on $G - v$.

Ground-maximal rendition ρ_1 of $G - v$ whose cells are \mathcal{H} -compatible.

Take a region G' around v of small treewidth.

Solve on G' . [Courcelle, '90]

Ground-maximal rendition ρ_2 of G' whose cells are \mathcal{H} -compatible.



Take a region R of cells of ρ' around v in W .

Each cell of ρ_1 and ρ_2 is contained in a cell of ρ' . \rightarrow can glue ρ_1 and ρ_2 at the boundary of R

\rightarrow replace the cells of ρ' in R with cells of ρ_2

\rightarrow replace the cells of ρ' outside of R with cells of ρ_1 (and use cells of ρ_1 outside of G')

Find a flat wall W in G whose interior G' has bounded treewidth (or conclude).

Ground-minimal rendition ρ' in G' .

Pick a vertex v in the center of W .

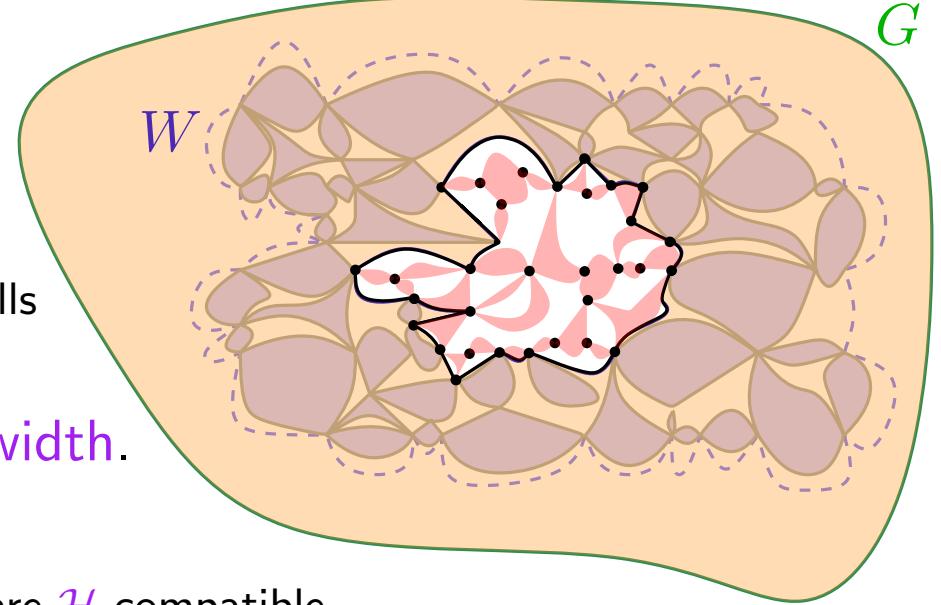
Solve recursively on $G - v$.

Ground-maximal rendition ρ_1 of $G - v$ whose cells are \mathcal{H} -compatible.

Take a region G' around v of small treewidth.

Solve on G' . [Courcelle, '90]

Ground-maximal rendition ρ_2 of G' whose cells are \mathcal{H} -compatible.



Take a region R of cells of ρ' around v in W .

Each cell of ρ_1 and ρ_2 is contained in a cell of ρ' . \rightarrow can glue ρ_1 and ρ_2 at the boundary of R

\rightarrow replace the cells of ρ' in R with cells of ρ_2

\rightarrow replace the cells of ρ' outside of R with cells of ρ_1 (and use cells of ρ_1 outside of G')

\Rightarrow rendition ρ of G whose cells are \mathcal{H} -compatible.

Find a flat wall W in G whose interior G' has bounded treewidth (or conclude).

Ground-minimal rendition ρ' in G' .

Pick a vertex v in the center of W .

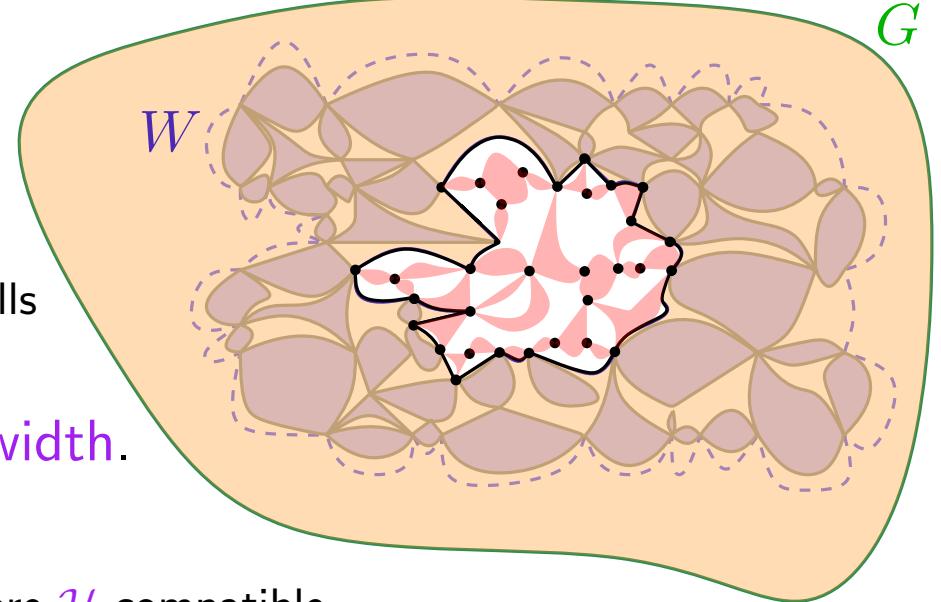
Solve recursively on $G - v$.

Ground-maximal rendition ρ_1 of $G - v$ whose cells are \mathcal{H} -compatible.

Take a region G' around v of small treewidth.

Solve on G' . [Courcelle, '90]

Ground-maximal rendition ρ_2 of G' whose cells are \mathcal{H} -compatible.



Take a region R of cells of ρ' around v in W .

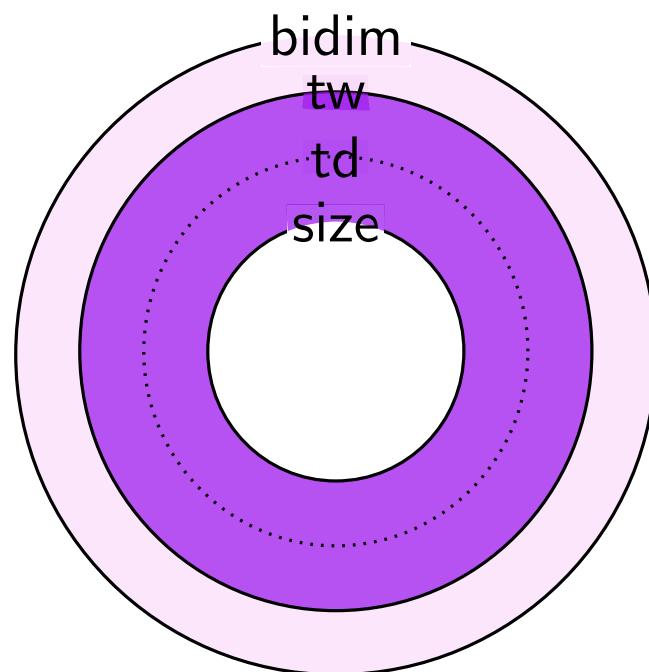
Each cell of ρ_1 and ρ_2 is contained in a cell of ρ' . \rightarrow can glue ρ_1 and ρ_2 at the boundary of R

\rightarrow replace the cells of ρ' in R with cells of ρ_2

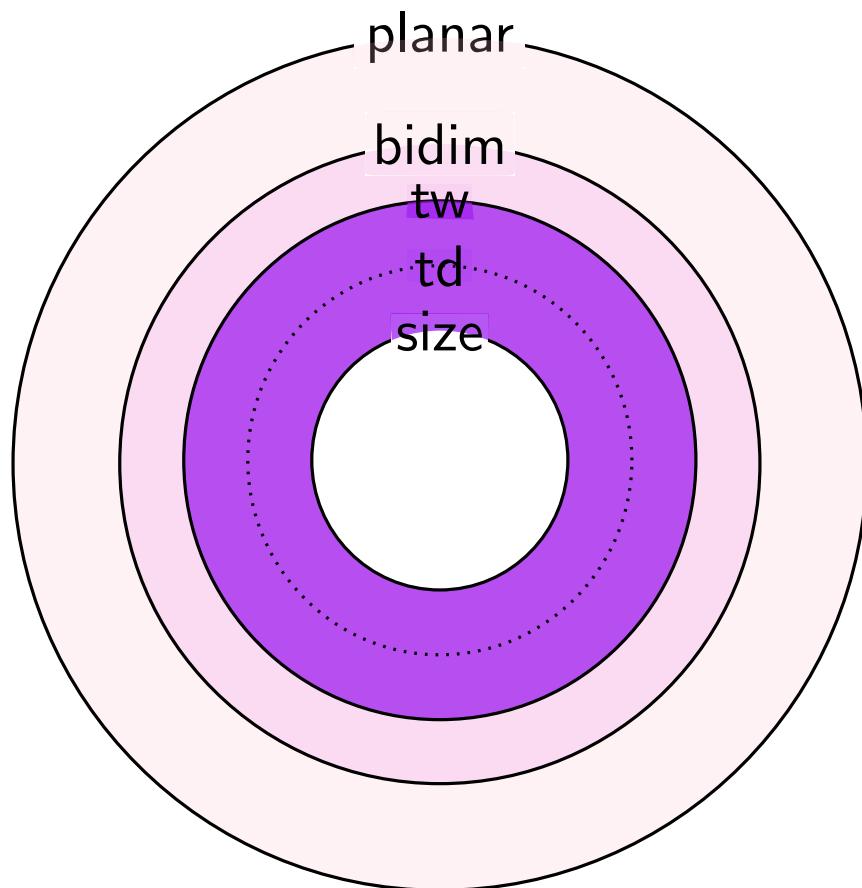
\rightarrow replace the cells of ρ' outside of R with cells of ρ_1 (and use cells of ρ_1 outside of G')

\Rightarrow rendition ρ of G whose cells are \mathcal{H} -compatible.

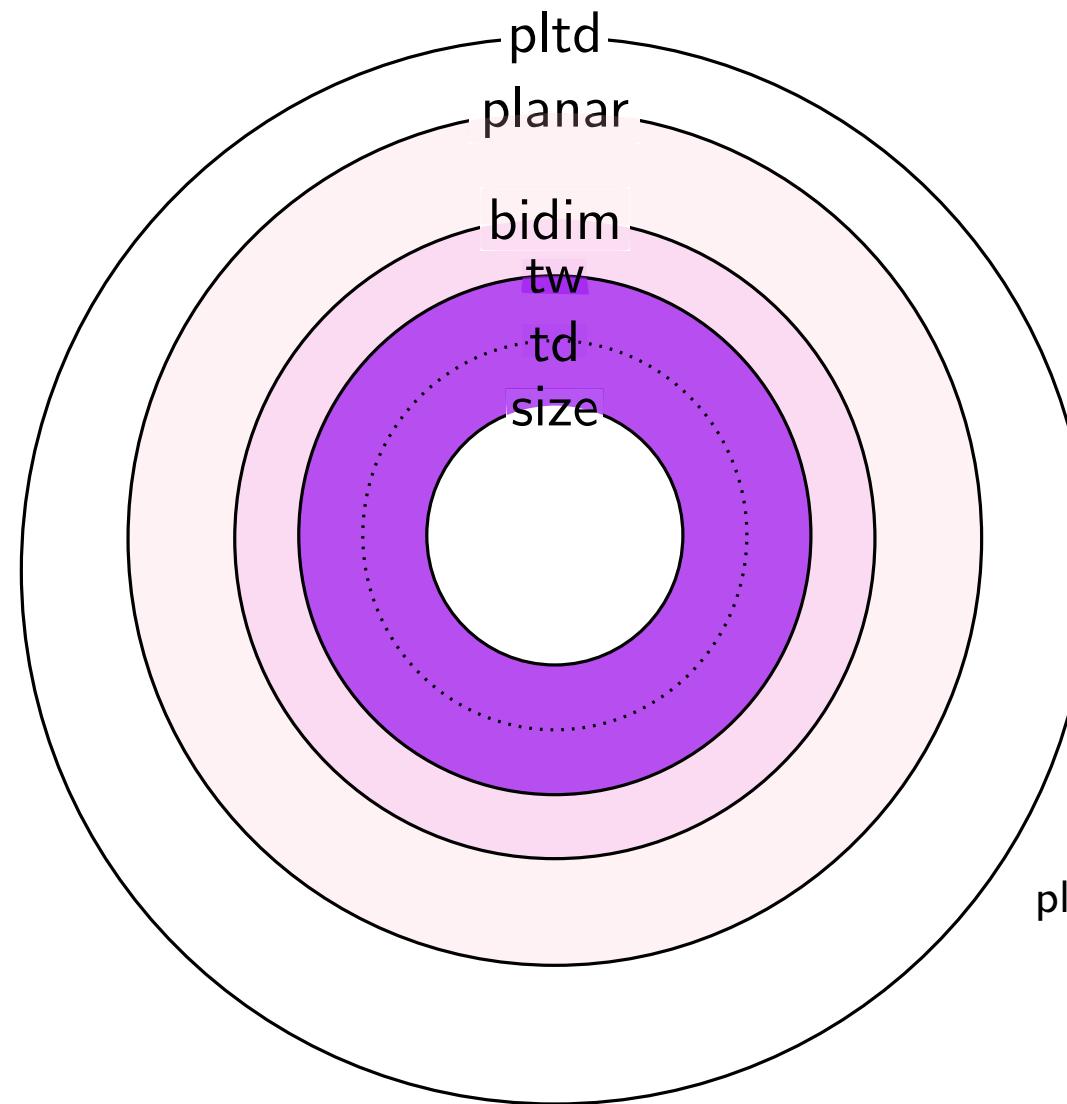
Going even further



Going even further



Going even further



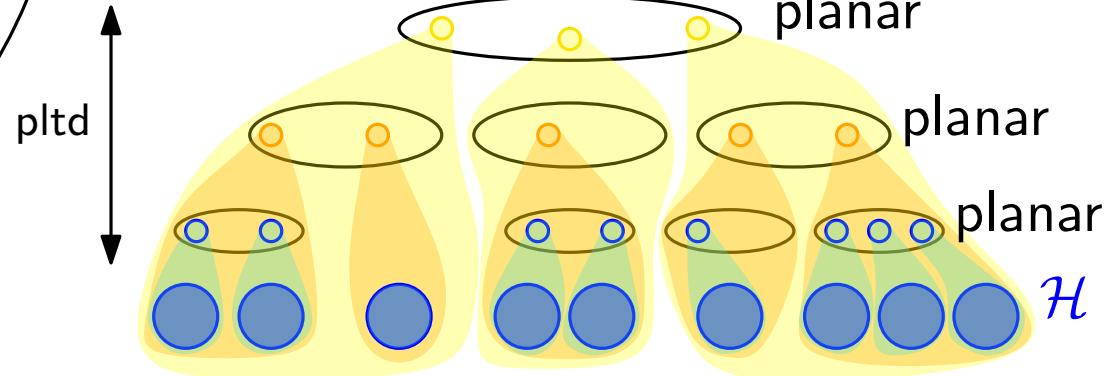
Graph class \mathcal{H}

- hereditary,
- closed under disjoint union,
- CMSO-definable, and
- VERTEX DELETION TO \mathcal{H} in time $\mathcal{O}_k(n^c)$.

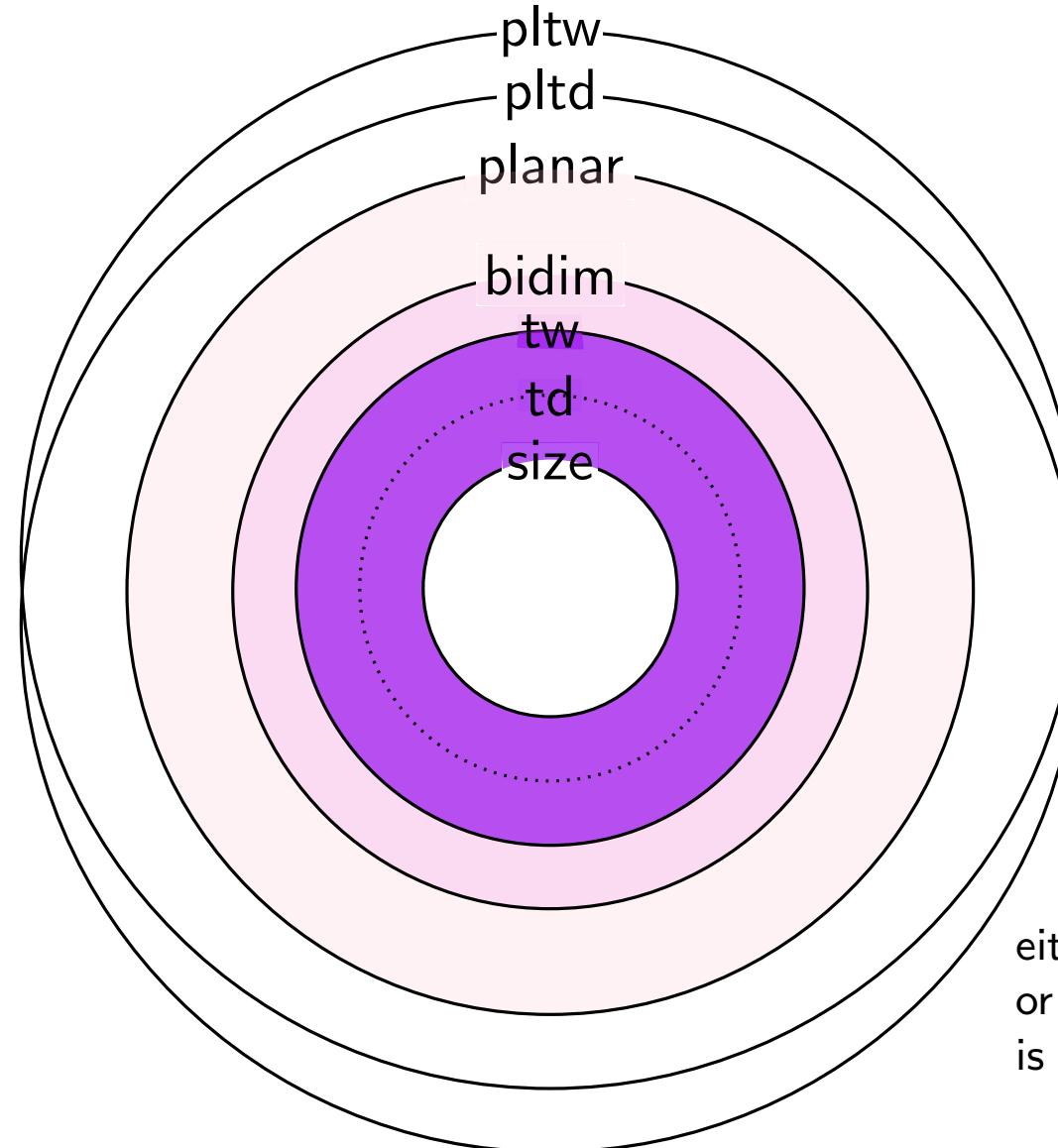
[Fomin, Golovach, Morelle, Thilikos]

One can decide if \mathcal{H} -pltd(G) $\leq k$ in time $\mathcal{O}_k(n^4 + n^c \log n)$.

Planar treedepth pltd



Going even further



Graph class \mathcal{H}

- hereditary,
- closed under disjoint union,
- CMO-definable, and
- VERTEX DELETION TO \mathcal{H} in time $\mathcal{O}_k(n^c)$.

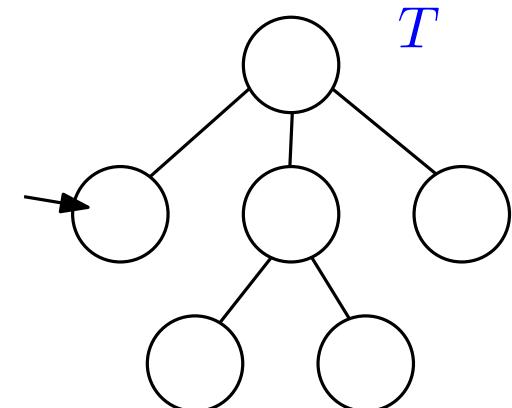
[Fomin, Golovach, Morelle, Thilikos]

One can decide if $\mathcal{H}\text{-pltw}(G) \leq k$ in time $\mathcal{O}_k(n^4 + n^c \log n)$.

Planar treewidth pltw

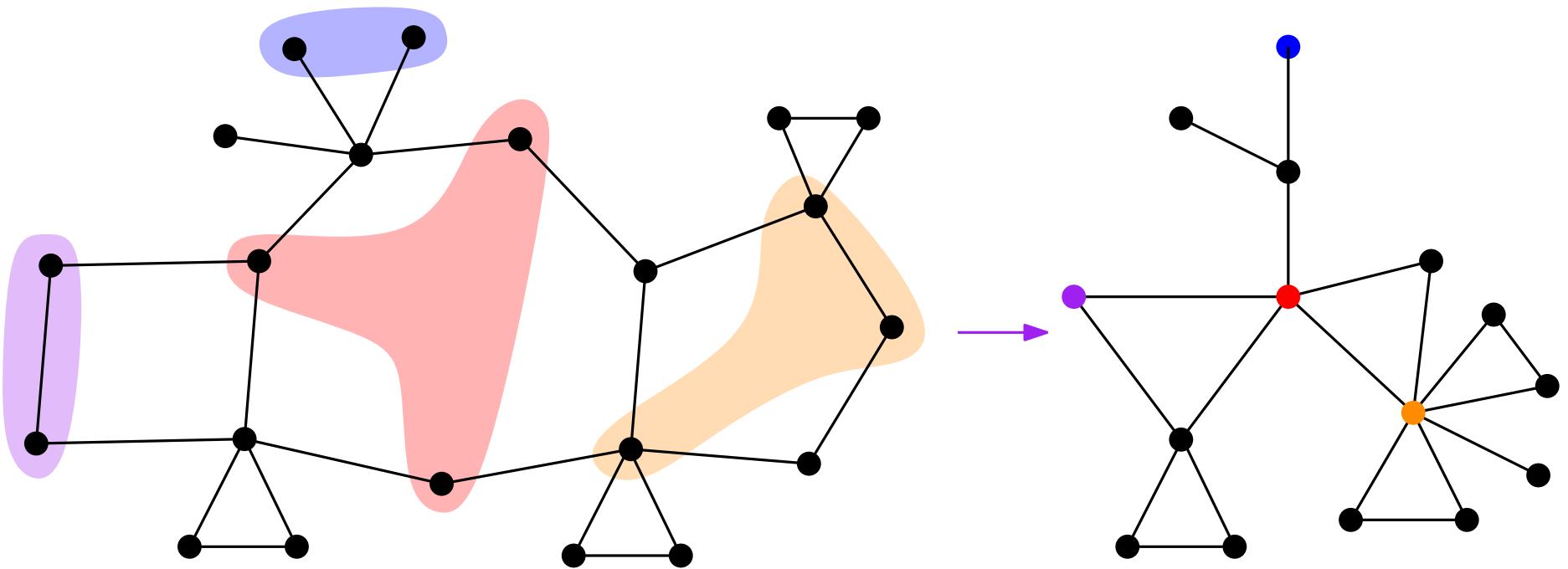
Tree decomposition $(T, \{B_t\}_t)$ of G

either $|B_t| \leq k + 1$
or the torso of B_t
is planar

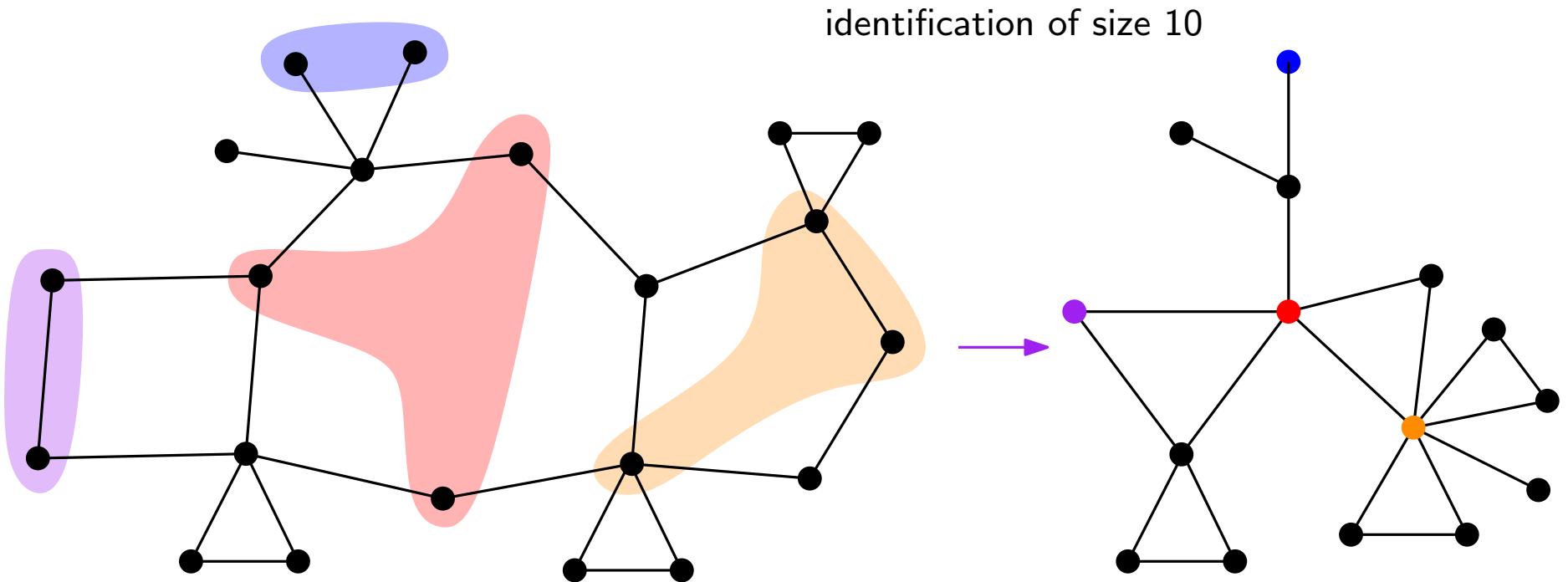


4. A new modification: vertex identification

Vertex identification



Vertex identification



Size of the identification = number of vertices involved in the identification

Why identifications?

Structure theorems meet graph modification problems

Why identifications?

Structure theorems meet graph modification problems

[Robertson, Seymour, '03]+[Thilikos, Wiederrecht, '23]

If G excludes a graph H as a minor, then:

Why identifications?

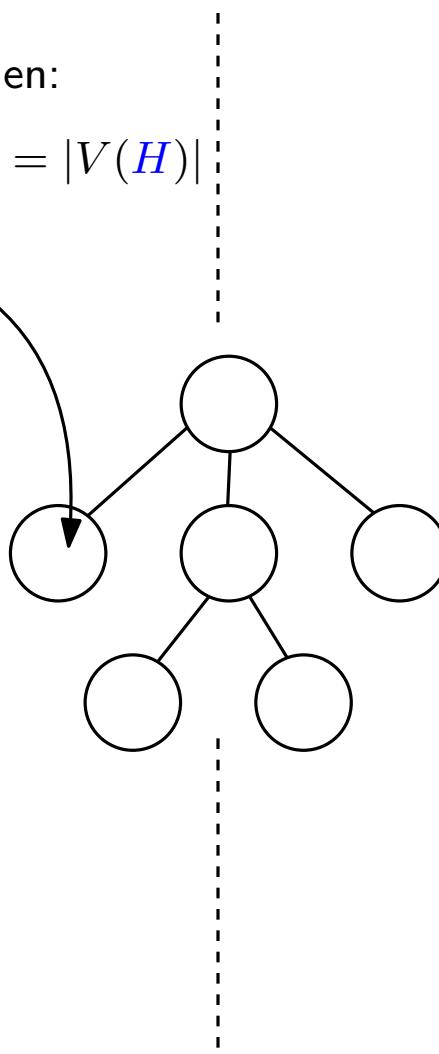
Structure theorems meet graph modification problems

[Robertson, Seymour, '03]+[Thilikos, Wiederrecht, '23]

If G excludes a graph H as a minor, then:

G has a tree decomposition s.t. $h = |V(H)|$

the torso of each bag



Why identifications?

Structure theorems meet graph modification problems

[Robertson, Seymour, '03]+[Thilikos, Wiederrecht, '23]

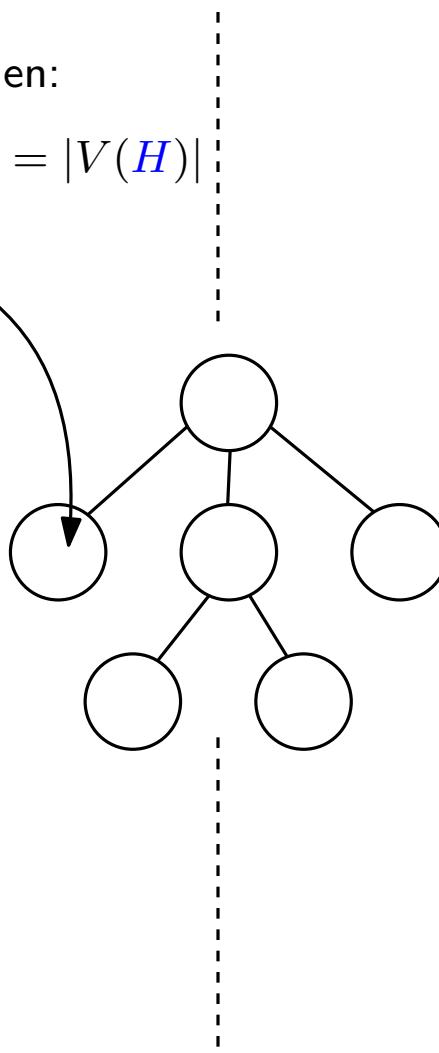
If G excludes a graph H as a minor, then:

G has a tree decomposition s.t. $h = |V(H)|$

the torso of each bag

is embeddable in some surface Σ_h

after deleting a vertex set S of bidimensionality $\leq f(h)$.



Why identifications?

Structure theorems meet graph modification problems

[Robertson, Seymour, '03]+[Thilikos, Wiederrecht, '23]

If G excludes a graph H as a minor, then:

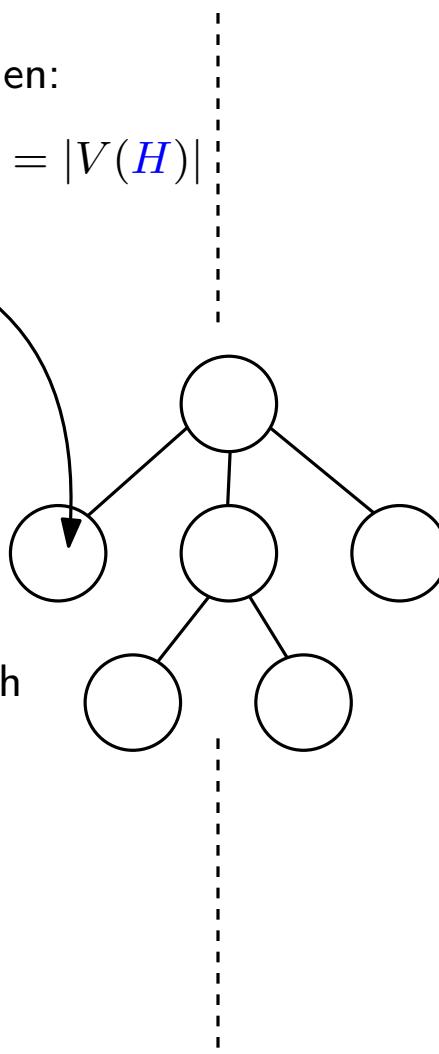
G has a tree decomposition s.t. $h = |V(H)|$

the torso of each bag

is embeddable in some surface Σ_h

after deleting a vertex set S of bidimensionality $\leq f(h)$.

Conversely, if G admits such a tree decomposition, then G excludes a graph H_h as a minor.



Why identifications?

Structure theorems meet graph modification problems

[Robertson, Seymour, '03]+[Thilikos, Wiederrecht, '23]

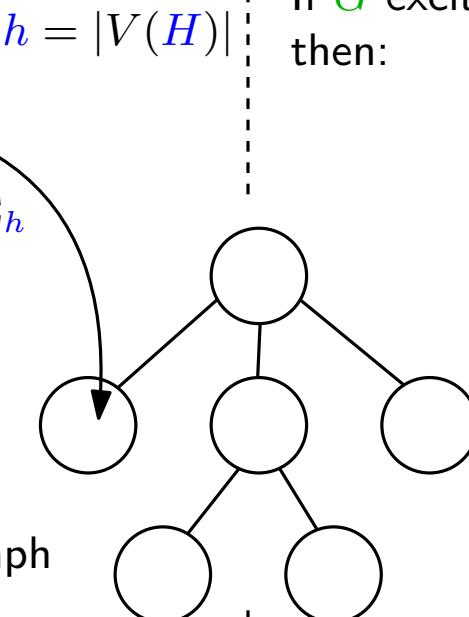
If G excludes a graph H as a minor, then:

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the torso of each bag

is embeddable in some surface Σ_h

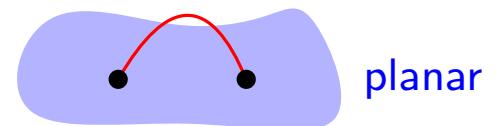
after deleting a vertex set S of
bidimensionality $\leq f(h)$.

Conversely, if G admits such a tree
decomposition, then G excludes a graph
 H_h as a minor.



[Morelle, Protopapas, Thilikos, Wiederrecht]

If G excludes an edge-apex graph H as a minor,
then:



Why identifications?

Structure theorems meet graph modification problems

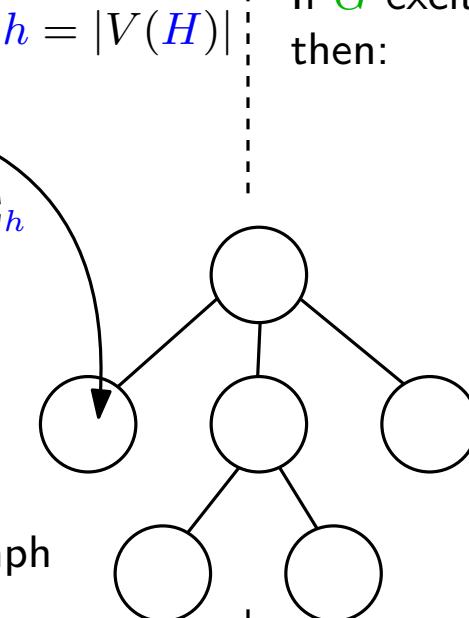
[Robertson, Seymour, '03]+[Thilikos, Wiederrecht, '23]

If G excludes a graph H as a minor, then:

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the torso of each bag

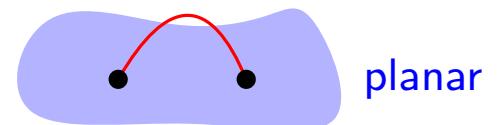
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Why identifications?

Structure theorems meet graph modification problems

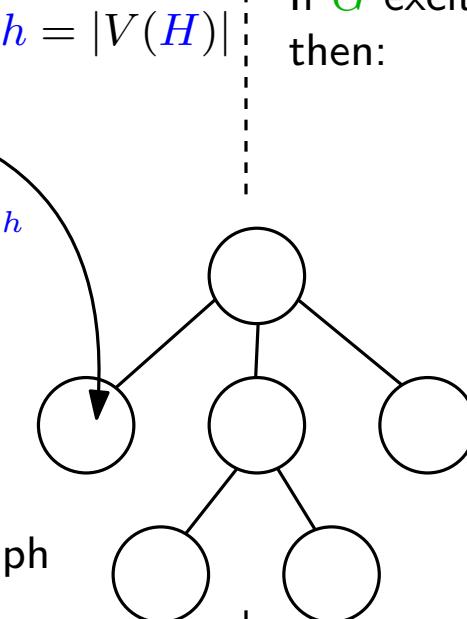
[Robertson, Seymour, '03]+[Thilikos, Wiederrecht, '23]

If G excludes a graph H as a minor, then:

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the torso of each bag

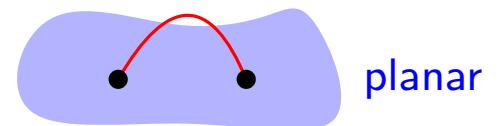
is embeddable in some surface Σ_h
after deleting a vertex set S of
bidimensionality $\leq f(h)$.

Conversely, if G admits such a tree
decomposition, then G excludes a graph
 H_h as a minor.



[Morelle, Protopapas, Thilikos, Wiederrecht]

If G excludes an edge-apex graph H as a minor,
then:



G has a tree decomposition s.t.
the torso of each bag
is embeddable in the projective plane
after identifying a vertex set S of
bidimensionality $\leq f(h)$.

Why identifications?

Structure theorems meet graph modification problems

[Robertson, Seymour, '03]+[Thilikos, Wiederrecht, '23]

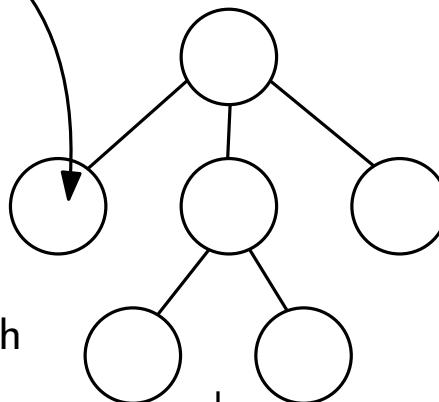
If G excludes a graph H as a minor, then:

G has a tree decomposition s.t.
the torso of each bag

is embeddable in some surface Σ_h
after deleting a vertex set S of
bidimensionality $\leq f(h)$.

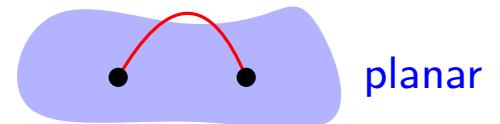
Conversely, if G admits such a tree
decomposition, then G excludes a graph
 H_h as a minor.

$$h = |V(H)|$$



[Morelle, Protopapas, Thilikos, Wiederrecht]

If G excludes an edge-apex graph H as a minor,
then:



G has a tree decomposition s.t.
the torso of each bag
is embeddable in the projective plane
after identifying a vertex set S of
bidimensionality $\leq f(h)$.

Conversely, if G admits such a tree
decomposition, then G excludes an
edge-apex graph H_h as a minor.

Results on identifications

[Morelle, Sau, Thilikos]

VERTEX IDENTIFICATION TO FORESTS is solvable in time
 $\mathcal{O}(1.2738^k + k\sqrt{\log k} \cdot n)$.

[Morelle, Sau, Thilikos]

If \mathcal{H} is minor-closed, then \mathcal{L} -REPLACEMENT TO \mathcal{H} is solvable in time
 $2^{\text{poly}_{\mathcal{H}}(k)} \cdot n^2$ for \mathcal{L} hereditary.

→ includes VERTEX IDENTIFICATION TO \mathcal{H}

Further research

Direction 1: Efficiency

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Can we improve the running time of the different algorithms?

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In particular, VERTEX DELETION TO \mathcal{H}

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$$\curvearrowright 2^{\mathcal{O}_{\mathcal{H}}(\mathbf{k}^c)}?$$

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Graph class \mathcal{H} hereditary, closed under disjoint union, and CMSO-definable.

Parameter p minor-monotone.

for each minor H of G , $p(H) \leq p(G)$

Conjecture: If VERTEX DELETION TO \mathcal{H} is FPT, then checking $\mathcal{H}\text{-}p(G) \leq k$ is also FPT.

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Proved for $p \in \{\text{td}, \text{tw}\}$ \rightarrow likely to hold for any p with $\text{tw} \leq p \leq \text{size}$.

[Agrawal, Kanesh, Lokshtanov, Panolan, Ramanujan, Saurabh, Zehavi, '22]

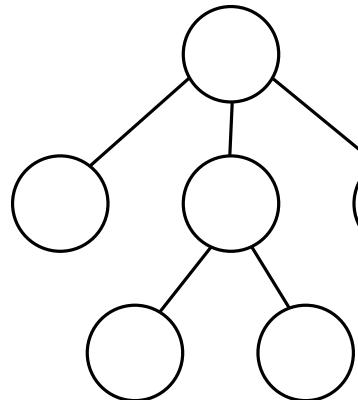
and $p \in \{\text{pltd}, \text{pltw}\}$ \rightarrow extension for any p ?

[Fomin, Golovach, Morello, Thilikos]

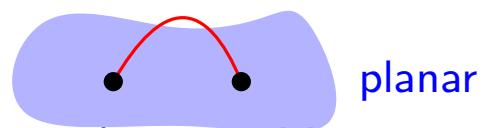
Direction 3: Structure theorems

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If G excludes an **edge-apex** graph H as a **minor**, then:

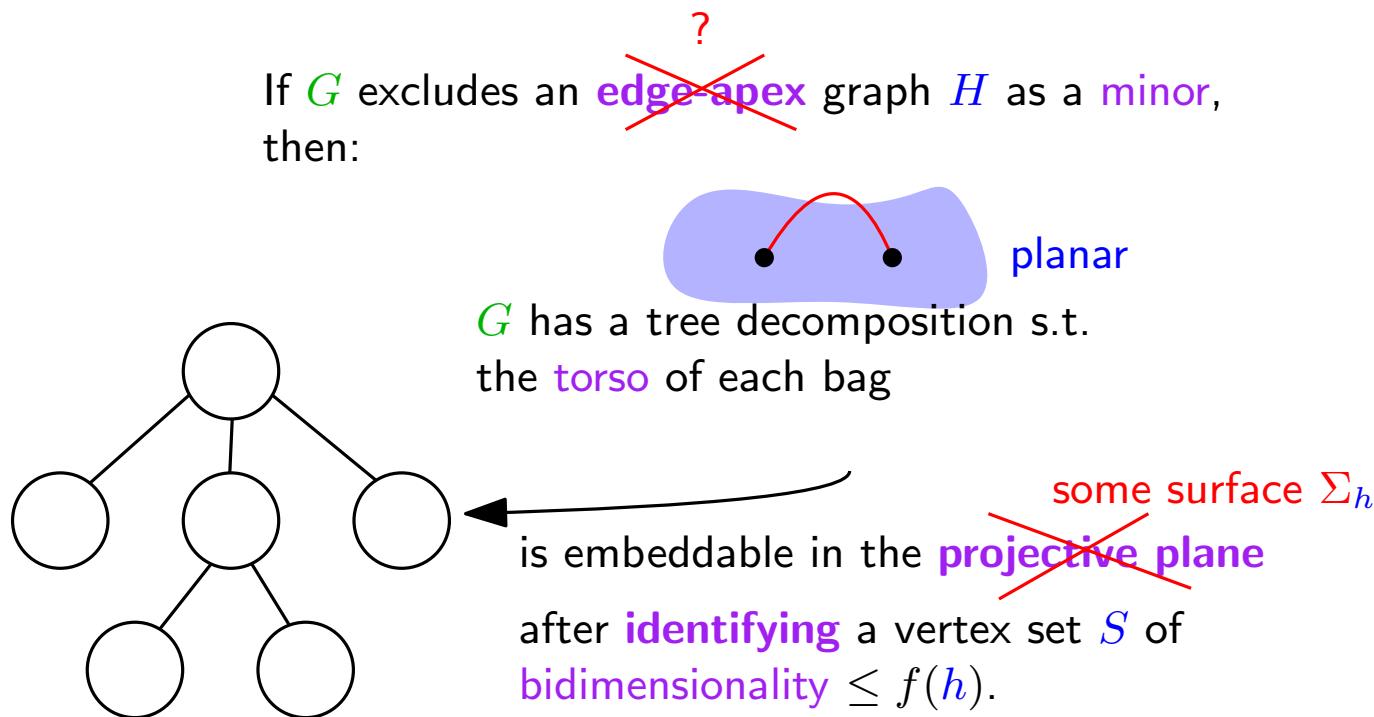


G has a tree decomposition s.t. the **torso** of each bag is embeddable in the **projective plane** after **identifying** a vertex set S of bidimensionality $\leq f(h)$.



planar

Direction 3: Structure theorems



Thank you!

- Faster parameterized algorithms for modification problems to minor-closed classes, with Ignasi Sau, Giannos Stamoulis, and Dimitrios M. Thilikos. ICALP 2023, TheoretCS 2024.
- Dynamic programming on bipartite tree decompositions, with Lars Jaffke, Ignasi Sau, and Dimitrios M. Thilikos. IPEC 2023, submitted to a journal.
- PACE Solver Description: Touiquidh, with Gaétan Berthe, Yoann Coudert–Osmont, Alexander Dobler, Amadeus Reinald, and Mathis Rocton. IPEC 2023.
- A note on locating sets in twin-free graphs, with Nicolas Bousquet, Quentin Chuet, Victor Falgas-Ravry, and Amaury Jacques. Discrete Mathematics 2025.
- On the parameterized complexity of computing good edge-labelings, with Davi de Andrade, Júlio Araújo, Ignasi Sau, and Ana Silva. Submitted to a journal.
- Vertex identification to a forest, with Ignasi Sau and Dimitrios M. Thilikos. Discrete Mathematics 2026.
- Graph modification of bounded size to minor-closed classes as fast as vertex deletion, with Ignasi Sau and Dimitrios M. Thilikos. ESA 2025.
- Excluding Pinched Spheres, with Evangelos Protopapas, Dimitrios M. Thilikos, and Sebastian Wiederrecht. Submitted to a journal.
- When does FTP become FPT?, with Matthias Bentert, Fedor V. Fomin, and Petr A. Golovach. WG 2025.
- Fault-Tolerant Matroid Bases, with Matthias Bentert, Fedor V. Fomin, and Petr A. Golovach. ESA 2025.
- H-Planarity and Parametric Extensions: when Modulators Act Globally, with Fedor V. Fomin, Petr A. Golovach, and Dimitrios M. Thilikos. Submitted to a conference.
- Faster Algorithms for the Pre-Assignment Problem for Unique Minimum Vertex Cover, with Marthe Bonamy, Timothé Picavet, and Alexander Scott. Submitted to a conference.